

# CPEN 455: Deep Learning

## Lecture 2 : Linear Models

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# Outline

- Statistical Learning Setup
- Linear Regression
  - Problem Specification
  - Model Design
  - Loss Design
  - Inference Algorithm
  - Learning/Training Algorithm (Gradient Descent)
  - Validation and Testing (Overfitting vs. Underfitting, Bias Variance Tradeoff)
- Linear Classification
  - Logistic Regression
  - Multiclass Logistic Regression

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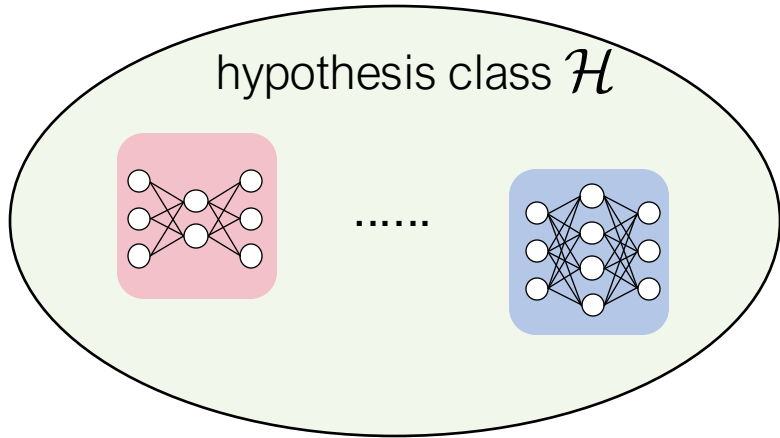
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# Statistical Learning Setup

i.i.d. dataset  $D$



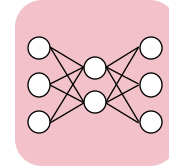
hypothesis class  $\mathcal{H}$



Learning Algorithm



“best” model



# Statistical Learning Setup

Let us review some key concepts and assumptions (mainly about supervised learning like classification and regression) in statistical learning theory, which was initially developed by Vladimir Vapnik, e.g., [1].

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## 1) Assumptions of IID sampling and unknown data distribution

Training data are sampled from an unknown data distribution in an i.i.d. (independent and identically distributed) fashion

$$(x_n, y_n) \stackrel{\text{iid}}{\sim} \mathbb{P}_{\text{data}}(x, y) \quad n = 1, \dots, N$$

Therefore, the training dataset

$$D = \{(x_n, y_n) | n = 1, \dots, N\} \sim \mathbb{P}_{\text{data}}(x, y)^N$$

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Either input or output could be continuous or discrete scalars, vectors, tensors, sets, sequences, graphs, ...

E.g. regression	$x_n \in \mathbb{R}^2$	$y_n \in \mathbb{R}$
classification	$x_n \in \mathbb{R}^2$	$y_n \in \{1, 2, \dots, K\}$

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## 2) Model and Loss

We introduce a *model* (a.k.a., *hypothesis*)  $f(x, w)$  with learnable parameters  $w$

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E.g. all linear models with weight norm no larger than 1  $\mathcal{H} = \{f(x, w) | f(x, w) = w^\top x, \|w\| \leq 1\}$

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*Loss* is denoted as  $\ell(y, f(x, w))$

*Generalization error* (a.k.a., *risk* or *expected loss*) is

$$\mathbb{E}_{\mathbb{P}_{\text{data}}(x, y)} [\ell(y, f(x, w))]$$

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Monte Carlo  
Estimation



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## 3) Learning

Ideally, we want to find a model in the hypothesis class that minimizes the risk:

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A learning algorithm can be viewed as a mapping that maps a training dataset, initial parameters, and hyperparameters to “optimal” parameters:

$$w^* = \mathcal{A}(D, w^0)$$

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# Linear Regression

- Problem Specification (1D-Regression)

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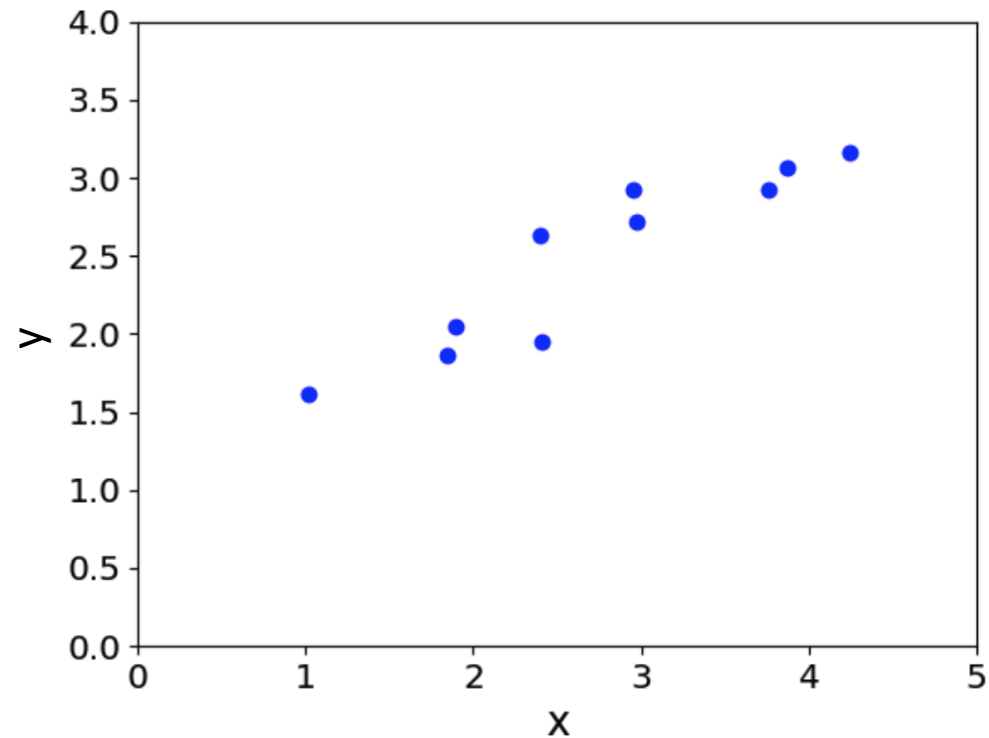
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Linear model (or a linear layer)  $\hat{y} = w^\top x + b$

