

EECE 571F: Deep Learning with Structures

Lecture 2: Invariance, Equivariance, and Deep Learning Models for Sets/Sequences

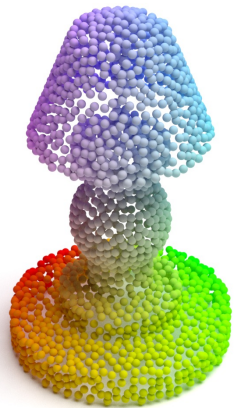
Renjie Liao

University of British Columbia

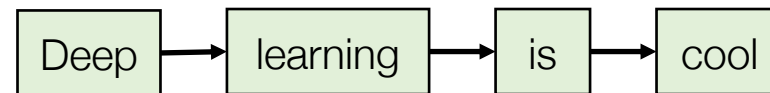
Winter, Term 2, 2021/22

Course Scope

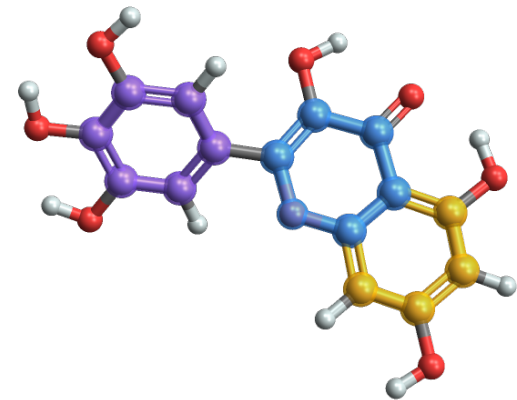
- **Supervised Learning with Observable Structures**
- Unsupervised / Self-supervised Learning with Observable Structures
- Supervised Learning with Latent Structures



Points/Sets



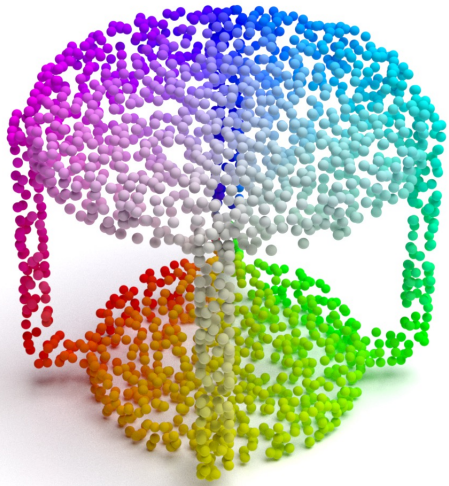
Lists/Sequences



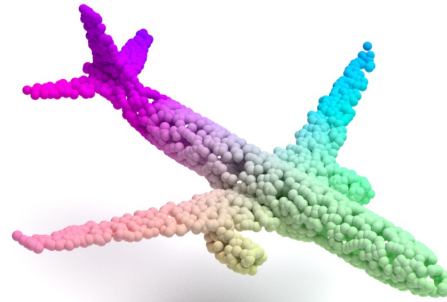
Graphs

Motivating Applications for Sets

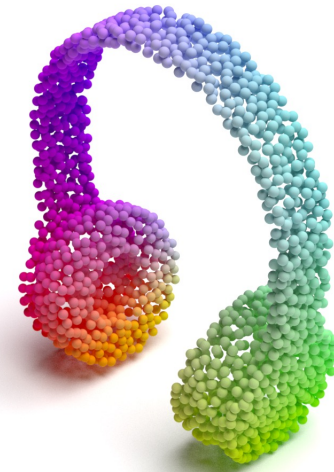
- Population Statistics
- Point Cloud Classification



Table



Airplane



Earphone

Invariance & Equivariance

- Invariance:

A mathematical object (or a class of mathematical objects) remains unchanged after operations or transformations of a certain type are applied to the objects

$$f(X) = f(g(X))$$

Invariance & Equivariance

- Invariance: **Symmetry Group: all transformations under which the object is invariant**

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- Equivariance:

Applying a transformation and then computing the function produces the same result as computing the function and then applying the transformation

$$g(f(X)) = f(g(X))$$

Revisit Convolution

Matrix multiplication views of (discrete) convolution:

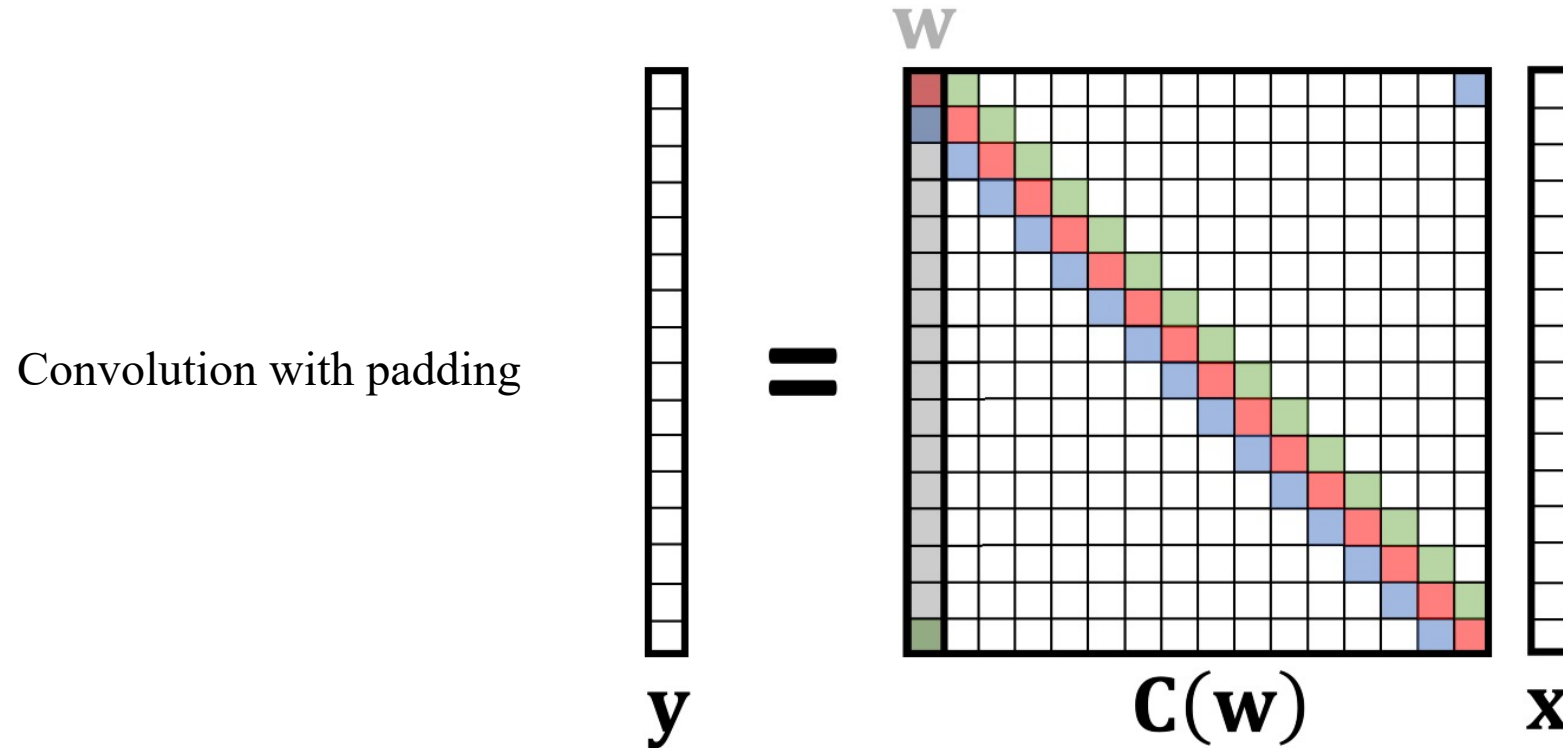
- Filter \Rightarrow Toeplitz matrix
- Data \Rightarrow Toeplitz matrix

Revisit Convolution

Matrix multiplication views of (discrete) convolution:

- Filter => Toeplitz matrix
- Data => Toeplitz matrix

Consider a special Toeplitz matrix: circulant matrix (must be square!)



Translation/Shift Operator

$\mathbf{y} = \mathbf{S} \mathbf{x}$

$\mathbf{y} = \mathbf{S}^T \mathbf{x}$

$\mathbf{S} \mathbf{S}^T = \mathbf{S}^T \mathbf{S} = \mathbf{I}$

Translation/Shift Operator

Shift operator is also a circulant matrix!

A diagram illustrating the shift operator S . On the left is a vertical vector y with four colored cells: white, yellow, blue, and green. In the middle is a 4x4 matrix S with black squares at (1,4), (2,1), (3,2), and (4,3). On the right is a vertical vector x with four colored cells: yellow, blue, green, and white. An equals sign is between y and S , and another equals sign is between S and x .

$$\mathbf{y} = \mathbf{S} \mathbf{x}$$

A diagram illustrating the inverse shift operator S^T . On the left is a vertical vector y with four colored cells: blue, green, white, and yellow. In the middle is a 4x4 matrix S^T with black squares at (1,1), (2,2), (3,3), and (4,4). On the right is a vertical vector x with four colored cells: yellow, blue, green, and white. An equals sign is between y and S^T , and another equals sign is between S^T and x .

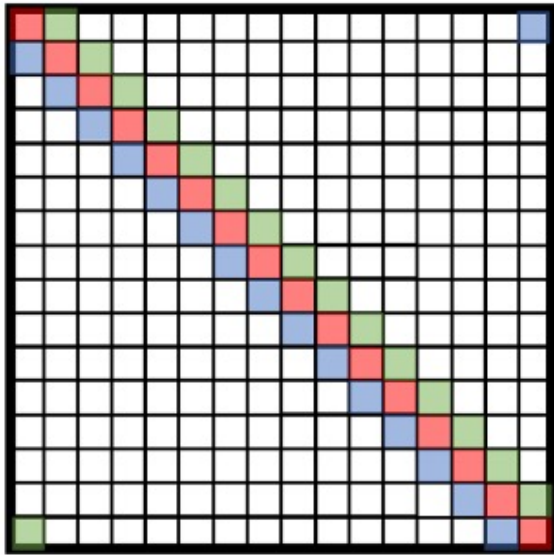
$$\mathbf{y} = \mathbf{S}^T \mathbf{x}$$

A diagram showing the identity property of the shift operator. It consists of four 4x4 matrices and three equals signs. The first matrix is S (black squares at (1,4), (2,1), (3,2), (4,3)). The second matrix is S^T (black squares at (1,1), (2,2), (3,3), (4,4)). The third matrix is S^T (black squares at (1,1), (2,2), (3,3), (4,4)). The fourth matrix is S (black squares at (1,4), (2,1), (3,2), (4,3)). The fifth matrix is I (black squares at (1,1), (2,2), (3,3), (4,4)).

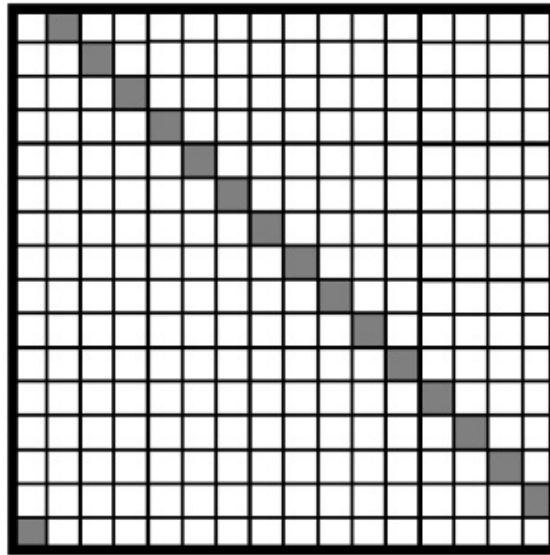
$$\mathbf{S} \mathbf{S}^T = \mathbf{S}^T \mathbf{S} = \mathbf{I}$$

Translation/Shift Equivariance

Matrix multiplication is non-commutative. But not for circulant matrices!



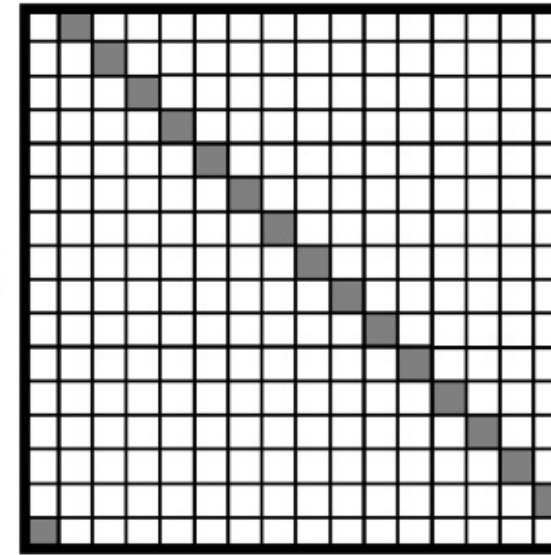
$C(w)$



S^T

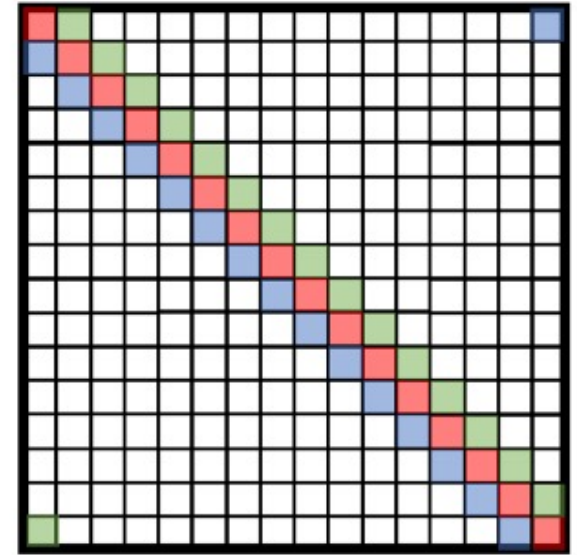
shift operator

$=$



S^T

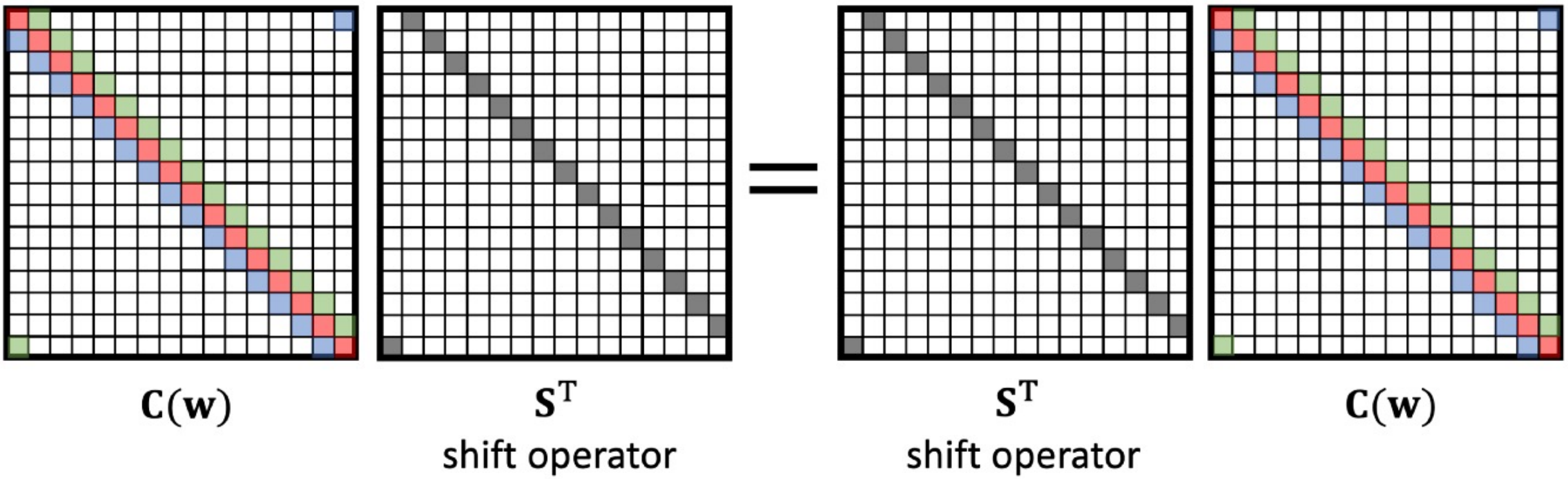
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Translation/Shift Equivariance

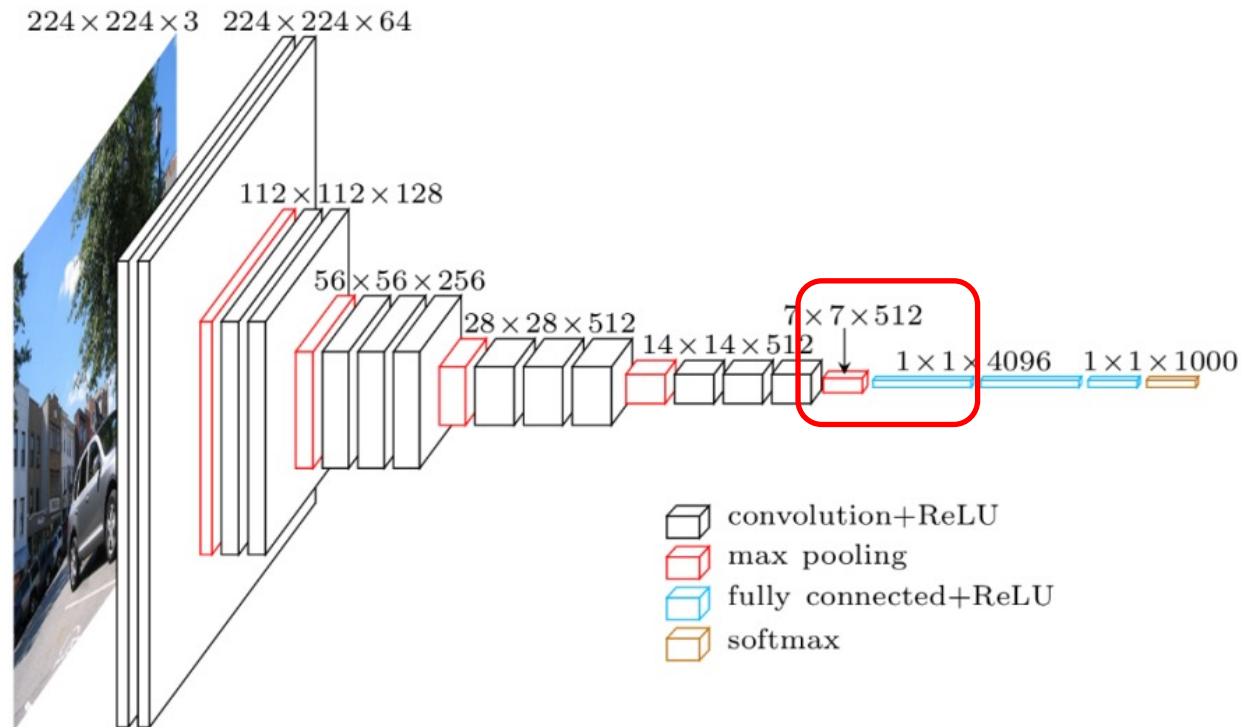
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Convolution is translation equivariant, i.e., $\text{Conv}(\text{Shift}(X)) = \text{Shift}(\text{Conv}(X))!$