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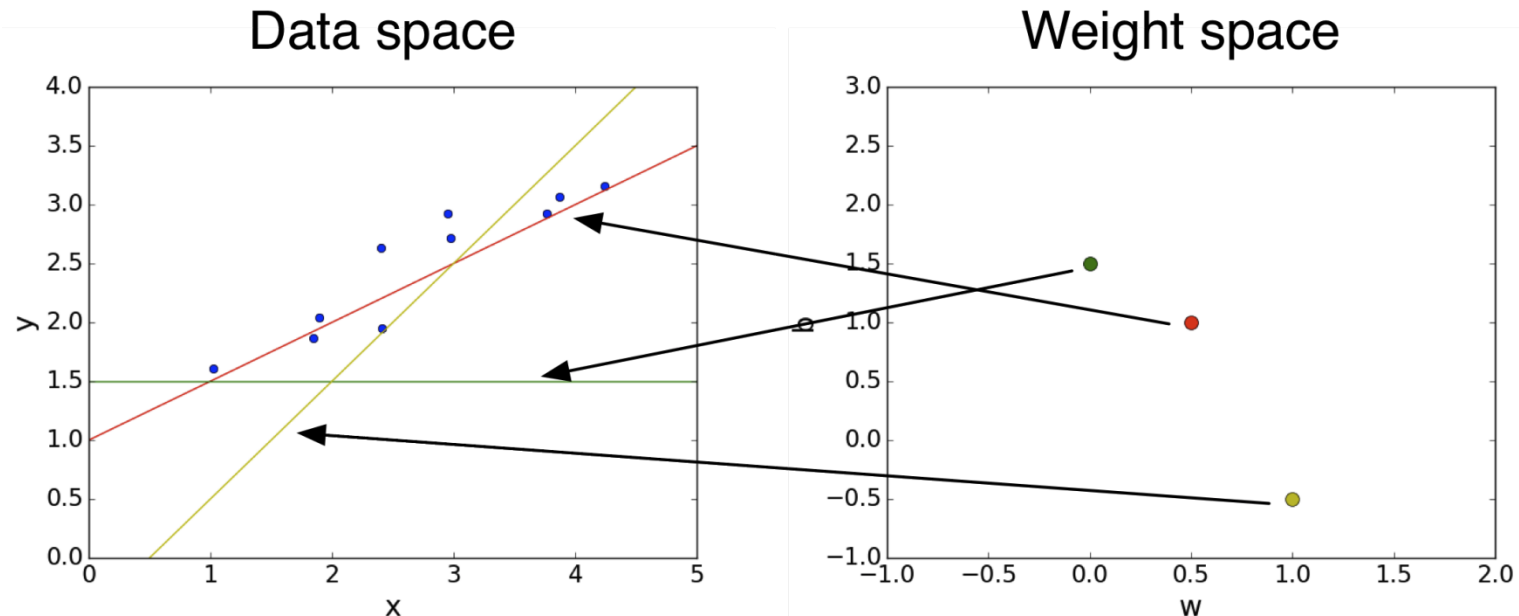
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- 3) Smooth L1 loss (similar to Huber loss used in robust statistics)

$$\ell(\hat{y}_n, y_n) = \begin{cases} \frac{1}{2\beta} \|\hat{y}_n - y_n\|_2^2 & \text{if } \|\hat{y}_n - y_n\|_1 < \beta \\ \|\hat{y}_n - y_n\|_1 - \frac{1}{2\beta} & \text{otherwise} \end{cases}$$



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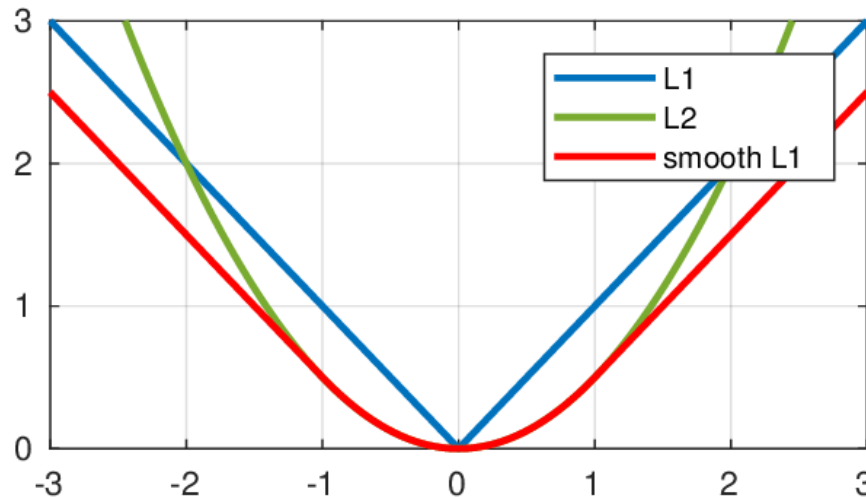
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For our linear models, inference is just:  $\hat{y} = w^\top x + b$

For other models in DL/ML, e.g., deep energy based models, one may need both of first two!