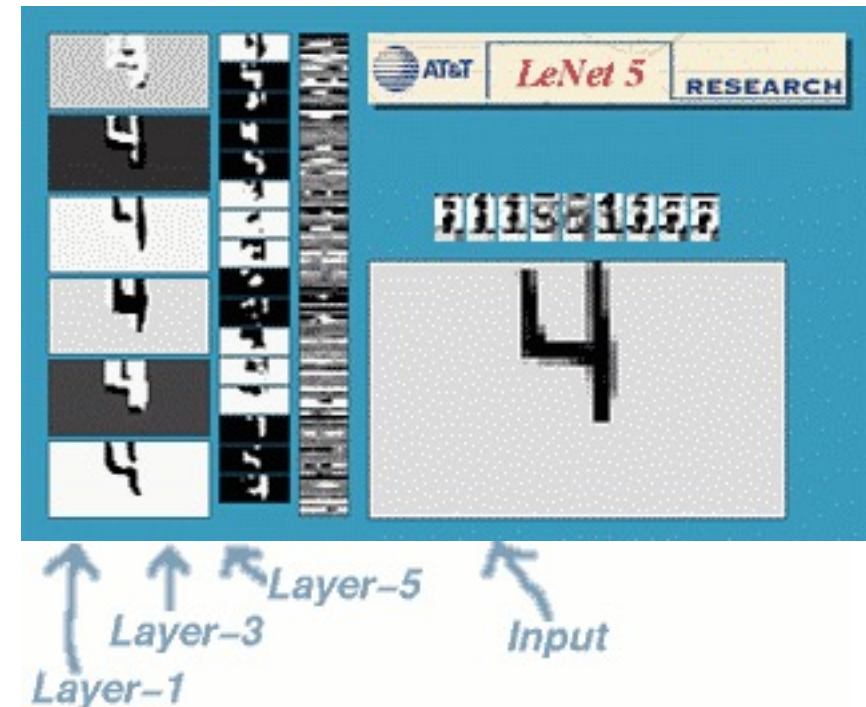
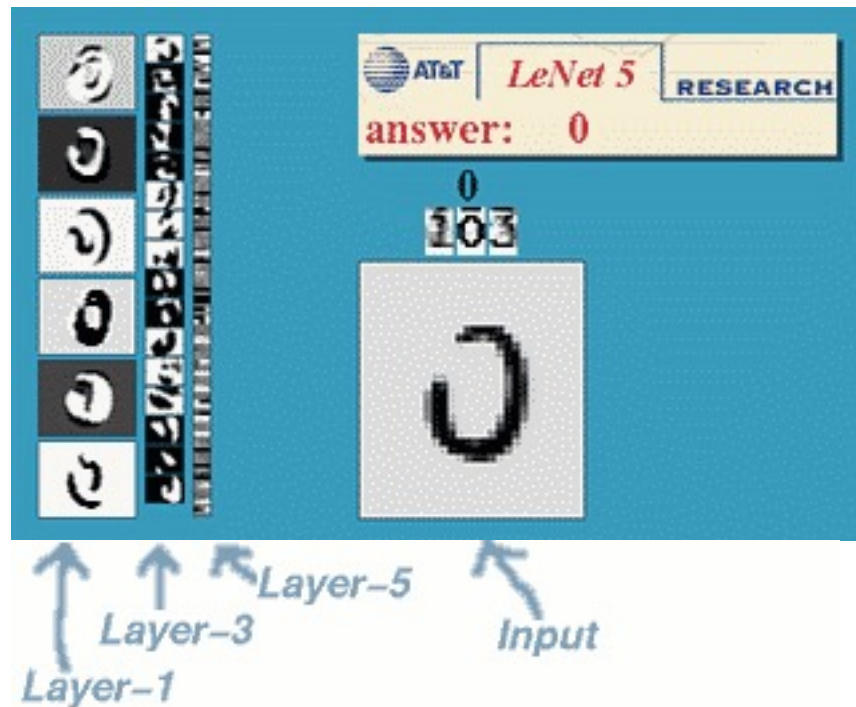
Translation/Shift Invariance

Global pooling gives you shift-invariance!

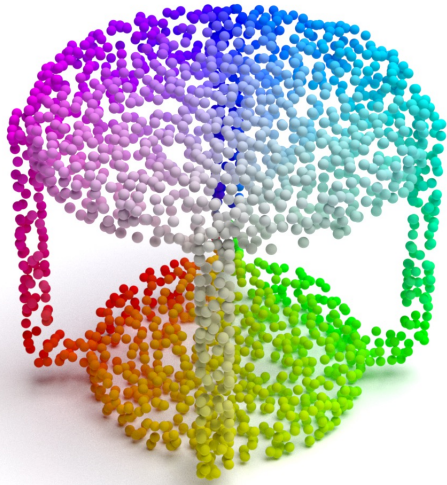


Translation/Shift Equivariance Invariance

Yann LeCun's LeNet Demo:



Permutation Invariance



Table

Point Clouds

$$X \in \mathbb{R}^{n \times 3}$$

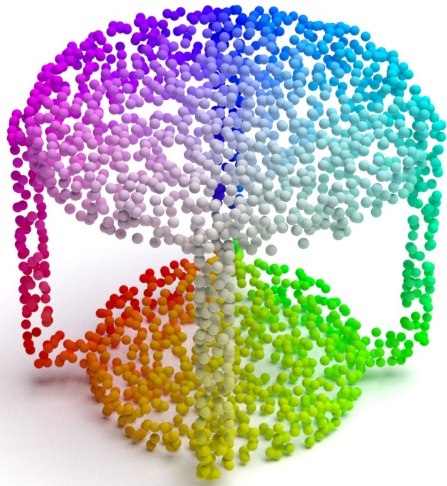
Probability of Classes

$$Y \in \mathbb{R}^{1 \times K}$$

Permutation / Shuffle

$$P \in \mathbb{R}^{n \times n}$$

Permutation Invariance



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$$\begin{bmatrix} 2 \\ 5 \\ 3 \\ 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}$$

Geometric Interpretation of Permutation Matrix

Birkhoff Polytope

$$B_n = \{P \in \mathbb{R}^{n \times n} \mid \forall i \forall j P_{ij} \geq 0, \forall i \sum_j P_{ij} = 1, \forall j \sum_i P_{ij} = 1\}$$

Doubly Stochastic Matrix

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Doubly Stochastic Matrix

Birkhoff–von Neumann Theorem:

1. Birkhoff Polytope is the convex hull of permutation matrices
2. Permutation matrices = Vertices of Birkhoff Polytope S_n

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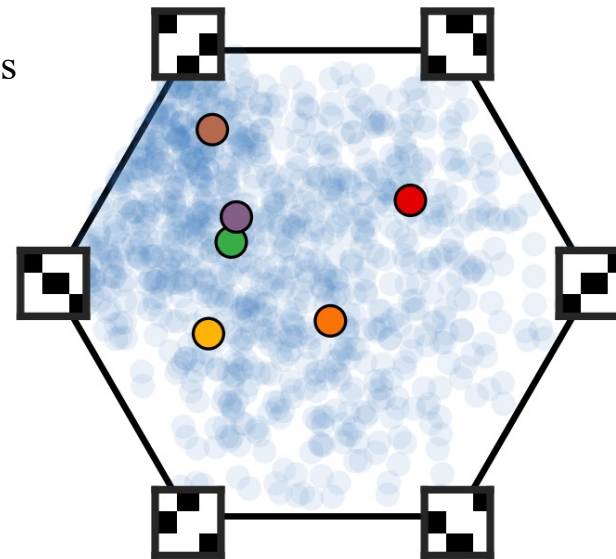
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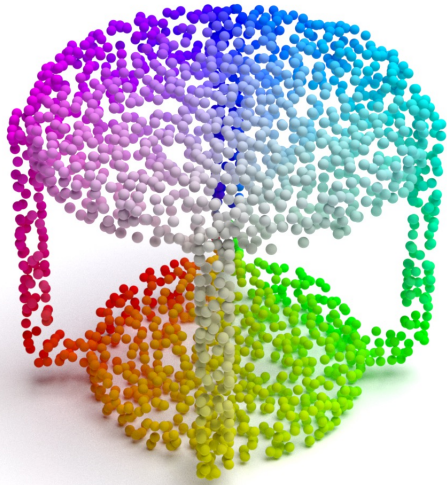
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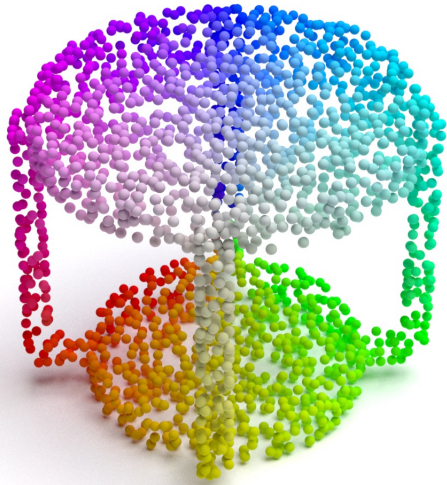
$$Y \in \mathbb{R}^{1 \times K}$$

Permutation / Shuffle

$$P \in \mathbb{R}^{n \times n}$$

$$Y = f(PX) \quad \forall P \in S_n$$

Permutation Equivariance



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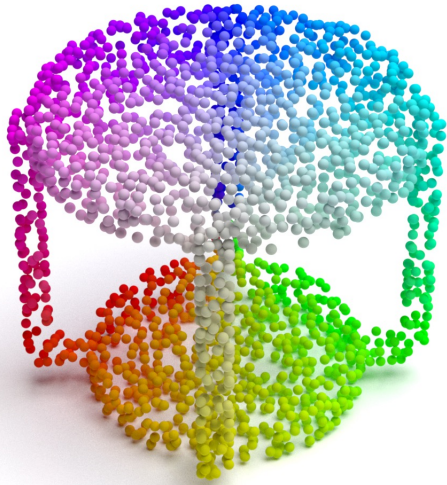
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Point Representations

$$H \in \mathbb{R}^{n \times d}$$

Permutation Equivariance



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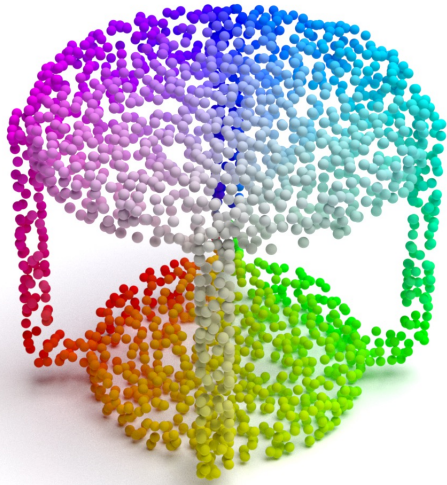
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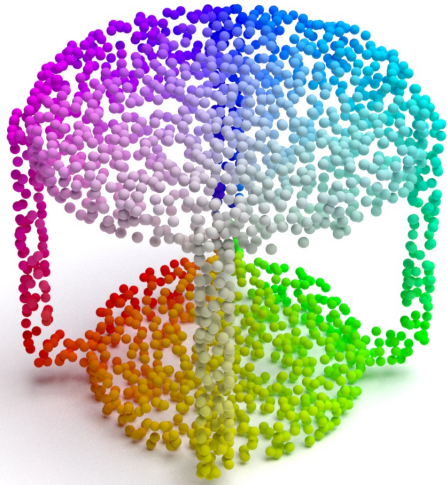
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$$H = f(X)$$

$$PH = Pf(X) = f(PX)$$

Permutation Equivariance



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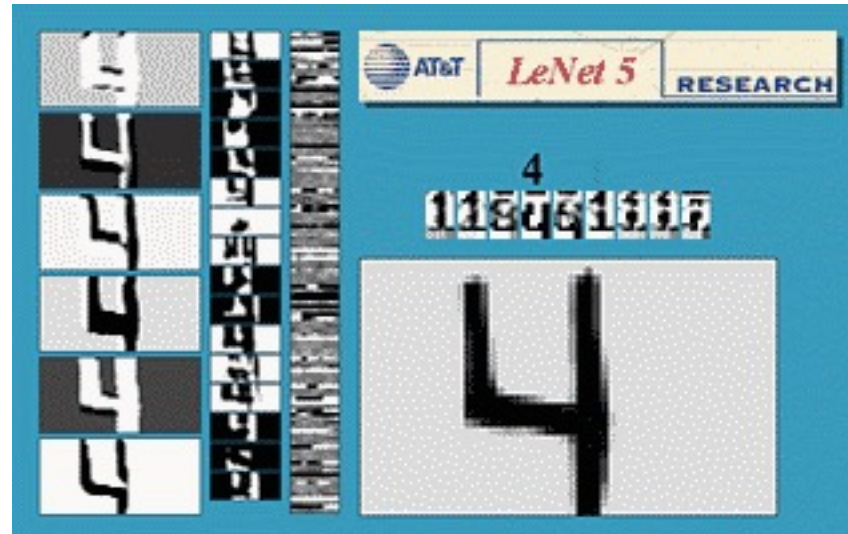
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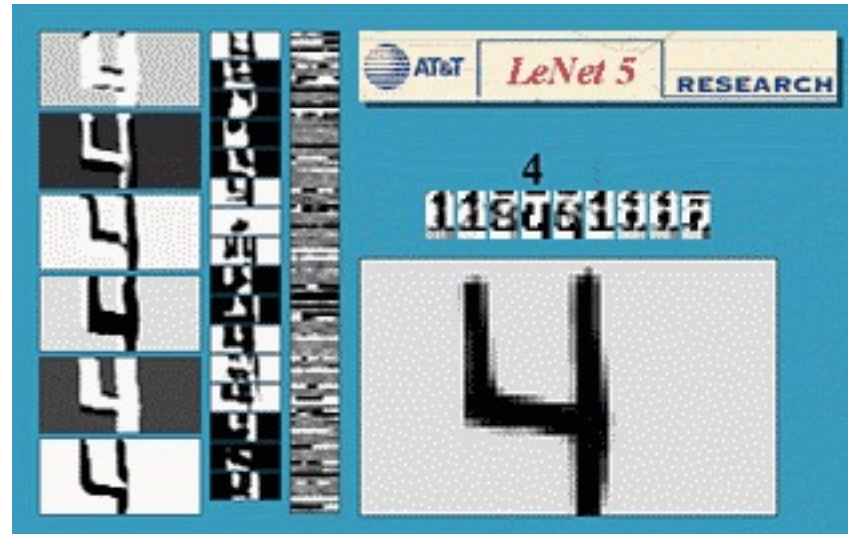
More on Invariance & Equivariance

- What about other transformations, e.g., scaling, 2D/3D rotations, Gauge transformation?



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- Generalize to Group Invariance & Equivariance

Recommend Taco Cohen's PhD Thesis: <https://pure.uva.nl/ws/files/60770359/Thesis.pdf>

Deep Learning for Sets

- Point-level Tasks

Input: a vector per point

Output: a label/vector per point

Predictions of individual points are independent, e.g., image classification

Deep Learning for Sets

- Point-level Tasks

Input: a vector per point

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Predictions of individual points are independent, e.g., image classification

- Set-level Tasks

Input: a set of vectors, each corresponds to a point

Output: a label/vector per set

Prediction of a set depends on all points, e.g., point cloud classification

Deep Learning for Sets

Key Challenges:

- Varying-sized input sets
- Permutation equivariant and invariant models
- Expressive models

Deep Learning for Sets

- Deep Sets [1]

Theorem 2 *A function $f(X)$ operating on a set X having elements from a countable universe, is a valid set function, i.e., **invariant** to the permutation of instances in X , iff it can be decomposed in the form $\rho\left(\sum_{x \in X} \phi(x)\right)$, for suitable transformations ϕ and ρ .*

Deep Learning for Sets

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Sketch of Proof

Sufficiency: summation is permutation invariant!

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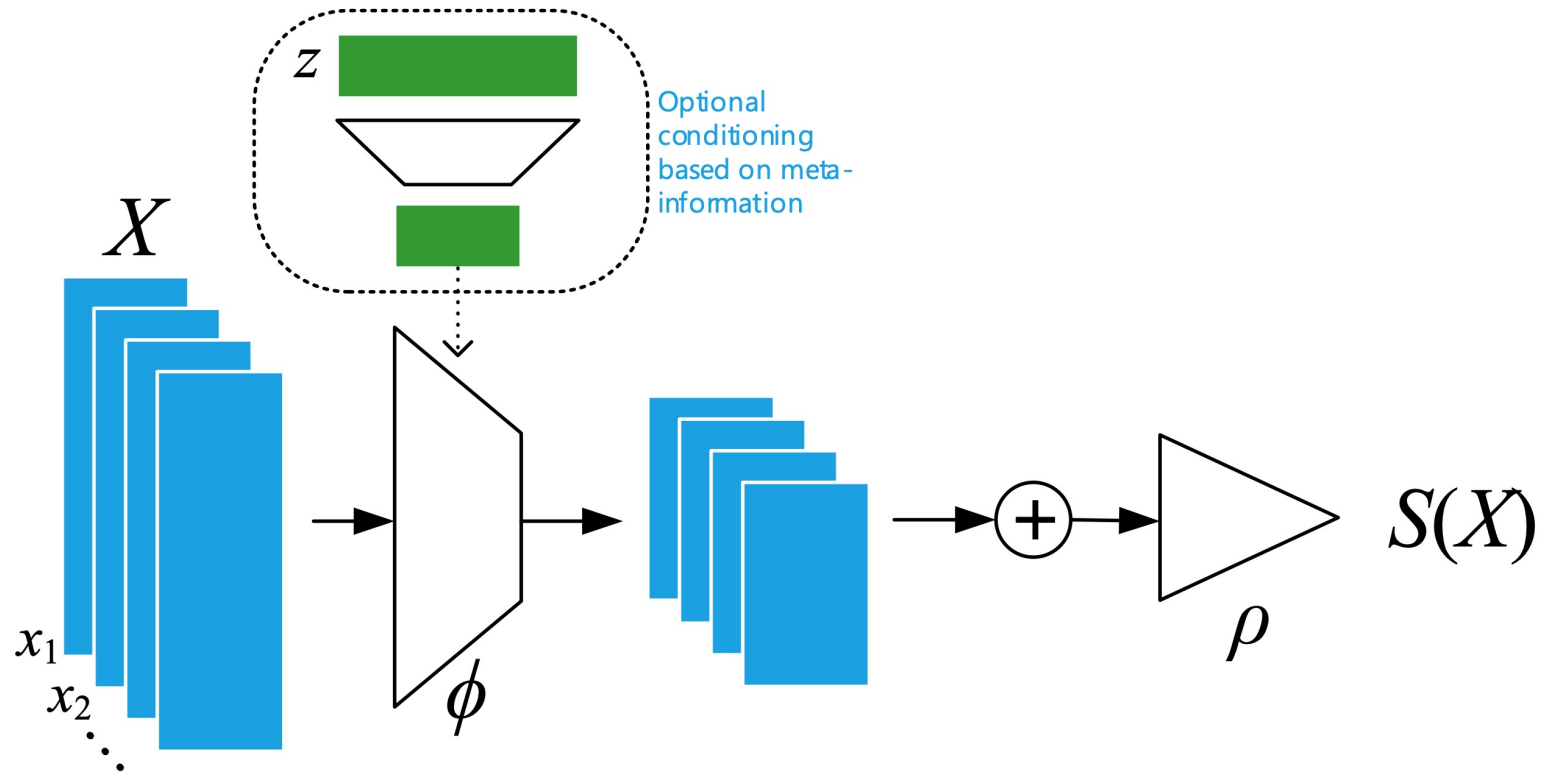
Necessity:

1. Construct a mapping $c : \mathfrak{X} \rightarrow \mathbb{N}$
2. Let $\phi(x) = 4^{-c(x)}$
3. Bijection $X \in 2^{\mathfrak{X}} \iff \sum_{x \in X} \phi(x)$

Deep Learning for Sets

- Deep Sets [1]

Invariant Architecture



Deep Learning for Sets

- Deep Sets [1] $\mathbf{f}_\Theta(\mathbf{x}) \doteq \sigma(\Theta\mathbf{x}) \quad \Theta \in \mathbb{R}^{M \times M}$

Lemma 3 *The function $\mathbf{f}_\Theta : \mathbb{R}^M \rightarrow \mathbb{R}^M$ defined above is permutation **equivariant** iff all the off-diagonal elements of Θ are tied together and all the diagonal elements are equal as well. That is,*

$$\Theta = \lambda \mathbf{I} + \gamma (\mathbf{1}\mathbf{1}^\top) \quad \lambda, \gamma \in \mathbb{R} \quad \mathbf{1} = [1, \dots, 1]^\top \in \mathbb{R}^M \quad \mathbf{I} \in \mathbb{R}^{M \times M} \text{ is the identity matrix}$$

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2. All off-diagonal elements are identical

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$$\pi_{k,l}\Theta = \Theta\pi_{k,l} \Rightarrow \pi_{k,l}\Theta\pi_{l,k} = \Theta \Rightarrow (\pi_{k,l}\Theta\pi_{l,k})_{l,l} = \Theta_{l,l} \Rightarrow \Theta_{k,k} = \Theta_{l,l}$$

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$$\pi_{j',j}\pi_{i,i'}\Theta = \Theta\pi_{j',j}\pi_{i,i'} \Rightarrow \pi_{j',j}\pi_{i,i'}\Theta(\pi_{j',j}\pi_{i,i'})^{-1} = \Theta \Rightarrow$$

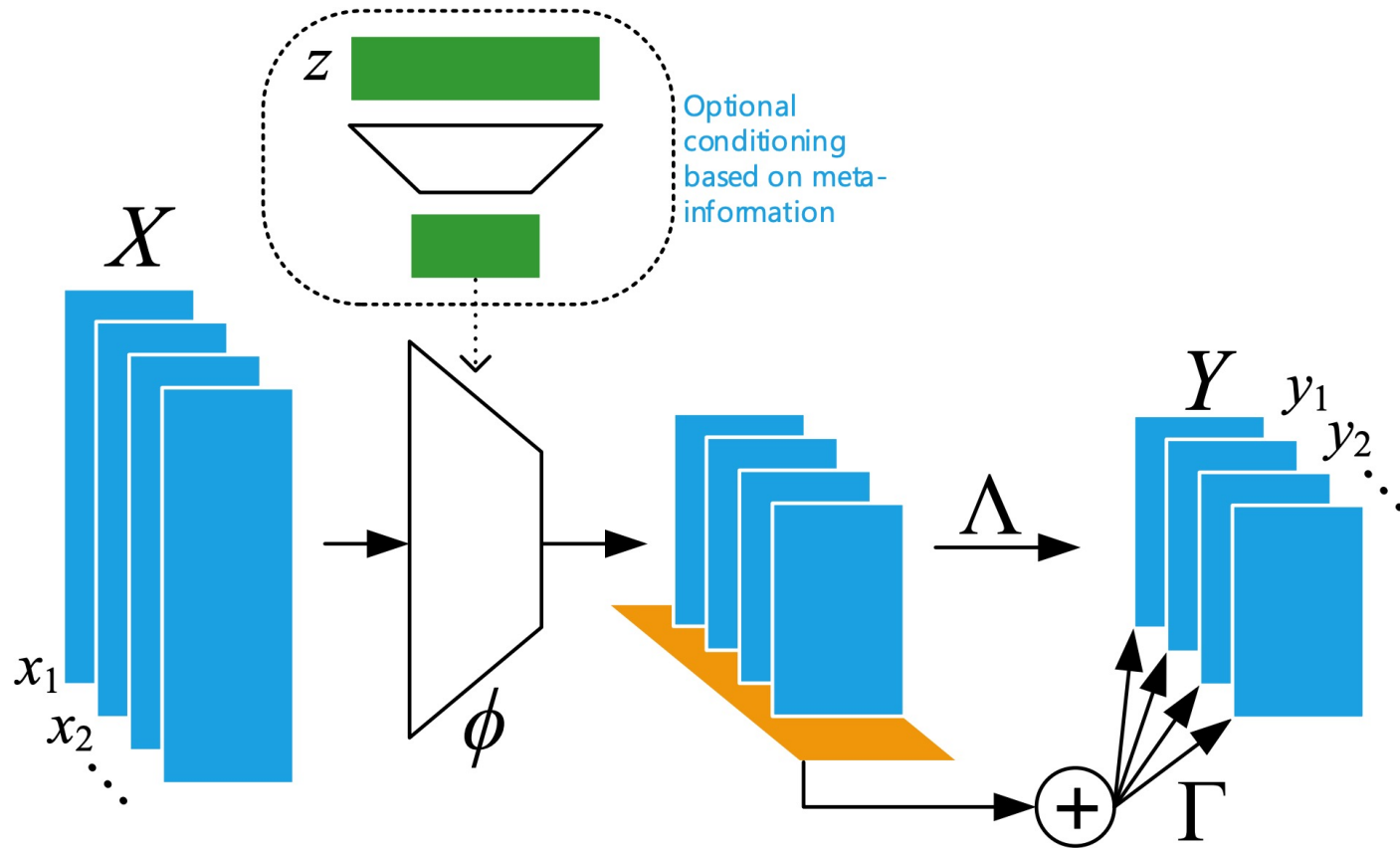
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Deep Learning for Sets

- Deep Sets [1]

Equivariant Architecture

$$f(\mathbf{x}) = \sigma(\mathbf{x}\Lambda - \mathbf{1}\mathbf{1}^T \mathbf{x}\Gamma)$$

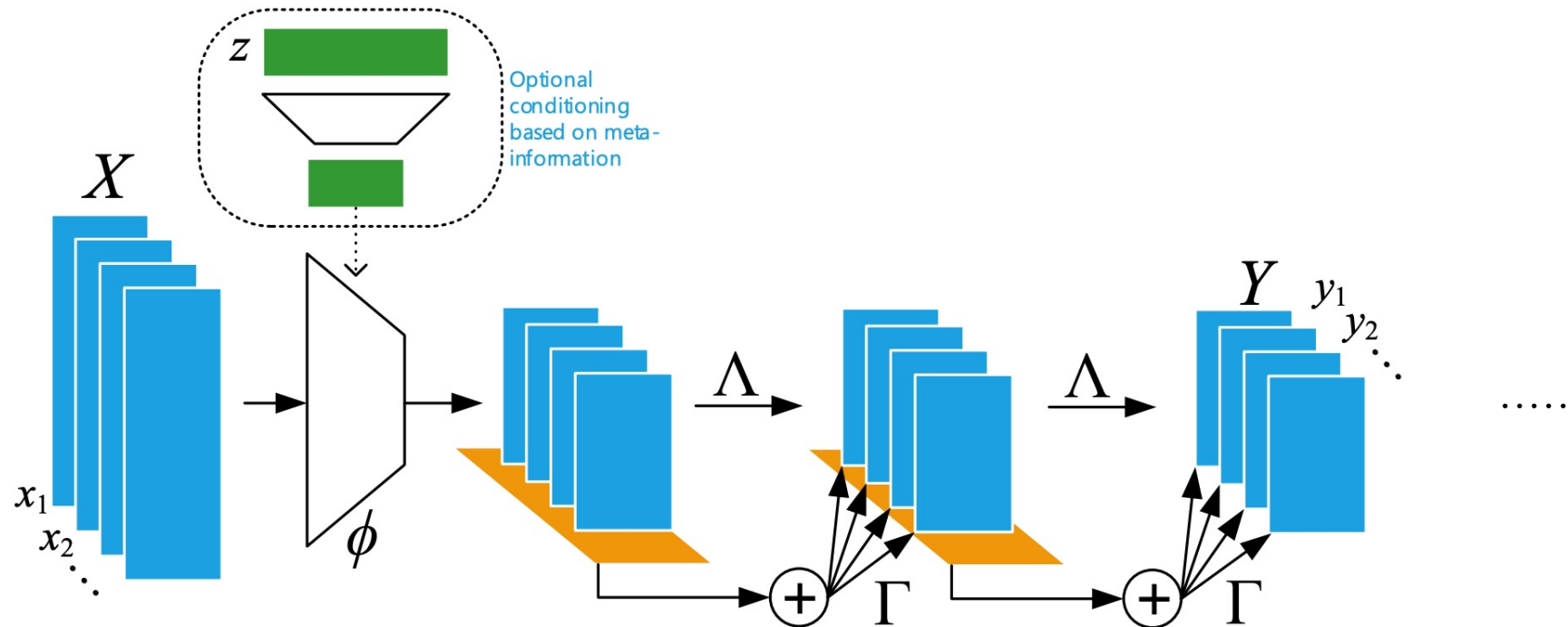


Deep Learning for Sets

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Recipe for making the model deep:

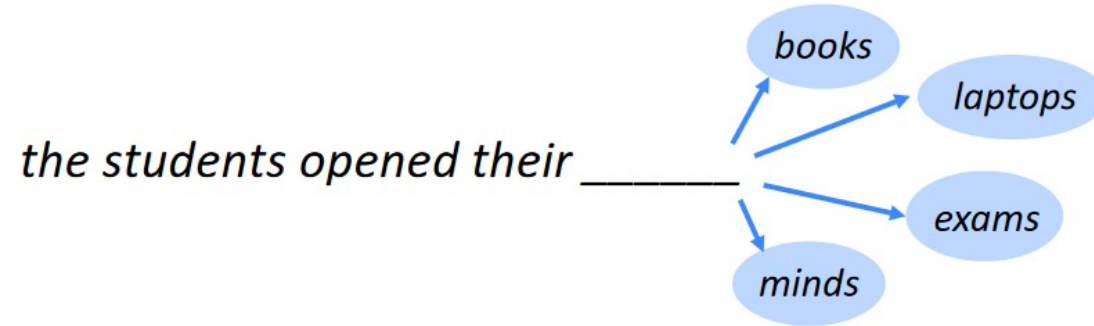
Stack multiple equivariant layers (+ invariant layer at the end), e.g., PointNet [2]



Deep Learning for Sequences

- Language Models

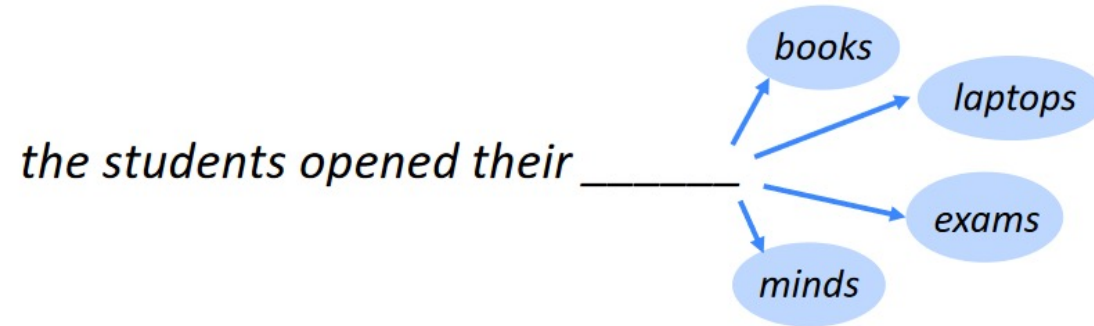
$$P(\mathbf{x}^{(t+1)} | \mathbf{x}^{(t)}, \dots, \mathbf{x}^{(1)})$$



Deep Learning for Sequences

- Language Models

$$P(\mathbf{x}^{(t+1)} | \mathbf{x}^{(t)}, \dots, \mathbf{x}^{(1)})$$



- Machine Translation



Deep Learning for Sequences

Key Challenges:

- Varying-sized input sequences

Deep Learning for Sequences

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- Orders “may” be crucial for cognition

Aoccdrnig to a rscheearch at Cmabrigde Uinervtisy, it deosn't mttar in waht oredr the ltteers in a wrod are, the olny iprmoetnt tihng is taht the frist and lsat ltteer be at the rghit pclae. The rset can be a toatl mses and you can sitll raed it wouthit porbelm. Tihs is bcuseae the huamn mnid deos not raed ervey lteter by istlef, but the wrod as a wlohe.

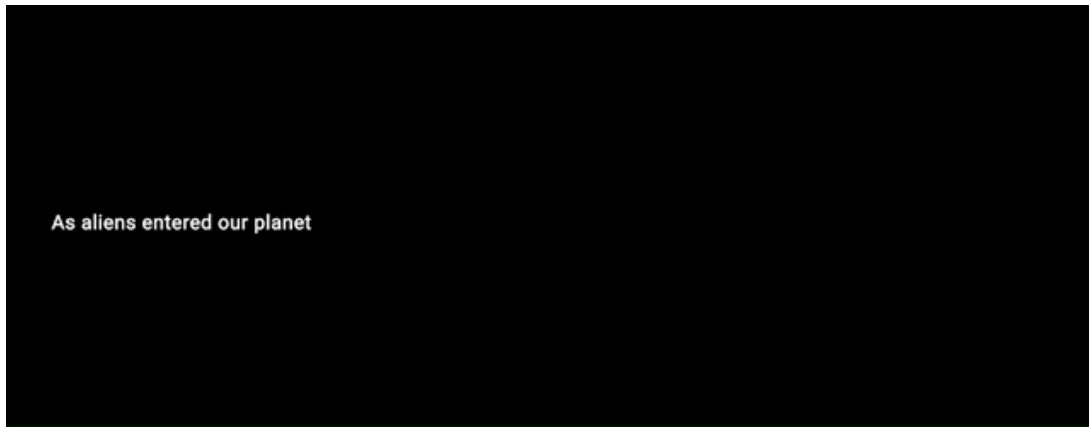
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- Complex statistical dependencies (e.g. long-range ones)