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Since learning is an optimization problem, a learning algorithm is just an optimization algorithm.

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## 1) Gradient-based learning algorithms:

- 1st order gradient method, e.g., stochastic gradient descent (SGD)
- 2nd order gradient method, e.g., Newton's method

.....

## 2) Gradient-free learning algorithms:

- Genetic algorithms
- Random search, e.g., simulated annealing

.....

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Therefore, with MSE loss, the learning problem is

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We can equivalently (why?) rewrite it as

$$\min_{w, b} L(w, b) = \frac{1}{2N} \sum_{n=1}^N \|w^\top x_n + b - y_n\|_2^2$$

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What is a gradient?



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What is a gradient?

Loss is typically a scalar, parameters can be viewed as a vector, the gradient is defined as

$$\frac{\partial L}{\partial w[i]} = \lim_{\epsilon \rightarrow 0} \frac{L(w + \epsilon e_i, b) - L(w, b)}{\epsilon}$$

where  $w[i]$  is the  $i$ -th element (scalar) of weight and  $e_i$  is a zero vector except that the  $i$ -th element is 1.

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**This definition (central difference version) is useful for checking the correctness of gradient implementation!**

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We learn from calculus about how to derive gradient via basic derivatives and their rules:

$$\begin{aligned} L(w, b) &= \frac{1}{2N} \sum_{n=1}^N \underbrace{\|w^\top x_n + b - y_n\|_2^2}_{l_n} \\ &= \frac{1}{2N} \sum_{n=1}^N \left( \sum_{d=1}^D w[d]x_n[d] + b - y_n \right)^2 \end{aligned}$$

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$$\begin{aligned} \frac{\partial L(w, b)}{\partial w[i]} &= \sum_{n=1}^N \frac{\partial L(w, b)}{\partial l_n} \frac{\partial l_n}{\partial w[i]} \\ &= \sum_{n=1}^N \frac{\partial \frac{1}{2N} \sum_{n=1}^N l_n^2}{\partial l_n} \frac{\partial l_n}{\partial w[i]} \\ &= \frac{1}{2N} \sum_{n=1}^N 2l_n \frac{\partial l_n}{\partial w[i]} \\ &= \frac{1}{N} \sum_{n=1}^N l_n \frac{\partial \left( \sum_{d=1}^D w[d]x_n[d] + b - y_n \right)}{\partial w[i]} \\ &= \frac{1}{N} \sum_{n=1}^N l_n x_n[i] \end{aligned}$$

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$$\frac{\partial L(w, b)}{\partial w[i]} = \sum_{n=1}^N \frac{\partial L(w, b)}{\partial l_n} \frac{\partial l_n}{\partial w[i]}$$

Write in a compact vector form:

$$\begin{aligned} \frac{\partial L(w, b)}{\partial w} &= \begin{bmatrix} \frac{\partial L(w, b)}{\partial w[1]} \\ \vdots \\ \frac{\partial L(w, b)}{\partial w[D]} \end{bmatrix} \\ &= \frac{1}{N} \sum_{n=1}^N l_n x_n \end{aligned}$$

$$\begin{aligned} &= \sum_{n=1}^N \frac{\partial \frac{1}{2N} \sum_{n=1}^N l_n^2}{\partial l_n} \frac{\partial l_n}{\partial w[i]} \\ &= \frac{1}{2N} \sum_{n=1}^N 2l_n \frac{\partial l_n}{\partial w[i]} \\ &= \frac{1}{N} \sum_{n=1}^N l_n \frac{\partial \left( \sum_{d=1}^D w[d]x_n[d] + b - y_n \right)}{\partial w[i]} \\ &= \frac{1}{N} \sum_{n=1}^N l_n x_n[i] \end{aligned}$$

# Linear Regression

- Learning Algorithm

$$L(w, b) = \frac{1}{2N} \sum_{n=1}^N \underbrace{\|w^\top x_n + b - y_n\|_2^2}_{l_n} = \frac{1}{2N} \sum_{n=1}^N \left( \sum_{d=1}^D w[d]x_n[d] + b - y_n \right)^2$$

$$\frac{\partial L(w, b)}{\partial w[i]} = \sum_{n=1}^N \frac{\partial L(w, b)}{\partial l_n} \frac{\partial l_n}{\partial w[i]}$$

Write in a compact vector form:

$$\frac{\partial L(w, b)}{\partial w} = \begin{bmatrix} \frac{\partial L(w, b)}{\partial w[1]} \\ \vdots \\ \frac{\partial L(w, b)}{\partial w[D]} \end{bmatrix}$$
$$= \frac{1}{N} \sum_{n=1}^N l_n x_n$$

$$= \sum_{n=1}^N \frac{\partial \frac{1}{2N} \sum_{n=1}^N l_n^2}{\partial l_n} \frac{\partial l_n}{\partial w[i]}$$
$$= \frac{1}{2N} \sum_{n=1}^N 2l_n \frac{\partial l_n}{\partial w[i]}$$
$$= \frac{1}{N} \sum_{n=1}^N l_n \frac{\partial \left( \sum_{d=1}^D w[d]x_n[d] + b - y_n \right)}{\partial w[i]}$$
$$= \frac{1}{N} \sum_{n=1}^N l_n x_n[i]$$

If N is too large, we can randomly sample a smaller subset (a.k.a. mini-batch) to compute the gradient.