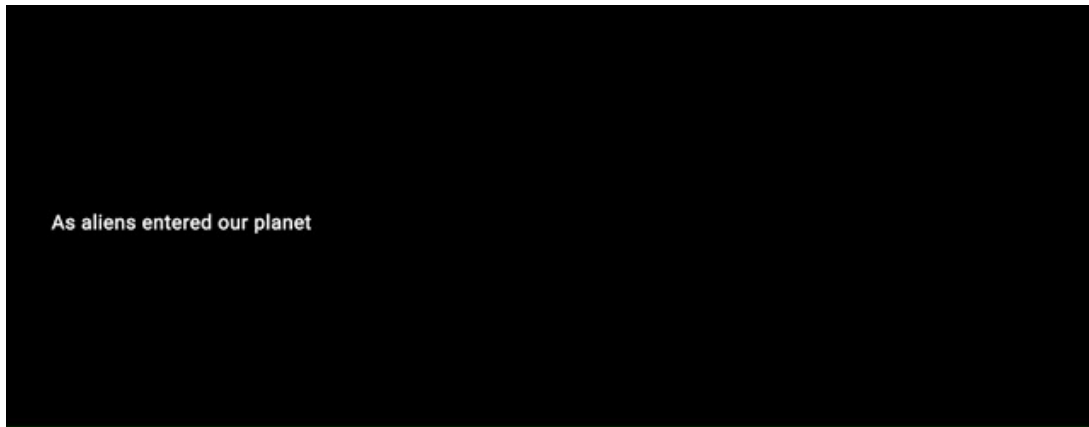
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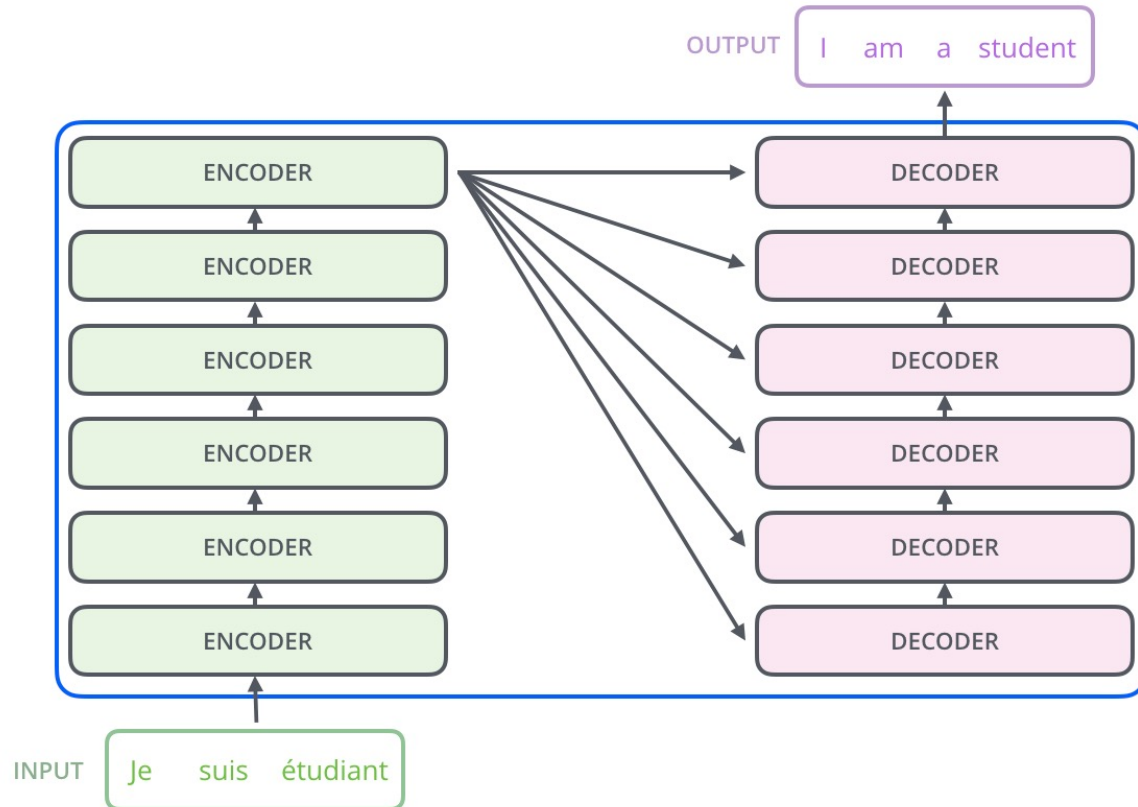
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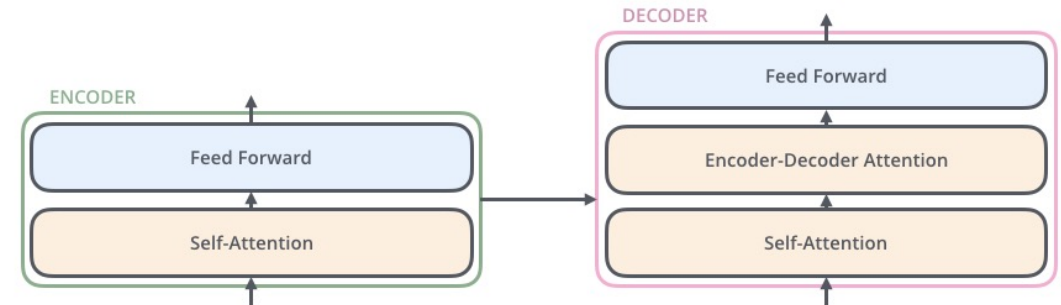
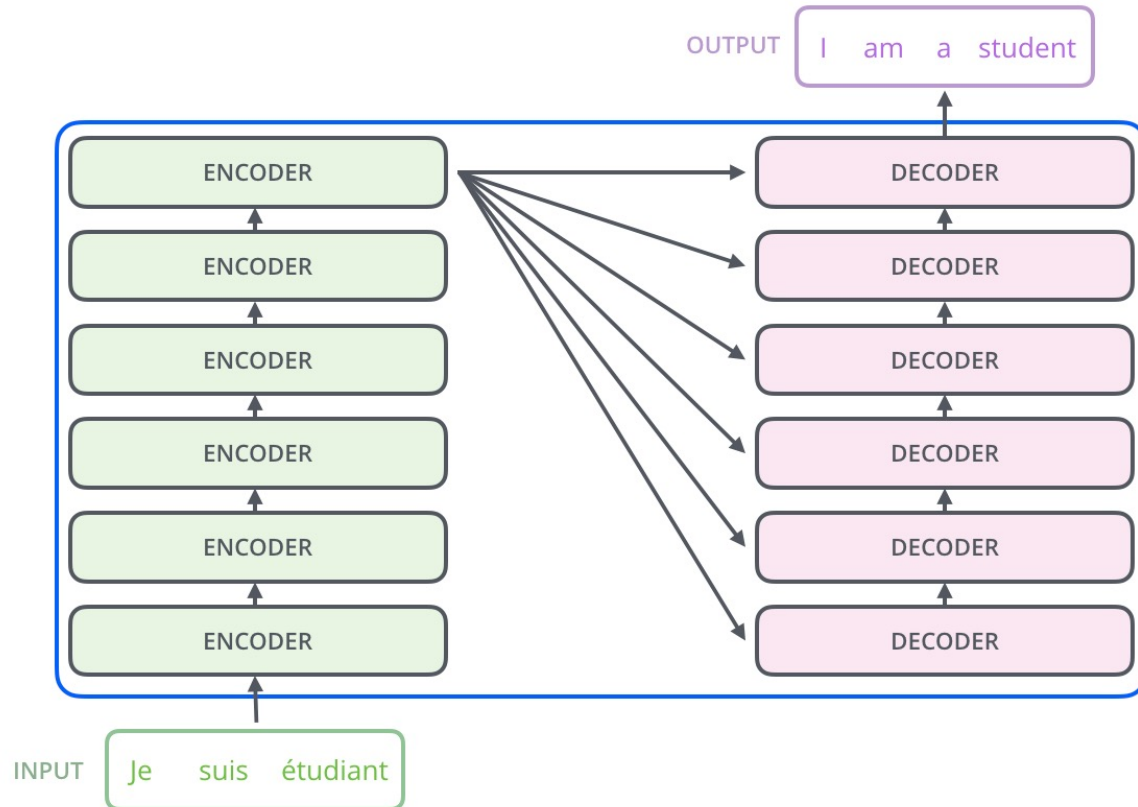


LSTM [3]
GRU [4]
Seq2Seq [5]
Transformer [6]

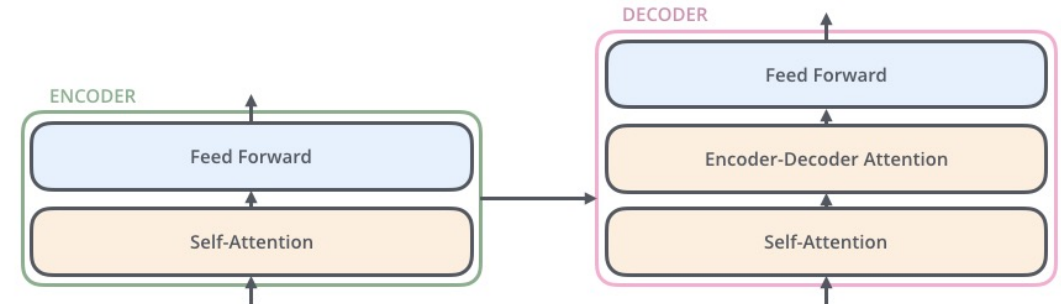
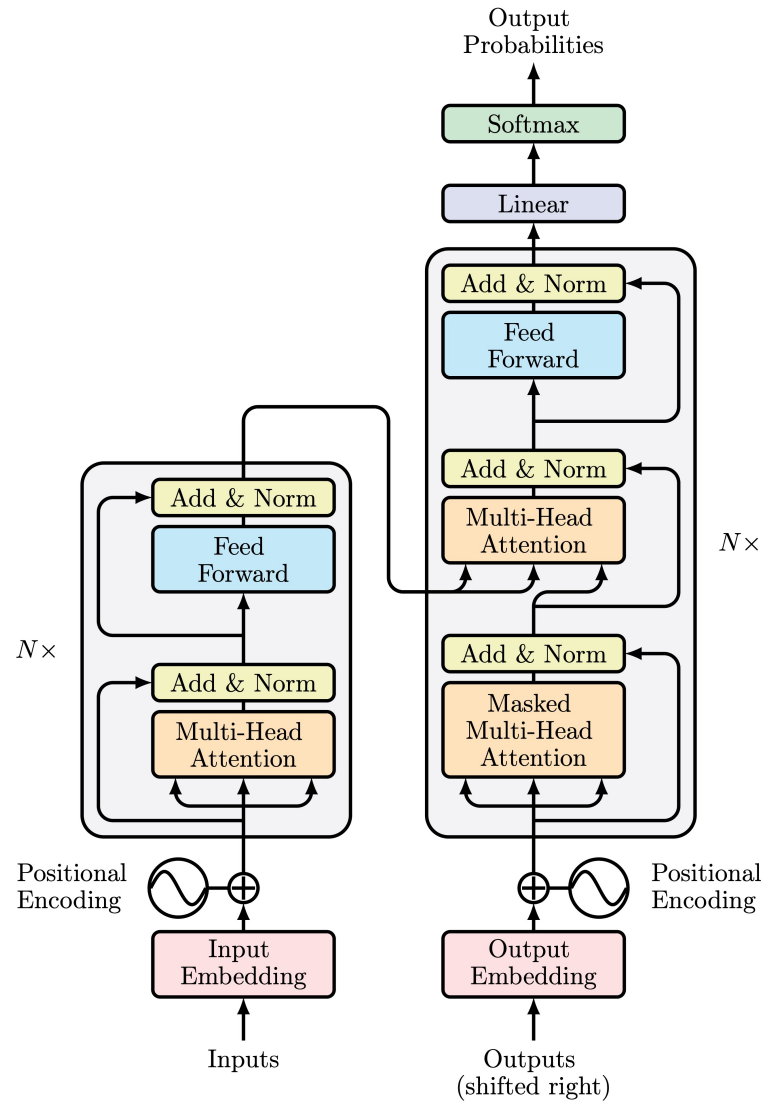
Transformers



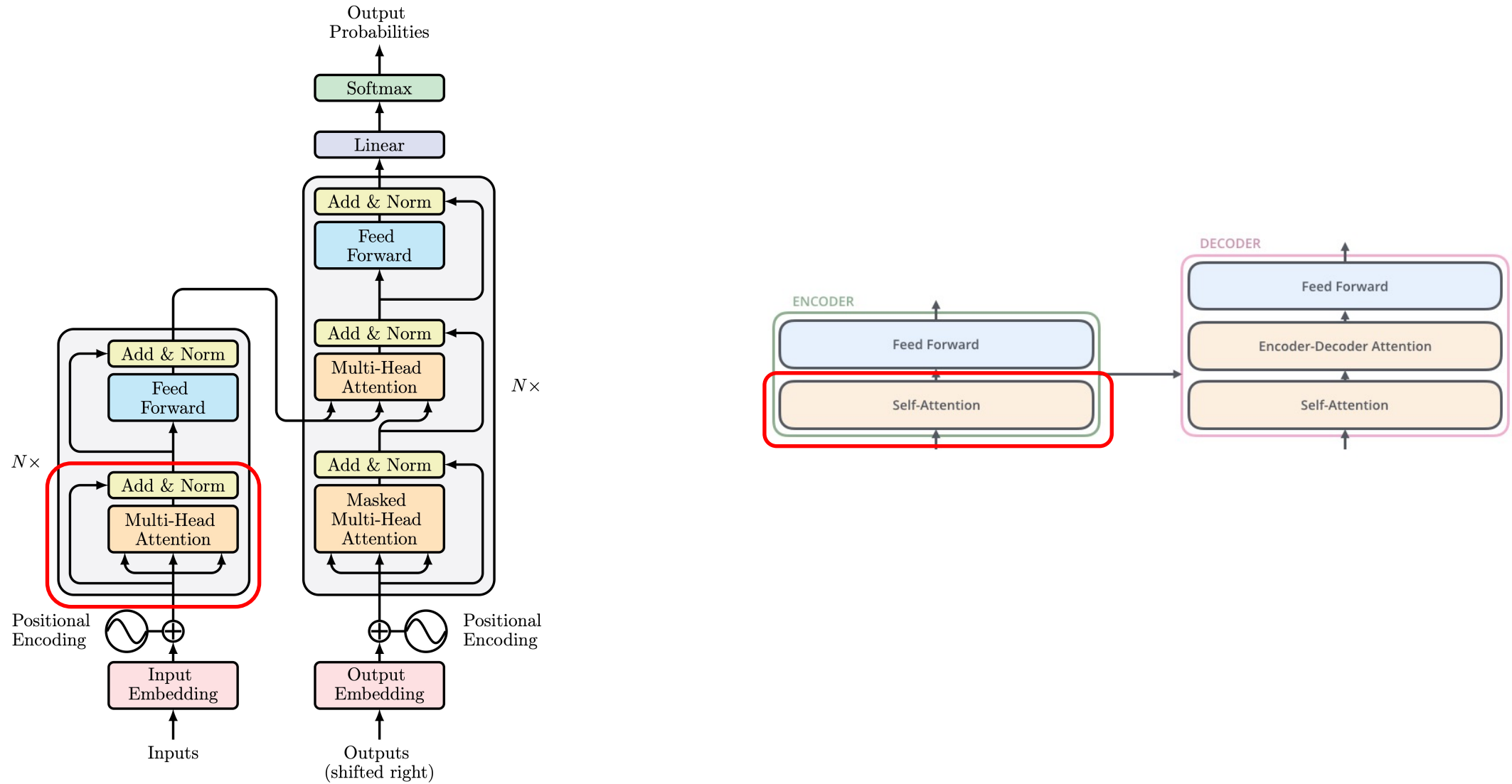
Transformers



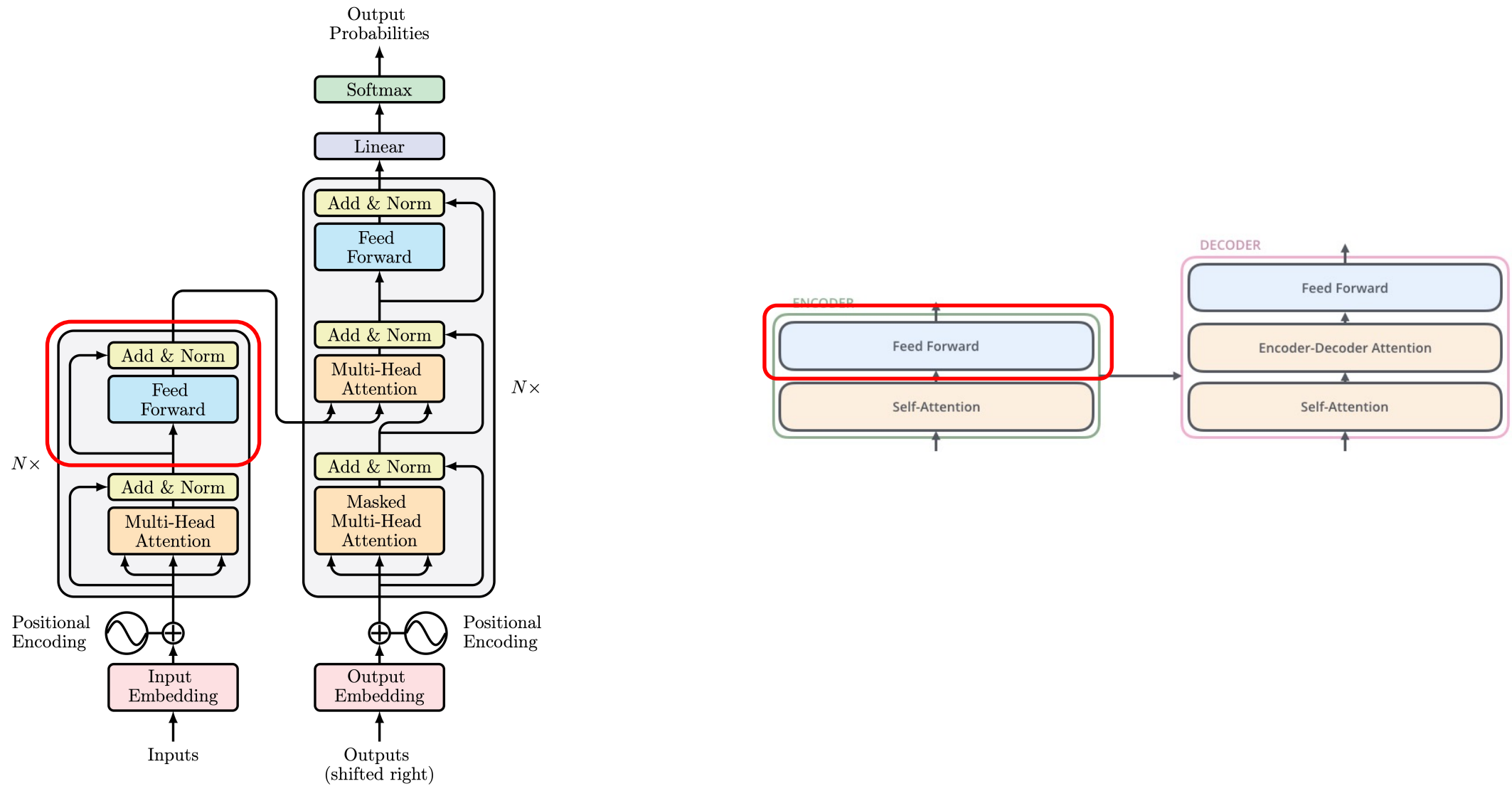
Transformers



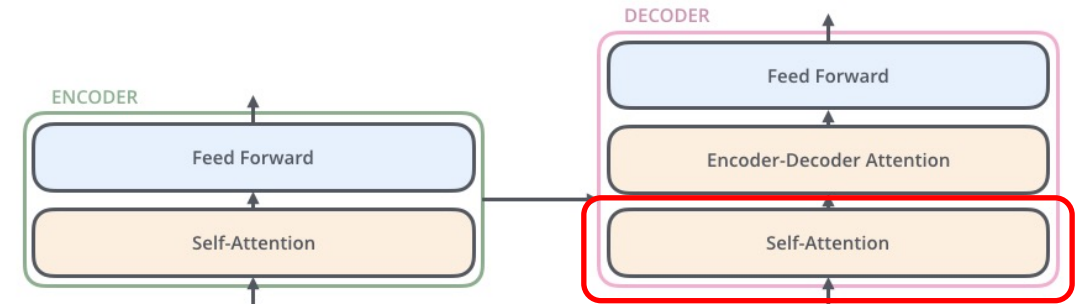
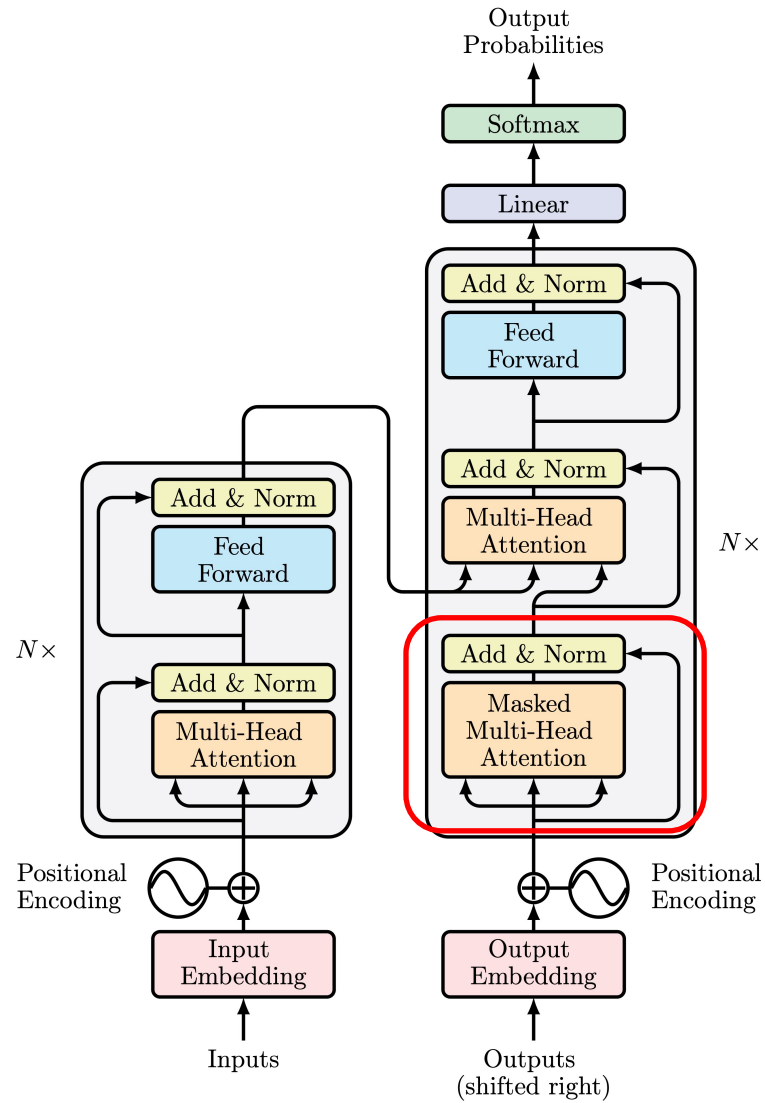
Transformers



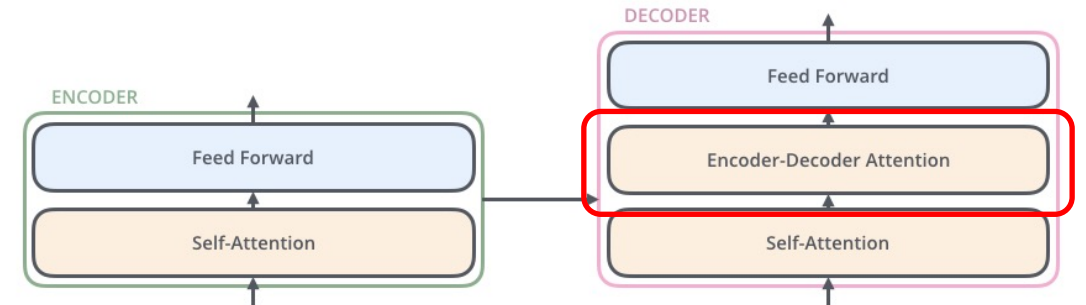
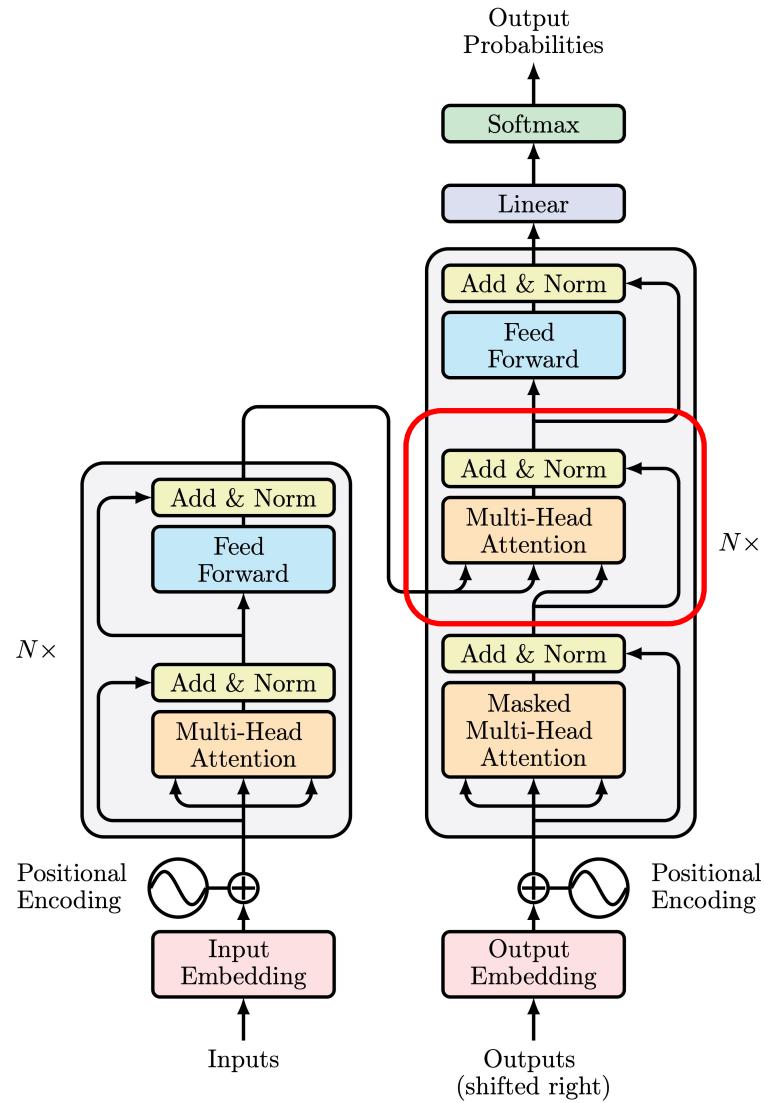
Transformers



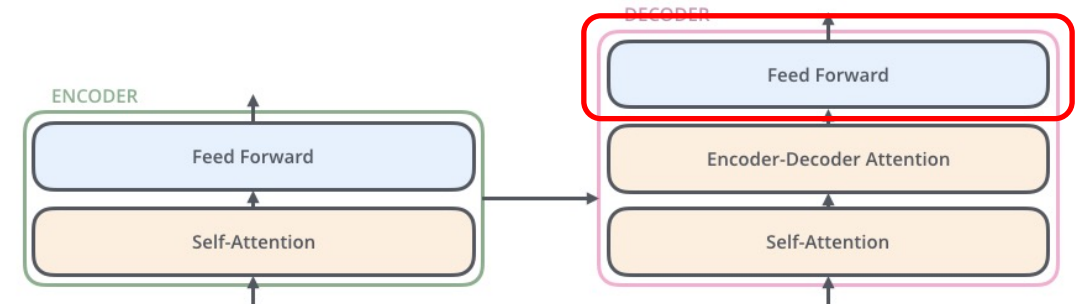
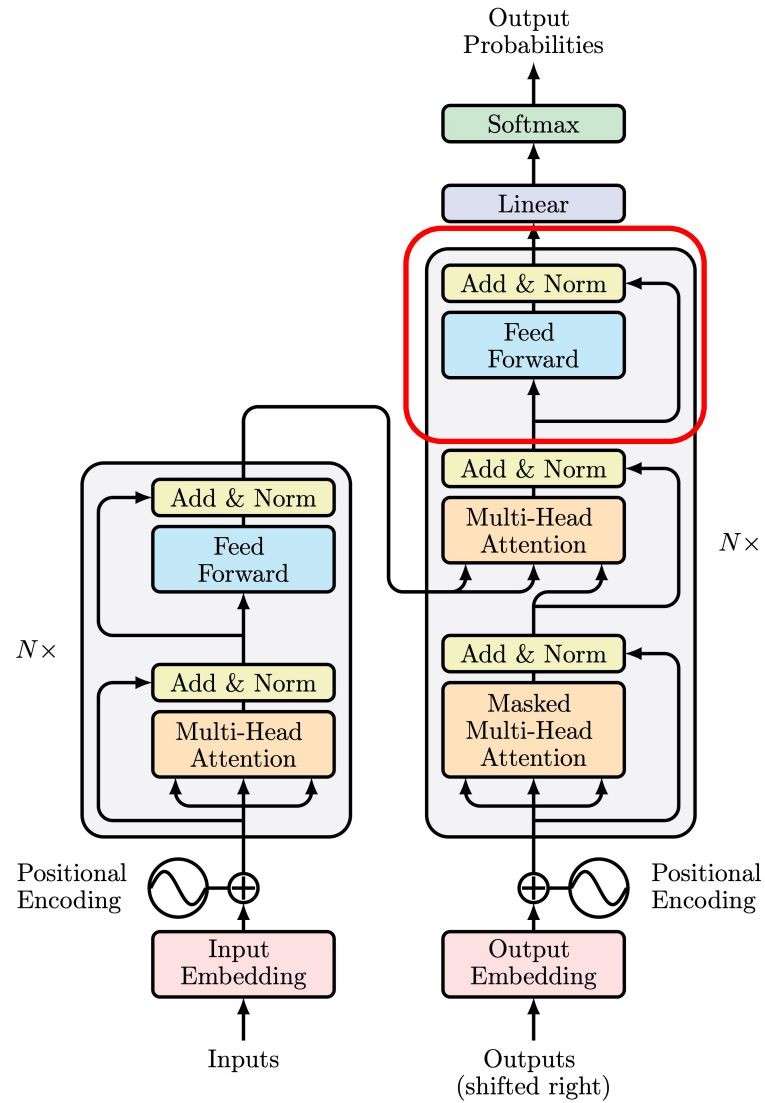
Transformers



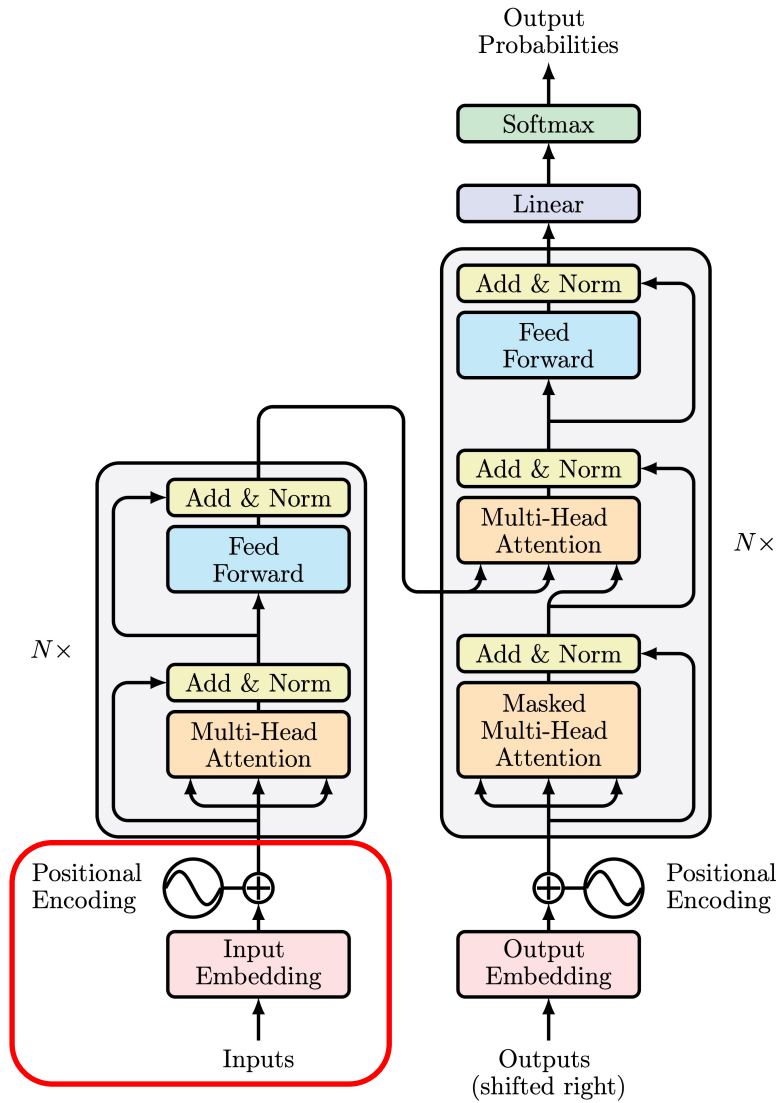
Transformers



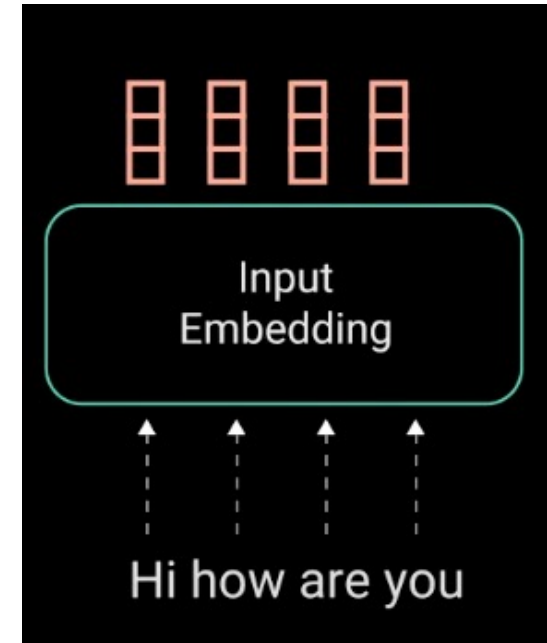
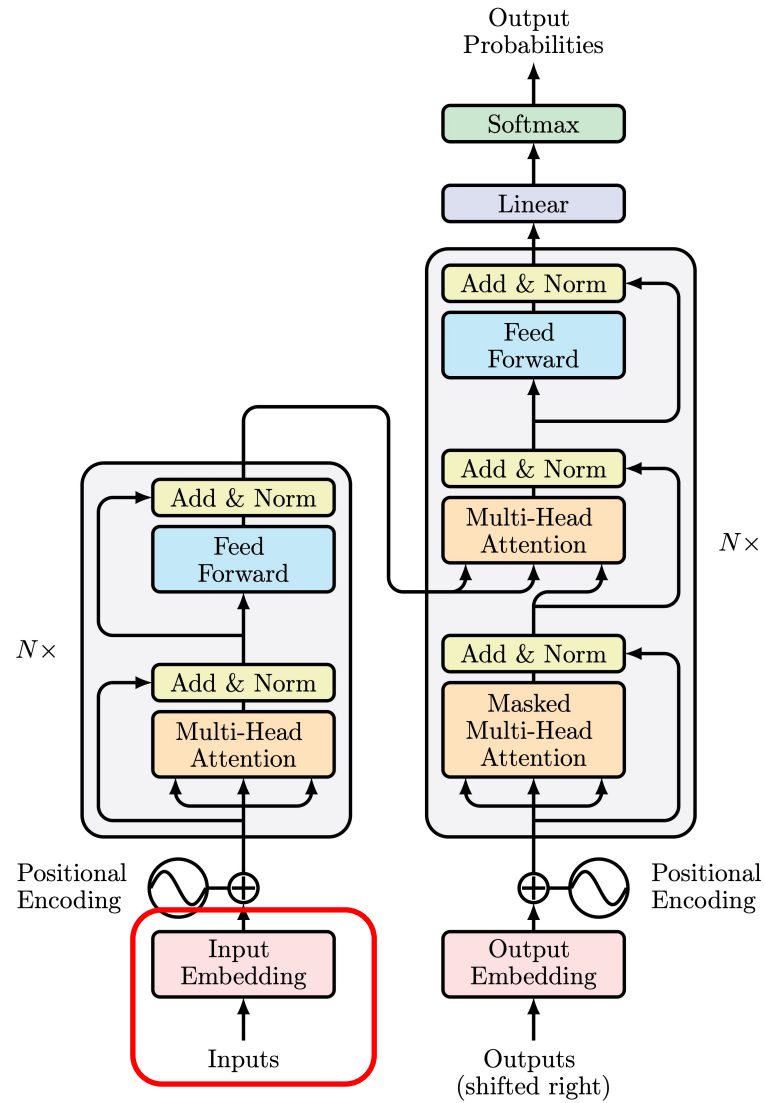
Transformers



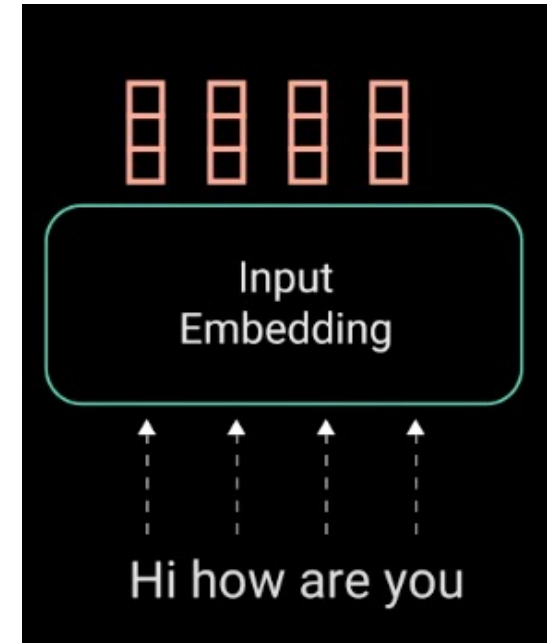
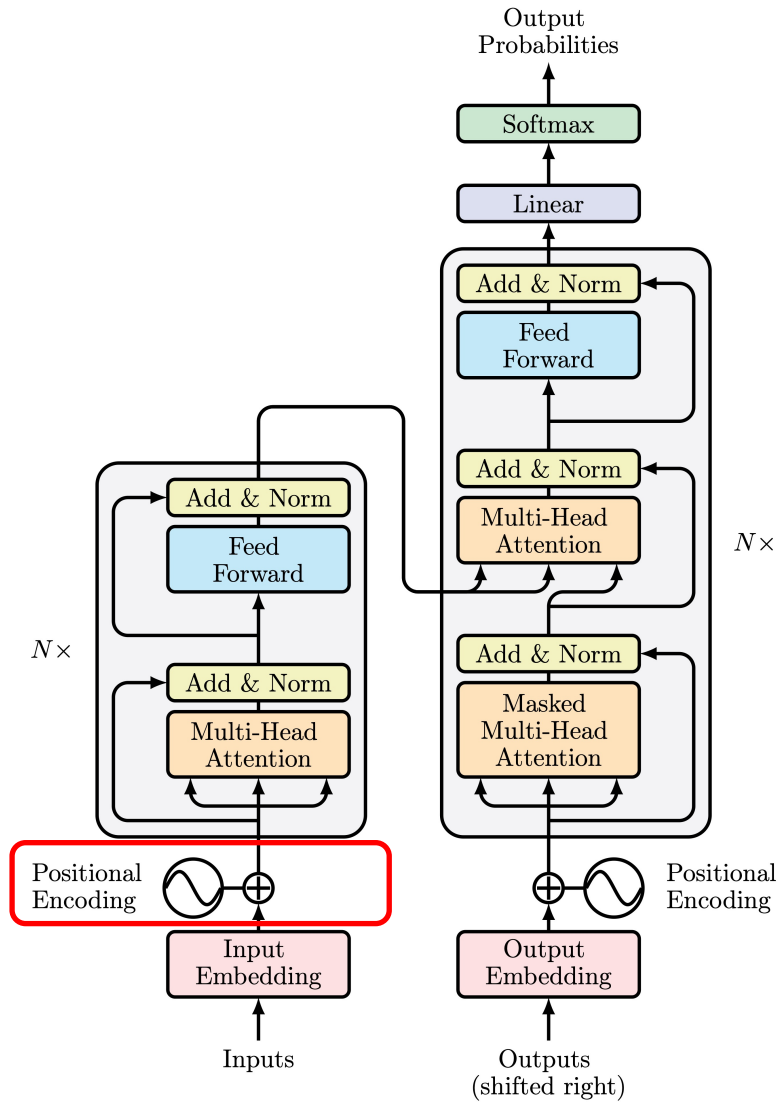
Input Encoding