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Then we can perform the gradient descent algorithms

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## Algorithm 1 GD Learning Algorithm

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- If we use full training dataset to compute the gradient per step, then it is called (*batch*) *gradient descent*

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- If we use full training dataset to compute the gradient per step, then it is called (*batch*) *gradient descent*
- If we use random mini-batch data to compute the gradient per step, then it is called *stochastic gradient descent*

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Is the model at the last step necessarily the best?

# Outline

- Statistical Learning Setup
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If your dataset is of a small size, then you can use k-fold cross-validation.

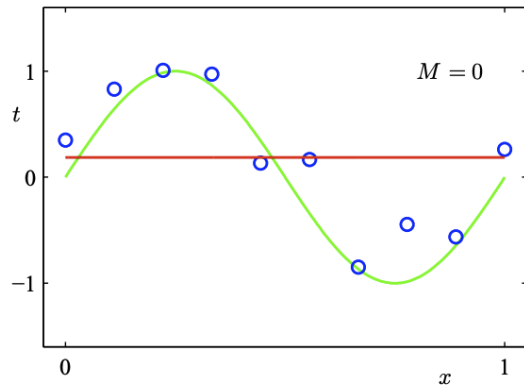
# Linear Regression

- Validation and Testing: Overfitting vs. Underfitting

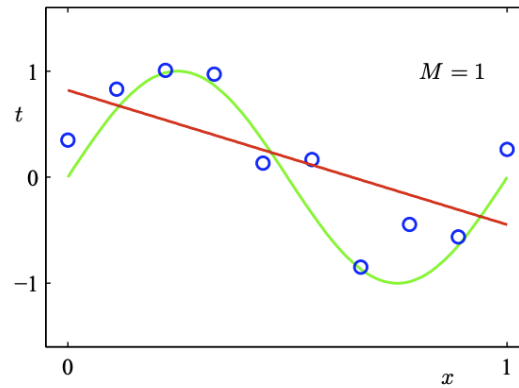
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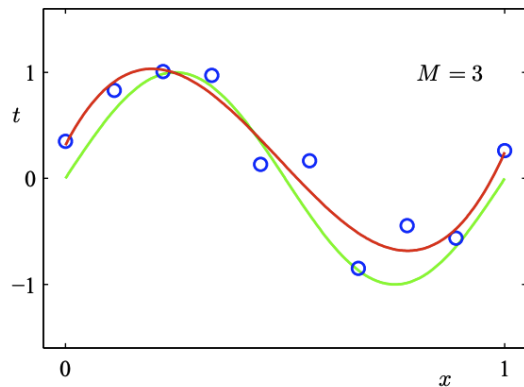
$$y = w_0$$



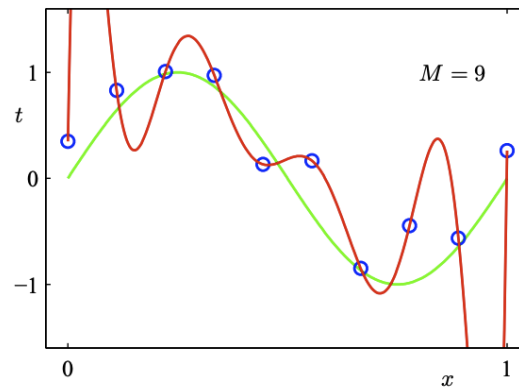
$$y = w_0 + w_1x$$



$$y = w_0 + w_1x + w_2x^2 + w_3x^3$$



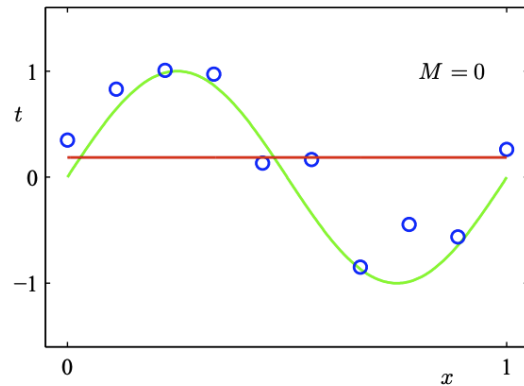
$$y = w_0 + w_1x + \dots + w_9x^9$$



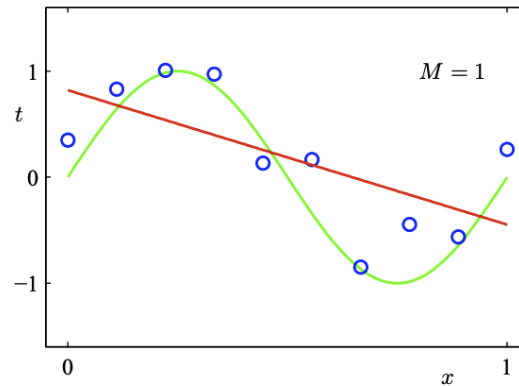
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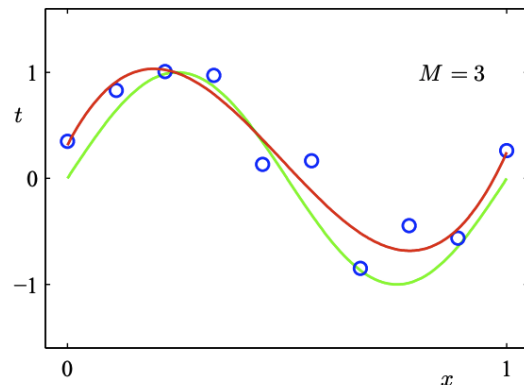
Underfitting:

Model is too simple to fit the data

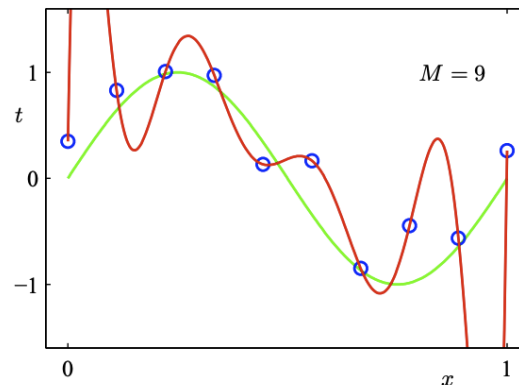
Overfitting:

Model is too complicate, perfectly fits the data, but does not generalize

$$y = w_0 + w_1x + w_2x^2 + w_3x^3$$



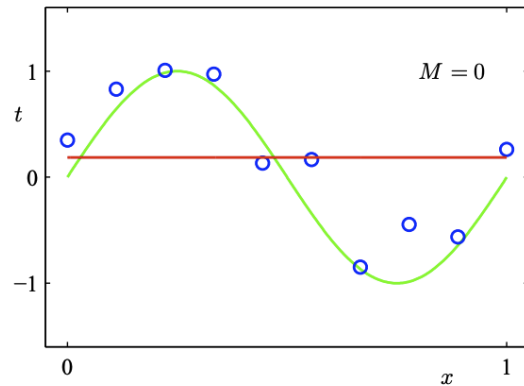
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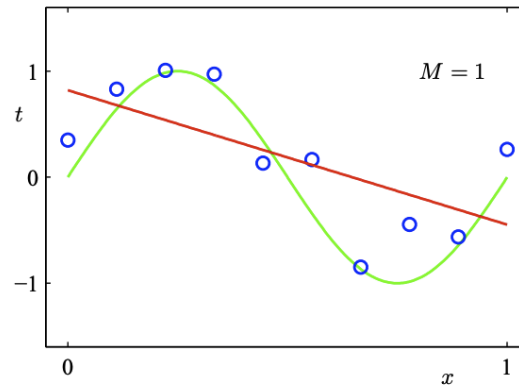
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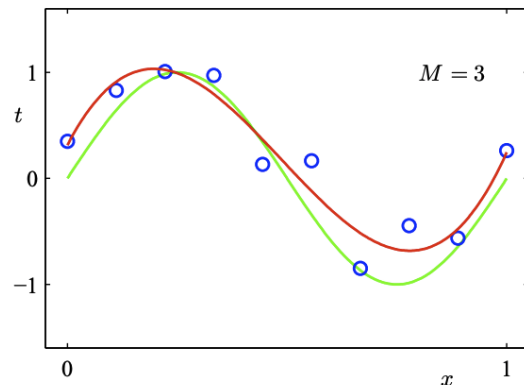
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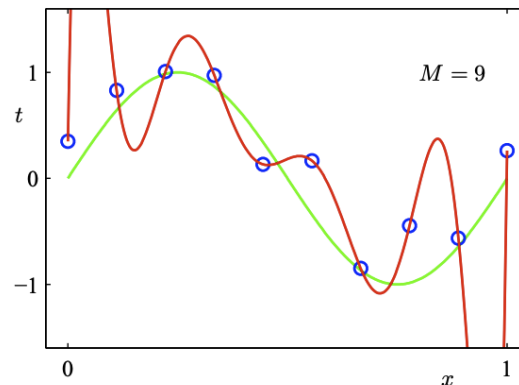
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$$y = w_0 + w_1x + w_2x^2 + w_3x^3$$



$$y = w_0 + w_1x + \dots + w_9x^9$$



There exists *benign overfitting* (i.e., complicated models perfectly fit and generalize well) in deep learning (cf. [32])!