Input Embedding



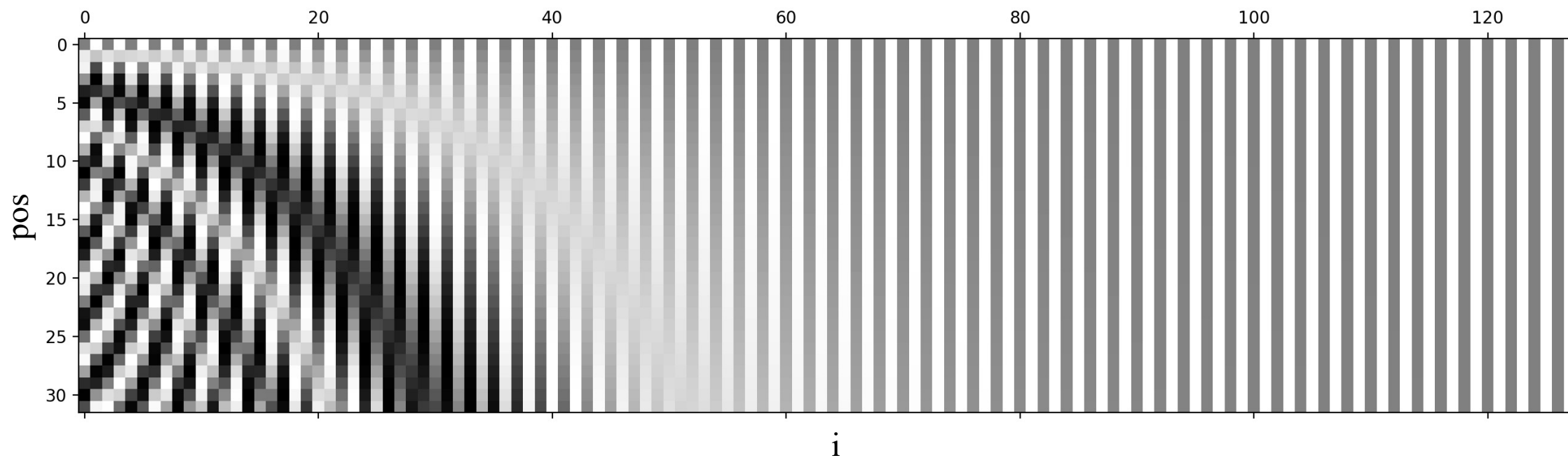
Positional Encoding



$$PE_{(pos,2i)} = \sin(pos/10000^{2i/d_{model}})$$

$$PE_{(pos,2i+1)} = \cos(pos/10000^{2i/d_{model}})$$

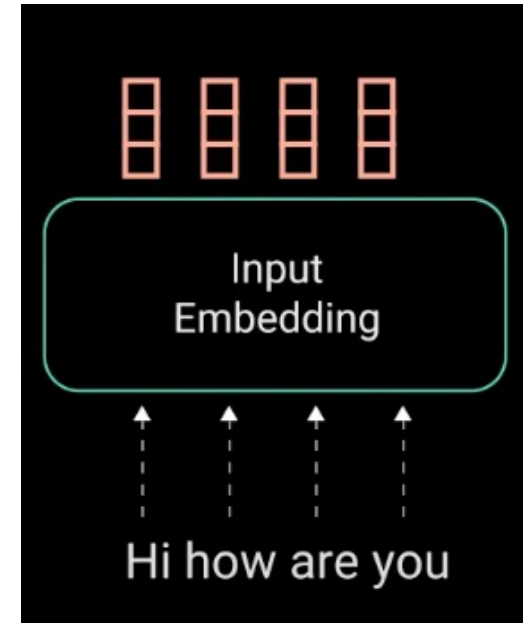
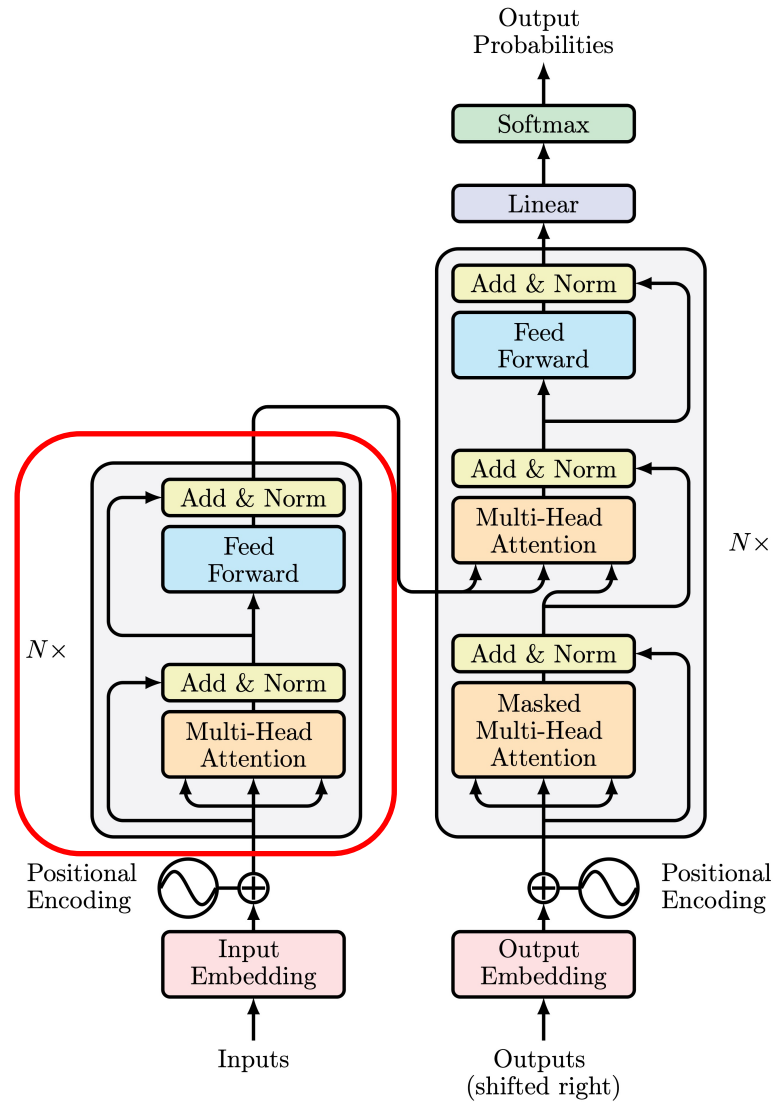
Positional Encoding



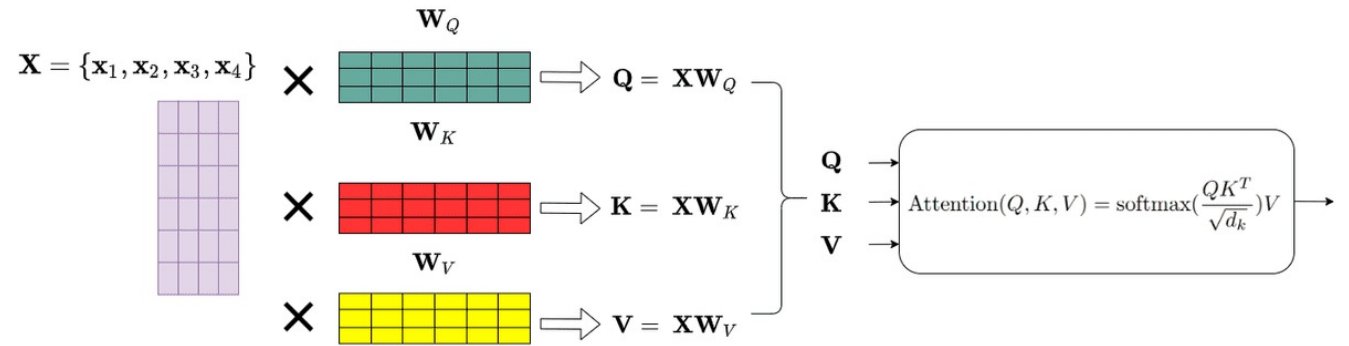
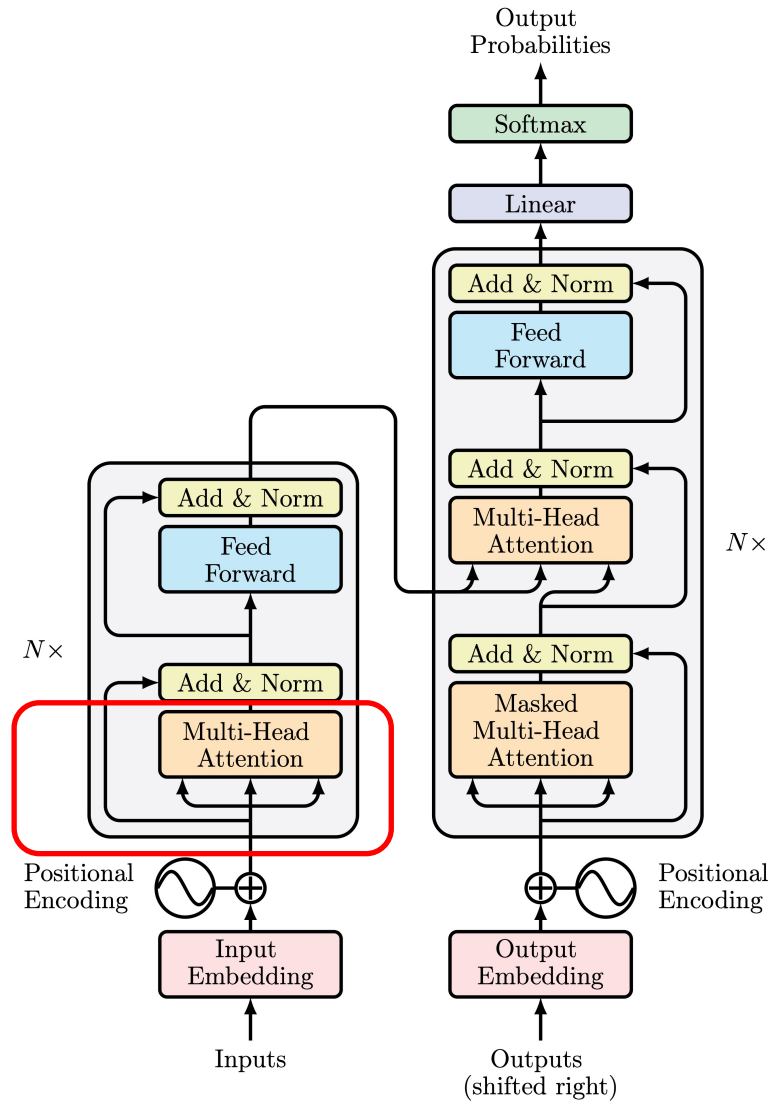
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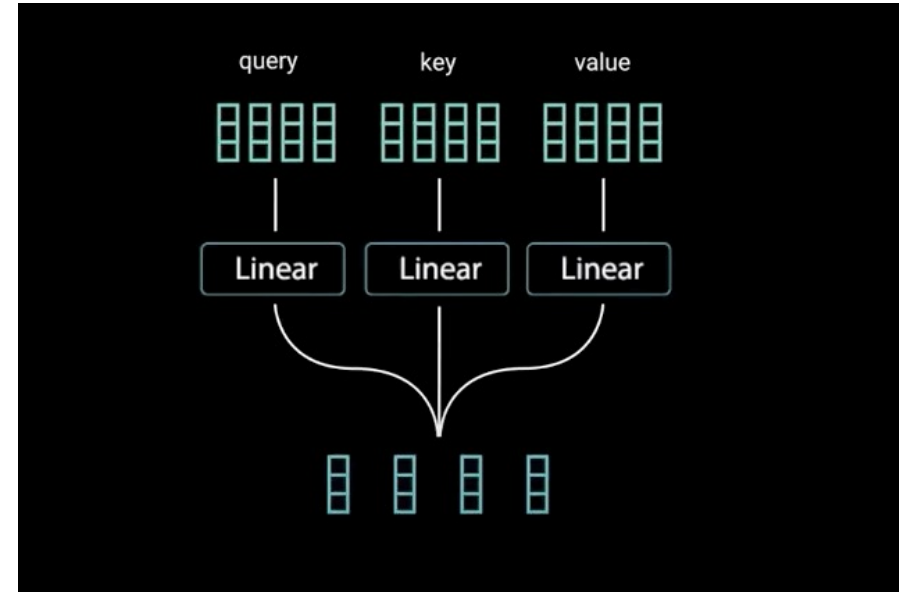
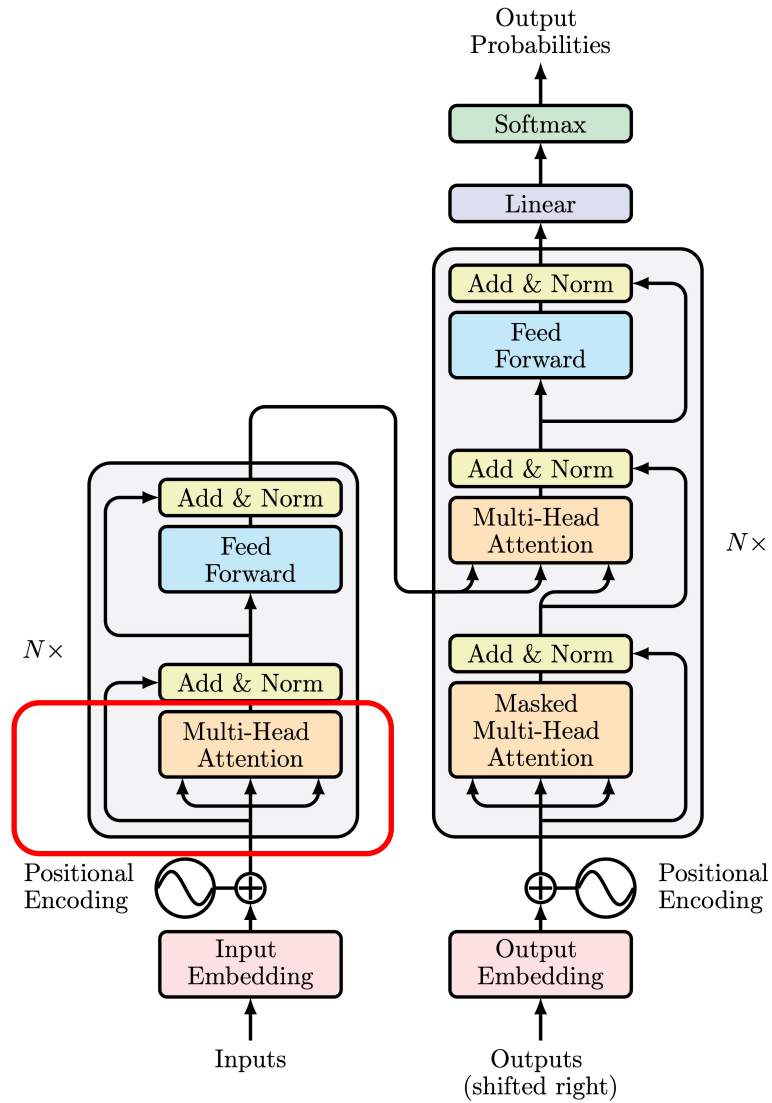
Encoder



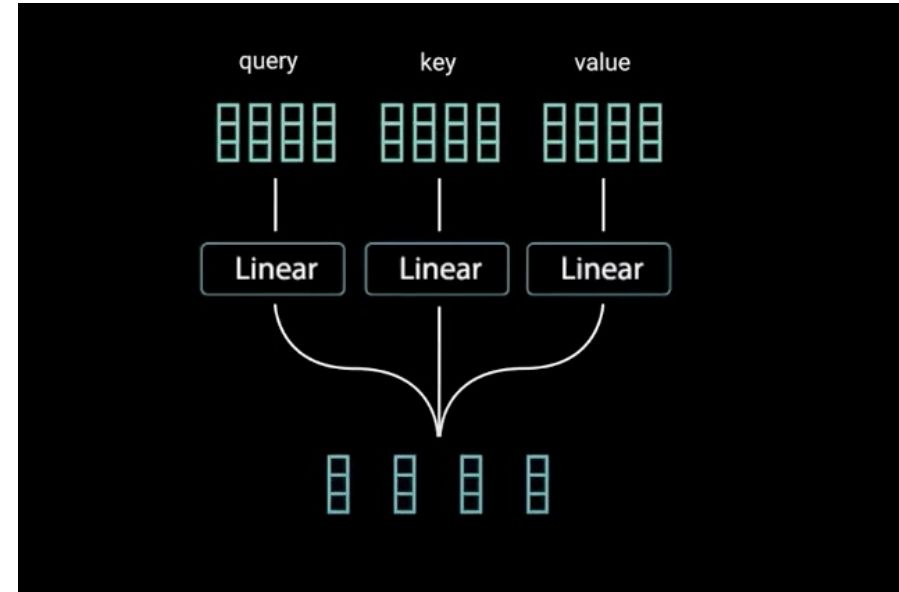
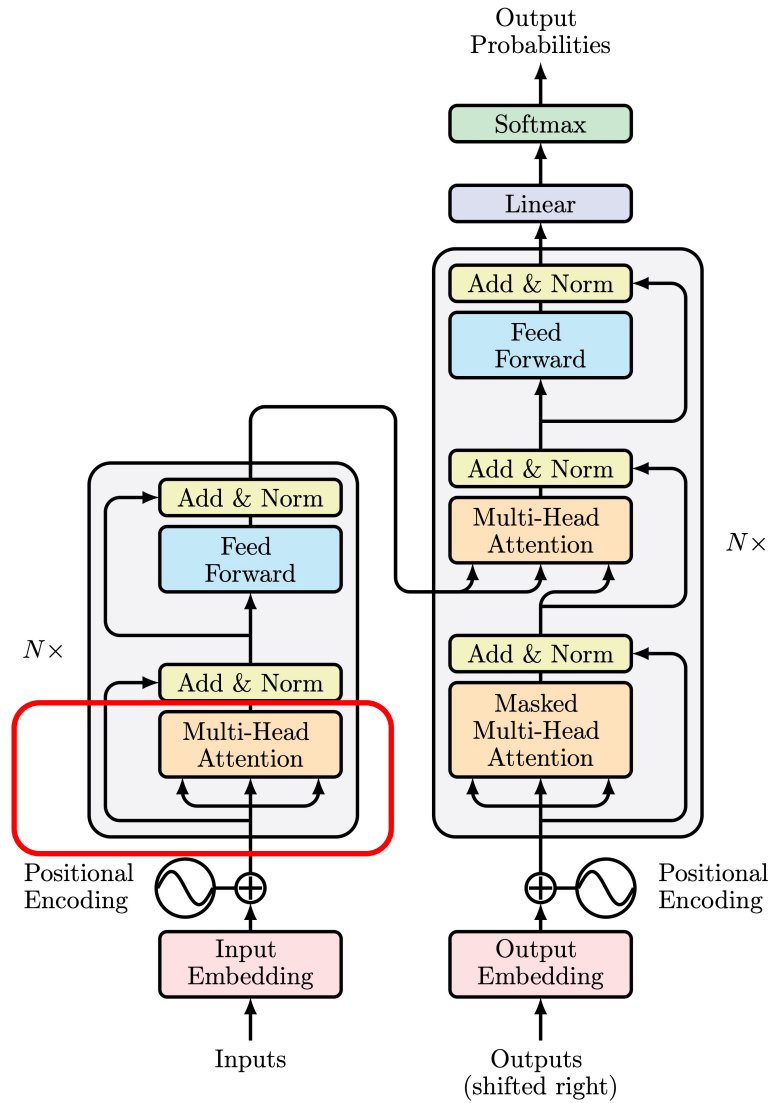
Multi-Head Attention



Multi-Head Attention

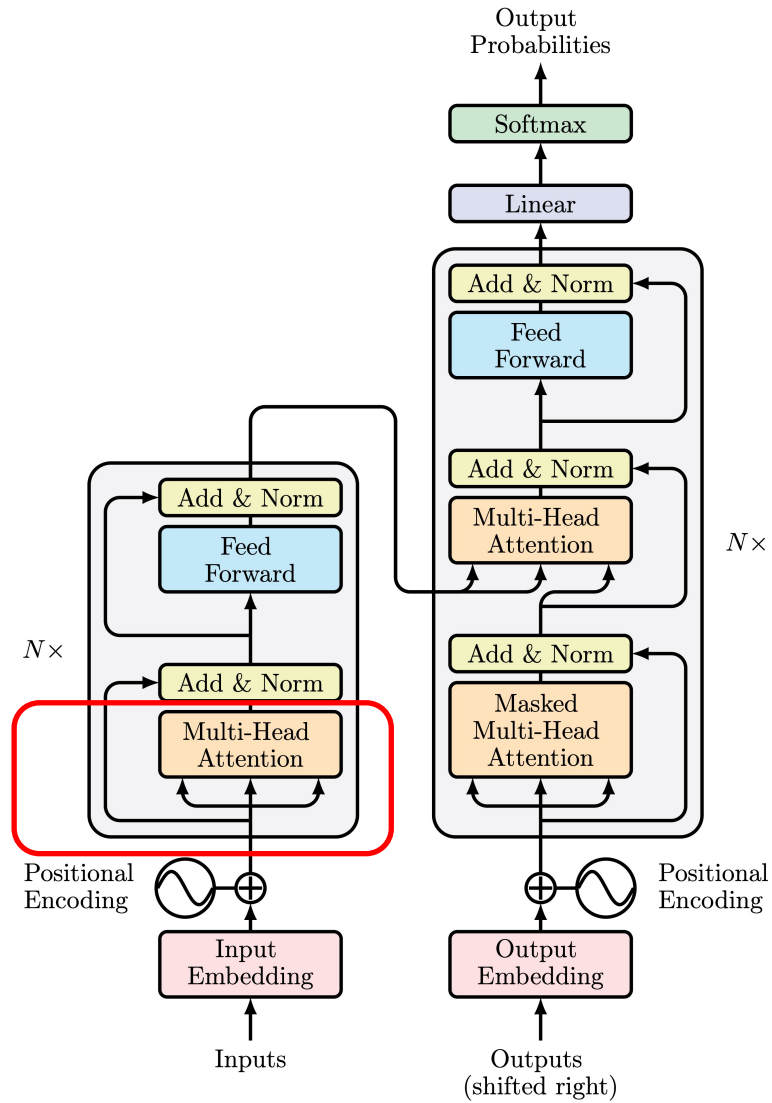


Multi-Head Attention

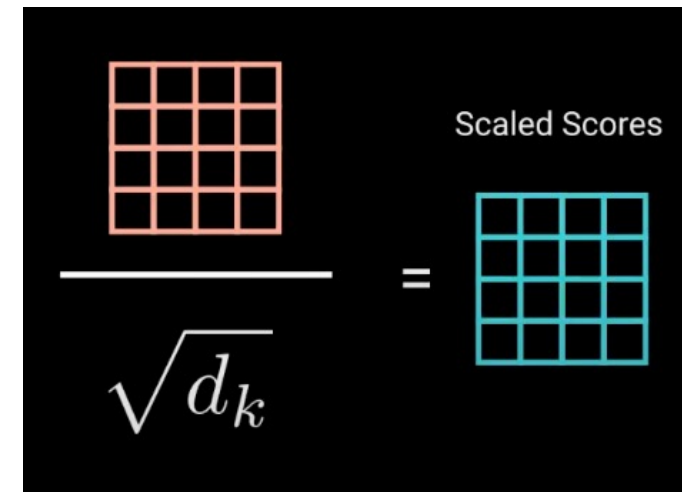


	Hi	how	are	you
Hi	98	27	10	12
how	27	89	31	67
are	10	31	91	54
you	12	67	54	92

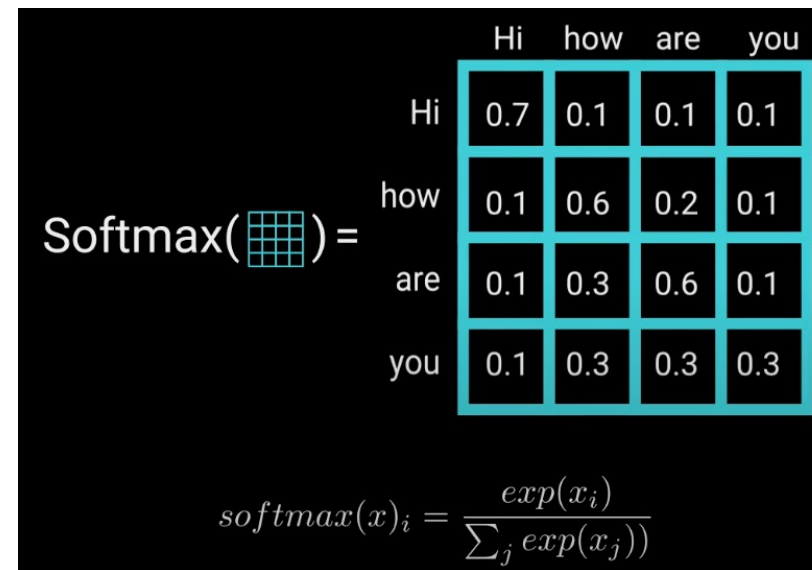
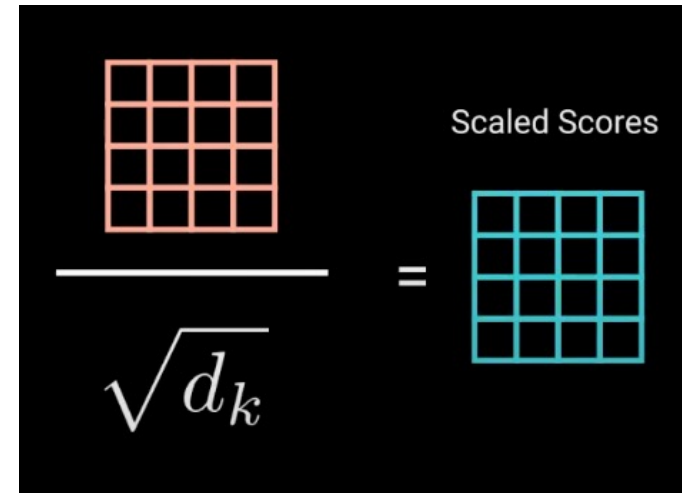
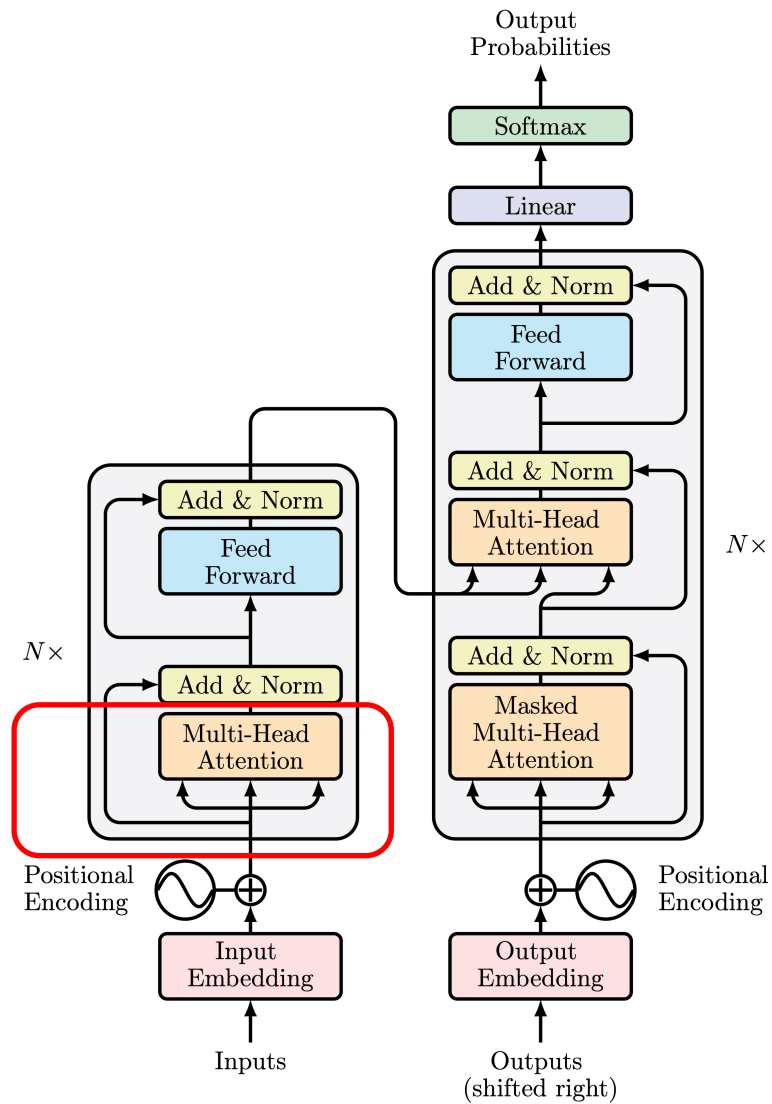
Multi-Head Attention



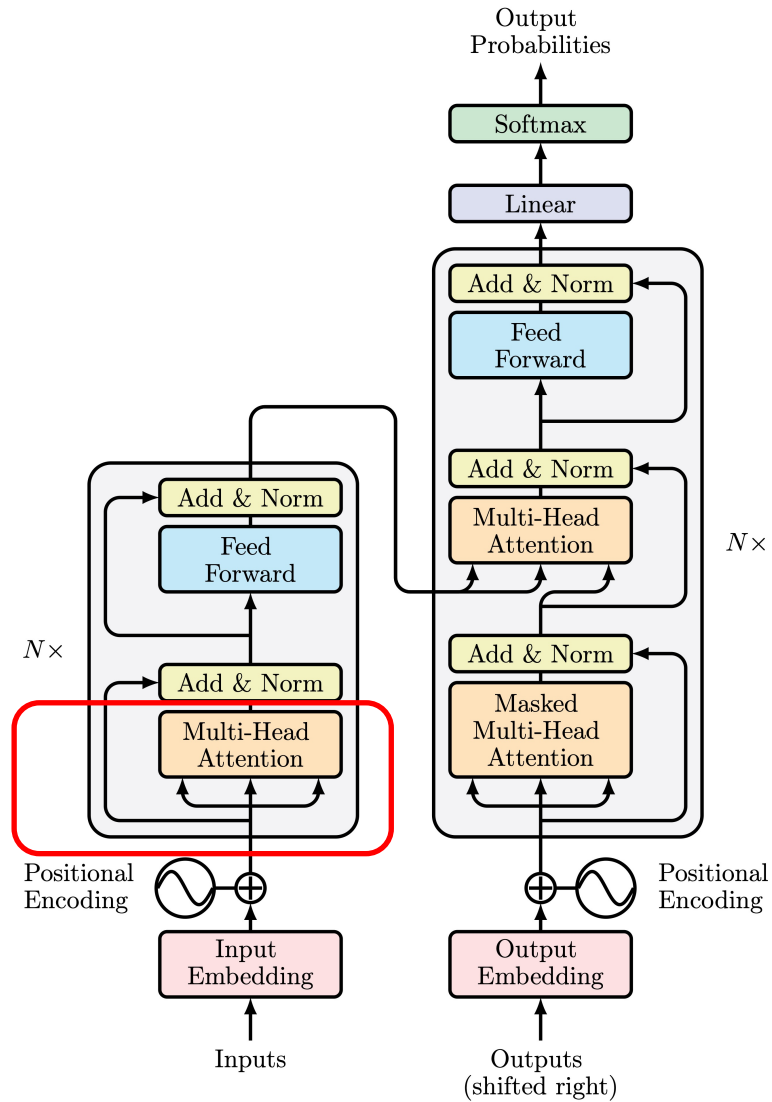
	Hi	how	are	you
Hi	98	27	10	12
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you	12	67	54	92



Multi-Head Attention



Multi-Head Attention



Softmax($\begin{bmatrix} \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{bmatrix}$) =

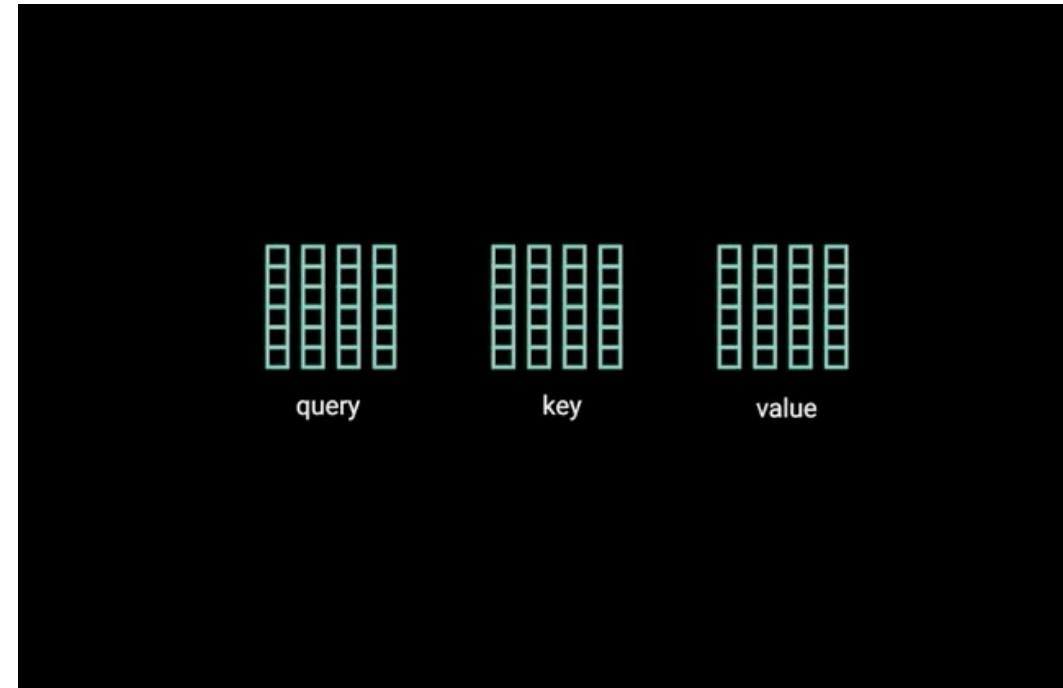
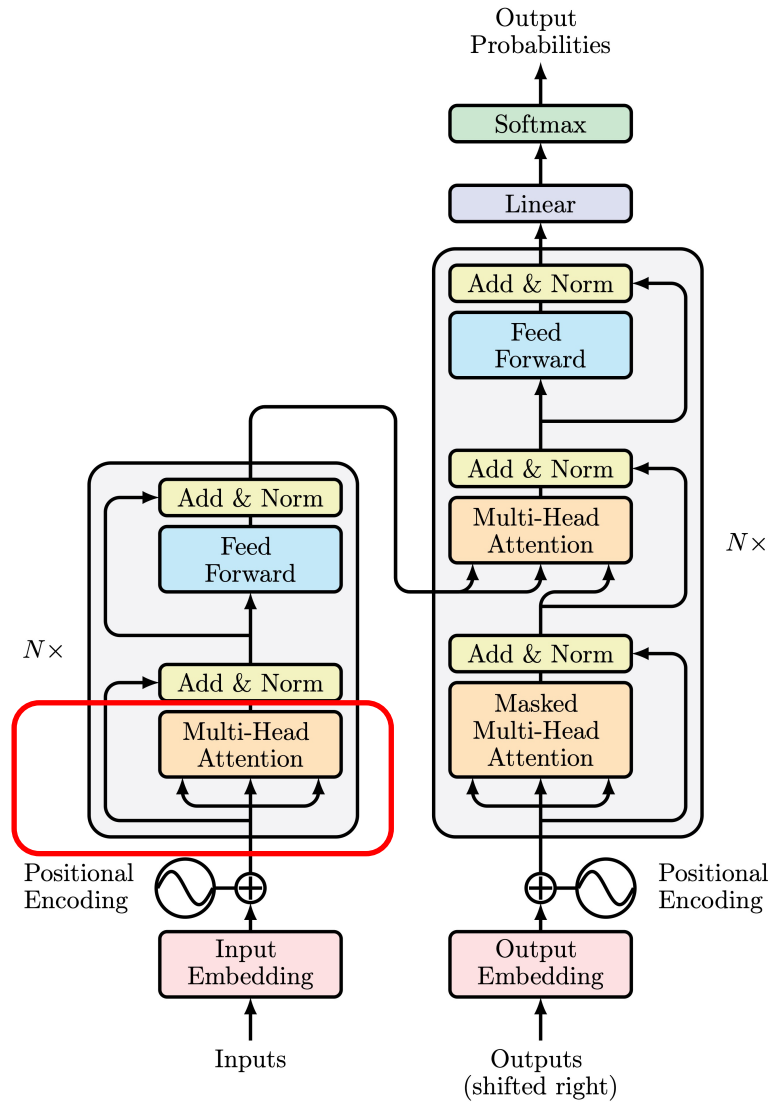
	Hi	how	are	you
Hi	0.7	0.1	0.1	0.1
how	0.1	0.6	0.2	0.1
are	0.1	0.3	0.6	0.1
you	0.1	0.3	0.3	0.3