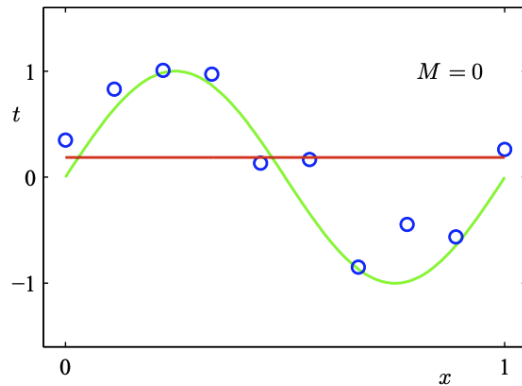
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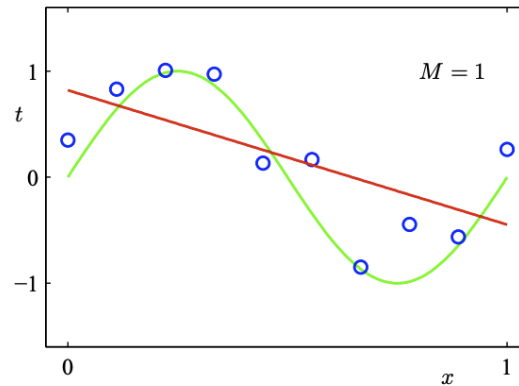
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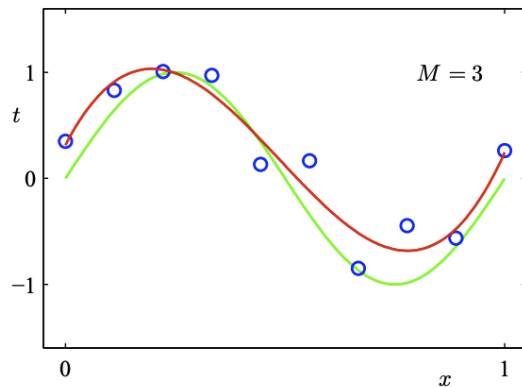


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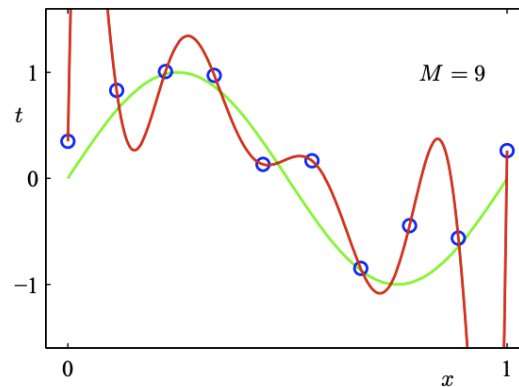


As the degree (complexity) increases, the variance of the model tends to increase, and the bias tends to decrease!

$$y = w_0 + w_1x + w_2x^2 + w_3x^3$$



$$y = w_0 + w_1x + \dots + w_9x^9$$



# Linear Regression

- Validation and Testing: Bias vs. Variance Tradeoff

Recall

$$(x_n, y_n) \stackrel{\text{iid}}{\sim} \mathbb{P}_{\text{data}}(x, y) \quad n = 1, \dots, N$$

Our training dataset

$$D = \{(x_n, y_n) | n = 1, \dots, N\} \sim \mathbb{P}_{\text{data}}(x, y)^N$$

Expected label/output

$$\bar{y}(x) = \mathbb{E}_{\mathbb{P}_{\text{data}}(y|x)} [y] = \int_y y \mathbb{P}_{\text{data}}(y|x) dy$$

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$$f(x, w^*) = f(x, \mathcal{A}(D, w^0)) \equiv f_D(x)$$

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Learning algorithm depends on training dataset, initial parameters, and hyperparameters

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- Validation and Testing: Bias vs. Variance Tradeoff

Generalization error

$$\mathbb{E}_{\mathbb{P}_{\text{data}}(x,y)} [(y - f_D(x))^2]$$

Expected generalization error

$$\mathbb{E}_{D \sim \mathbb{P}_{\text{data}}(x,y)^N, (x,y) \sim \mathbb{P}_{\text{data}}(x,y)} [(y - f_D(x))^2]$$

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This is what we really care in comparing different learning systems as it considers all possible training sets!



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# Linear Regression

- Validation and Testing: Bias vs. Variance Tradeoff

Decomposition of expected generalization error:

$$\mathbb{E}_{D,x,y} [(y - f_D(x))^2] = \mathbb{E}_{D,x} [(f_D(x) - \bar{f}(x))^2] + 2\mathbb{E}_{D,x,y} [(f_D(x) - \bar{f}(x))(\bar{f}(x) - y)] + \mathbb{E}_{x,y} [(\bar{f}(x) - y)^2]$$

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$$\begin{aligned}\mathbb{E}_{x,y} [(\bar{f}(x) - y)^2] &= \mathbb{E}_{x,y} [(\bar{f}(x) - \bar{y}(x) + \bar{y}(x) - y)^2] \\ &= \mathbb{E}_{x,y} [(\bar{f}(x) - \bar{y}(x))^2] + 2\mathbb{E}_{x,y} [(\bar{f}(x) - \bar{y}(x))(\bar{y}(x) - y)] + \mathbb{E}_{x,y} [(\bar{y}(x) - y)^2]\end{aligned}$$

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**Variance:** Captures how much your classifier changes if you train on a different training set. How "over-specialized" is your classifier to a particular training set (overfitting)? If we have the best possible model for our training data, how far off are we from the average classifier?

**Bias:** What is the inherent error that you obtain from your classifier even with infinite training data? This is due to your classifier being "biased" to a particular kind of solution (e.g. linear classifier). In other words, bias is inherent to your model.

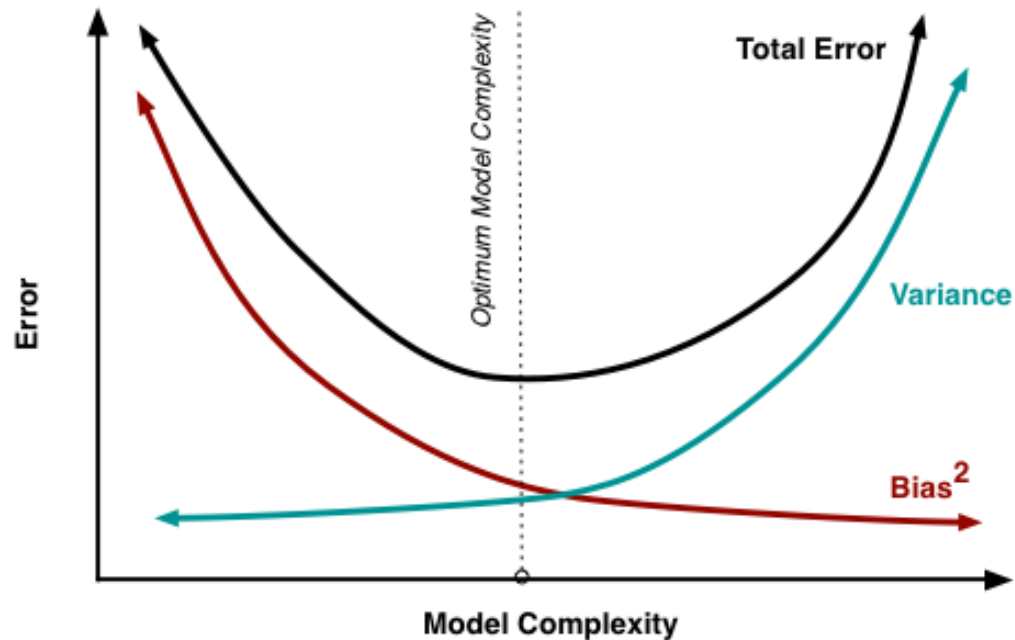
**Noise:** How big is the data-intrinsic noise? This error measures ambiguity due to your data distribution and feature representation. You can never beat this, it is an aspect of the data.

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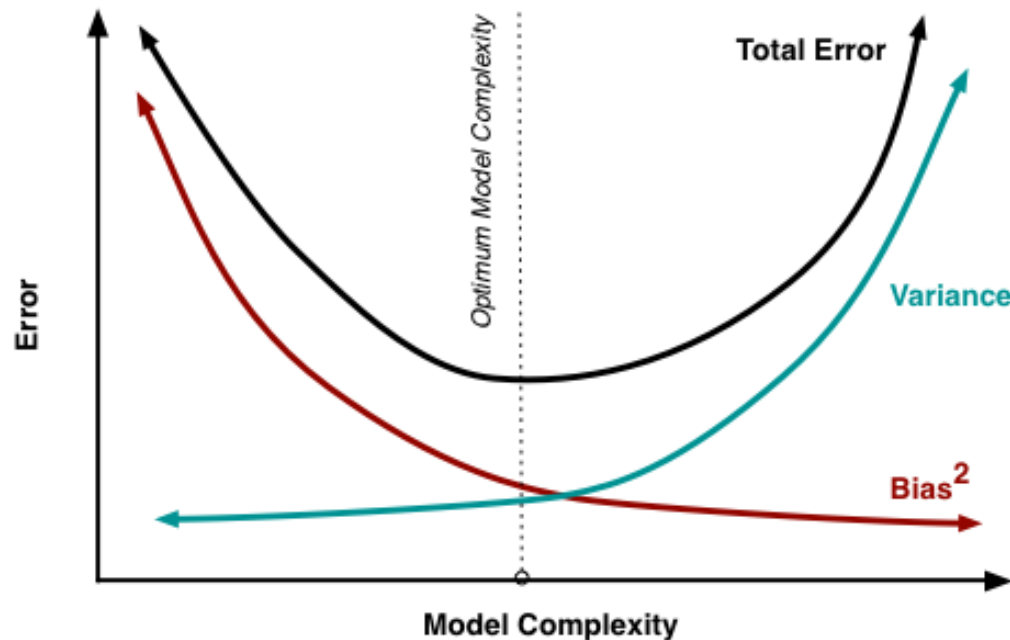


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This classic bias-variance tradeoff can not explain deep learning as the model complexity measure is hard to find, e.g., #parameters is clearly not the right one!

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# Linear Models for Classification

Suppose we'd like to do a binary classification with a linear model

$$\{(x_n, y_n) | n = 1, \dots, N\} \stackrel{\text{iid}}{\sim} \mathbb{P}_{\text{data}}(x, y)$$

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**Answer: continuous approximation!**

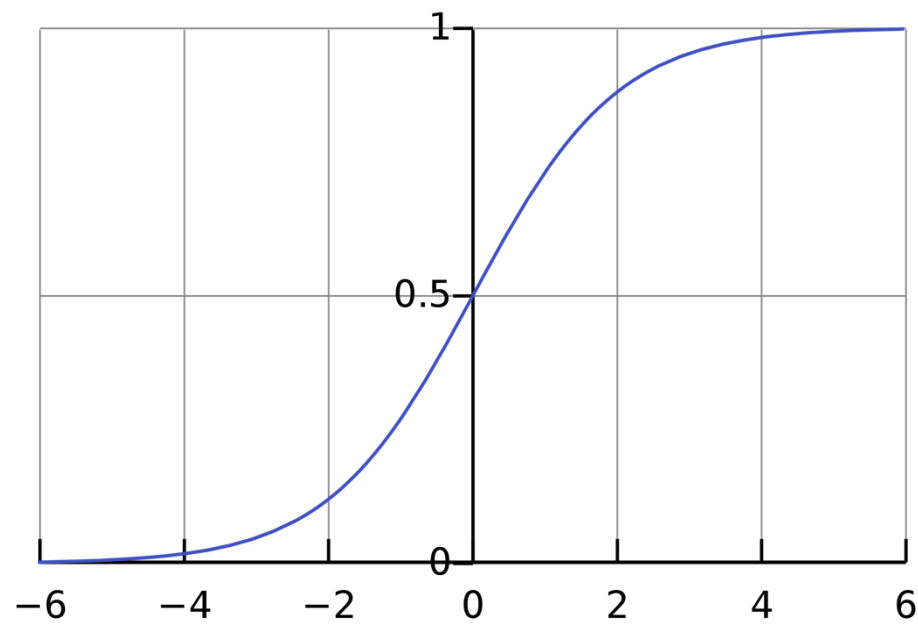
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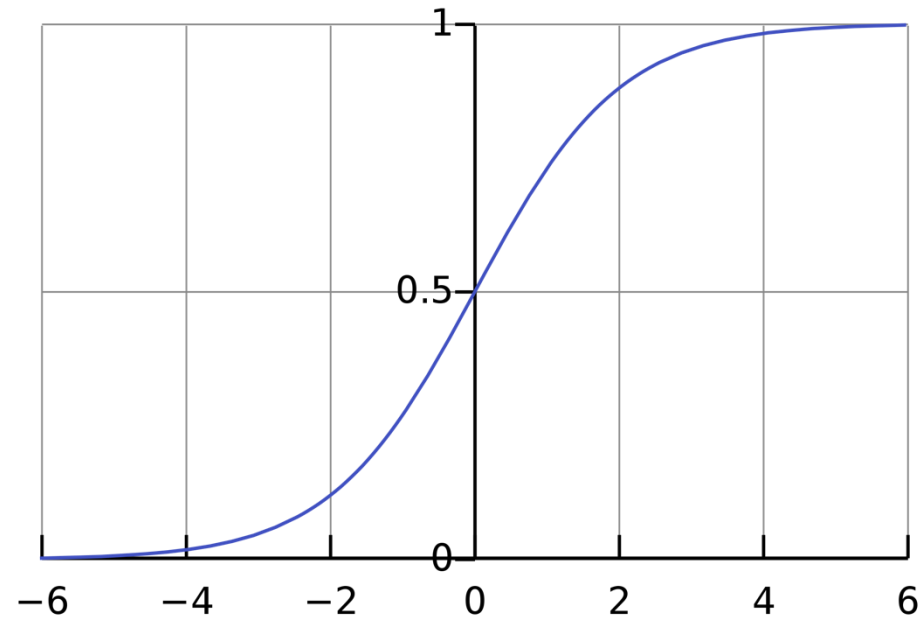
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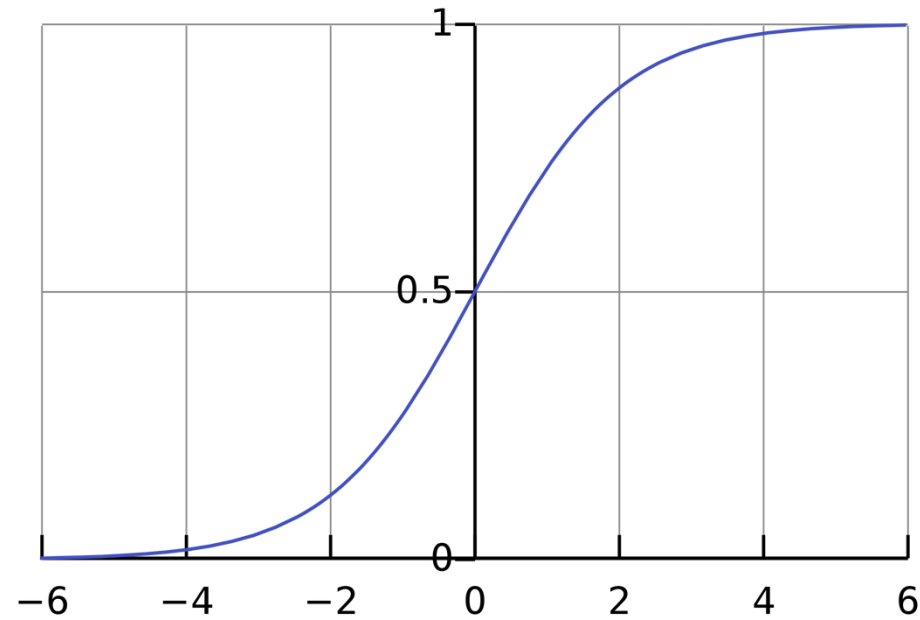
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**This outputs a probability!**



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In practice, the *softmax+cross-entropy* is implemented via this *log-sum-exp* trick!

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$$\lim_{\beta \rightarrow 0} \text{softmax}(x) = \underbrace{[0, \dots, 0, 1, 0, \dots, 0]}_{\text{k-th entry is 1 and } k = \text{argmax}_i x[i]}$$

# More About Softmax

Softmax is an approximation to the argmax.

To see this, we can change the base of the power

$$e \rightarrow e^{\frac{1}{\beta}}$$

Therefore, *softmax* should actually be called *softargmax*!

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Also,

$$\lim_{\beta \rightarrow \infty} \text{softmax}(x) = \left[ \frac{1}{K}, \dots, \frac{1}{K} \right]$$

$\beta$  is often called as *temperature*.

# References

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Questions?