$$\text{softmax}(x)_i = \frac{\exp(x_i)}{\sum_j \exp(x_j)}$$

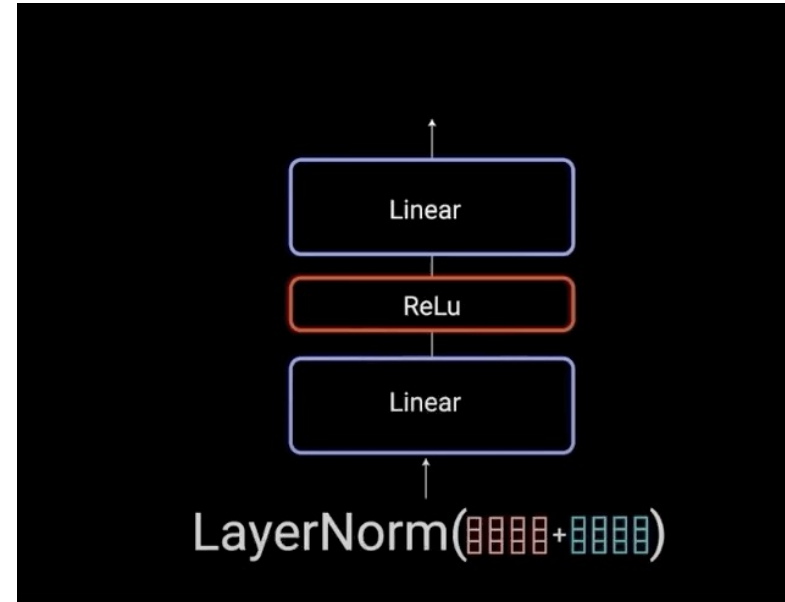
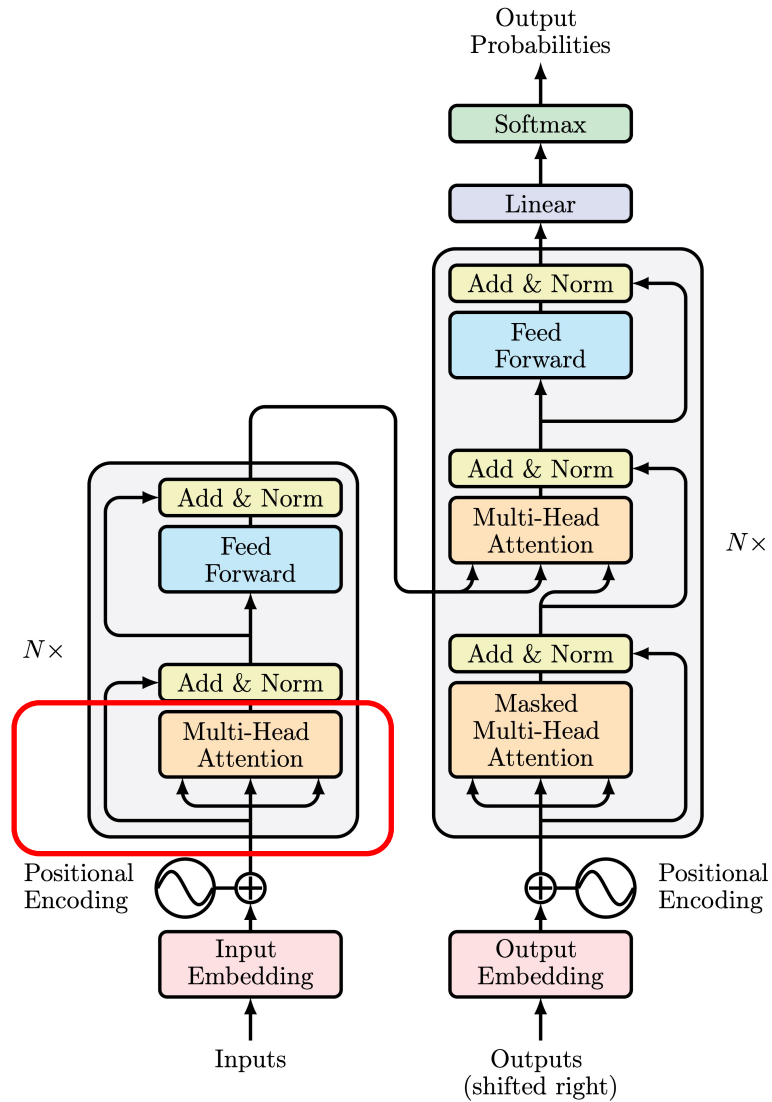
attention weights value output

The diagram shows a 4x4 grid of attention weights (cyan) multiplied by a 4x4 grid of value vectors (green) to produce a 4x4 grid of output vectors (orange).

Multi-Head Attention



Layer Norm & Residual Connection



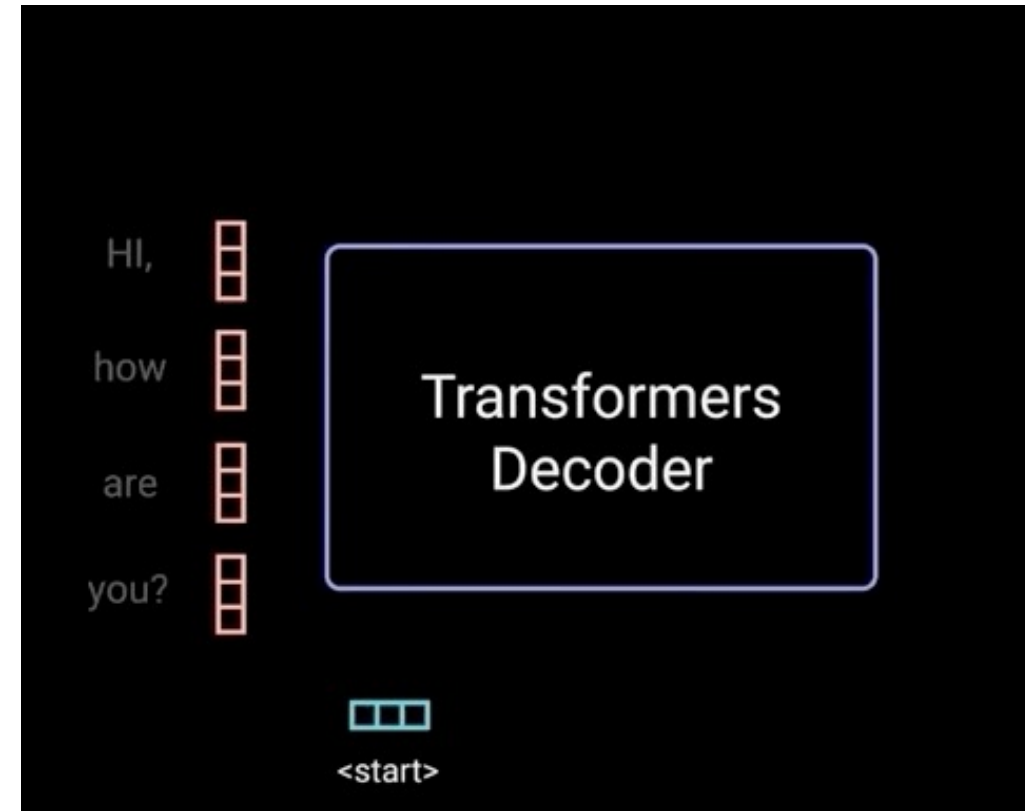
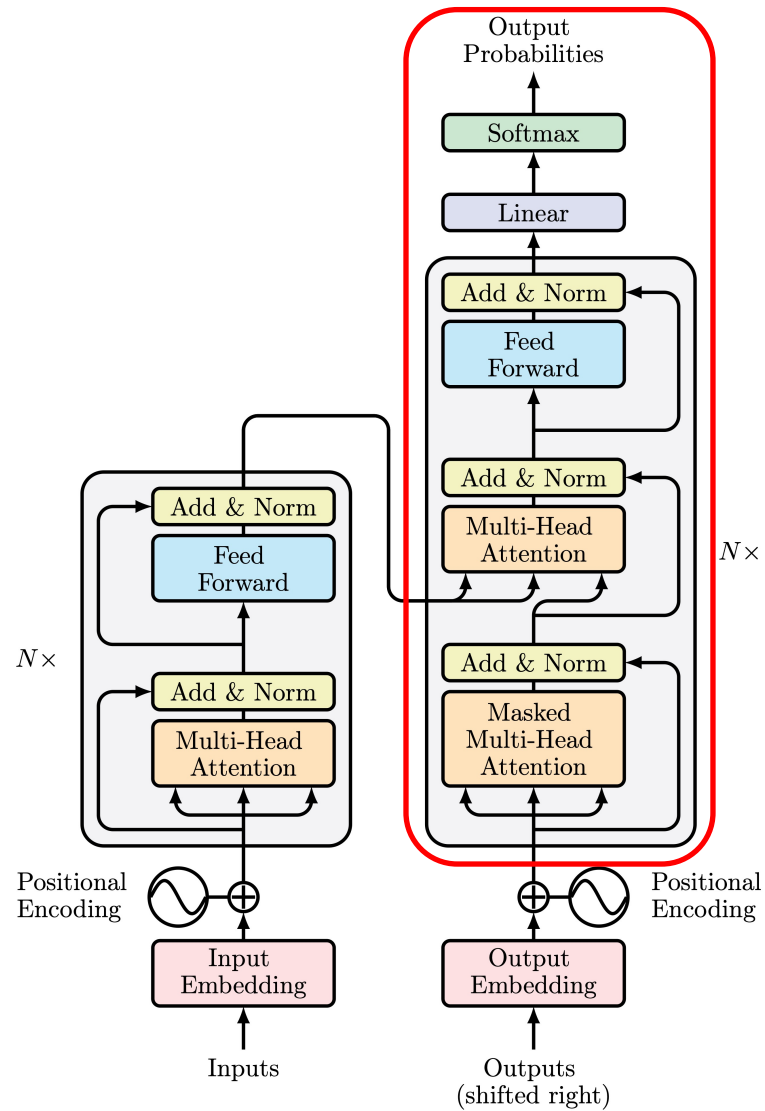
$$\mu_i = \frac{1}{K} \sum_{k=1}^K x_{i,k}$$

$$\sigma_i^2 = \frac{1}{K} \sum_{k=1}^K (x_{i,k} - \mu_i)^2$$

$$\hat{x}_{i,k} = \frac{x_{i,k} - \mu_i}{\sqrt{\sigma_i^2 + \epsilon}}$$

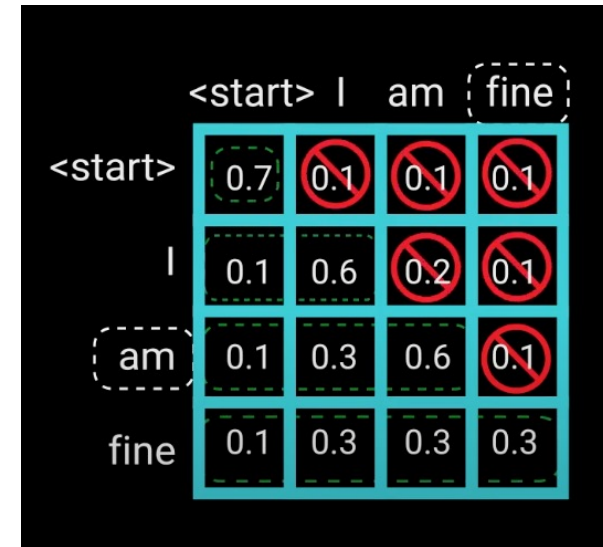
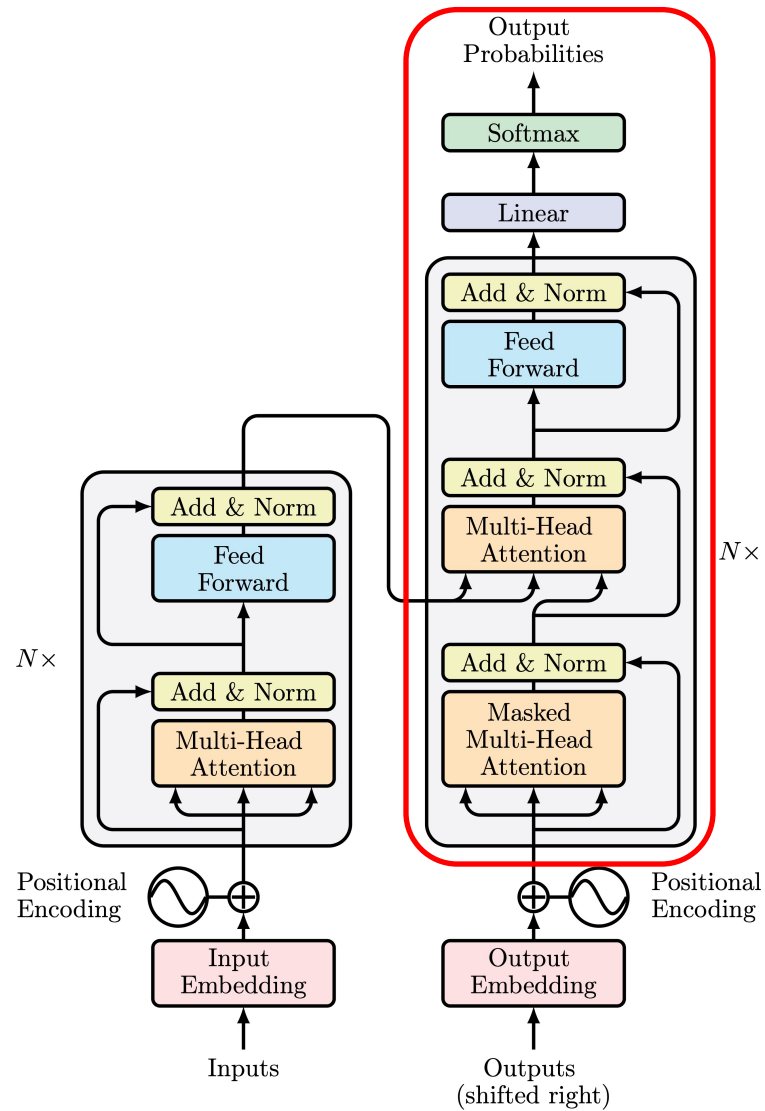
$$y_i = \gamma \hat{x}_i + \beta \equiv \text{LN}_{\gamma, \beta}(x_i)$$

Decoder



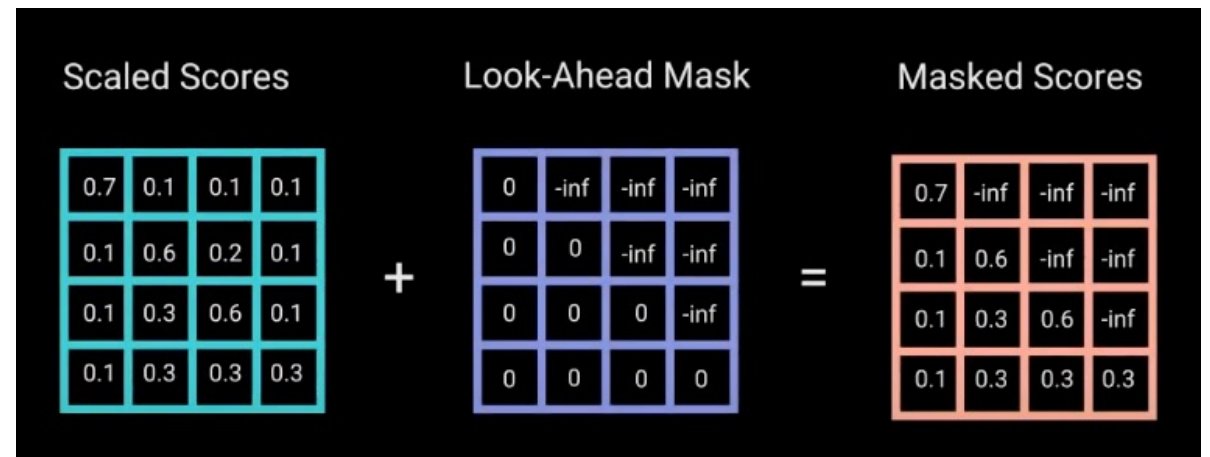
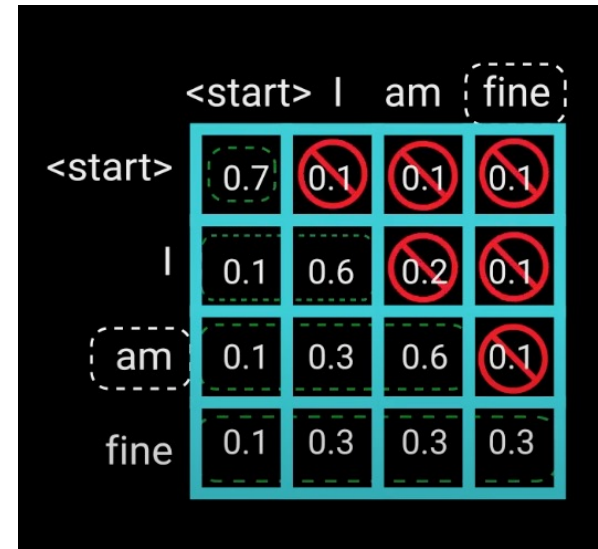
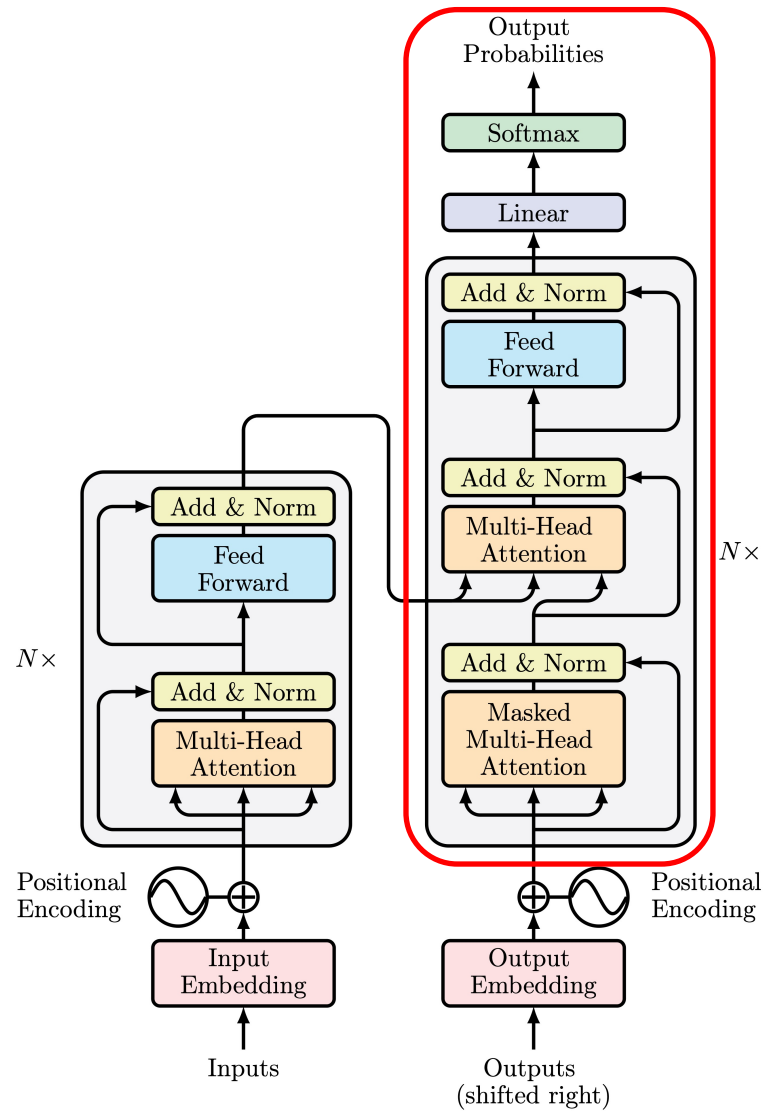
For certain applications like language models, decoder should be autoregressive!

Masked Multi-Head Attention

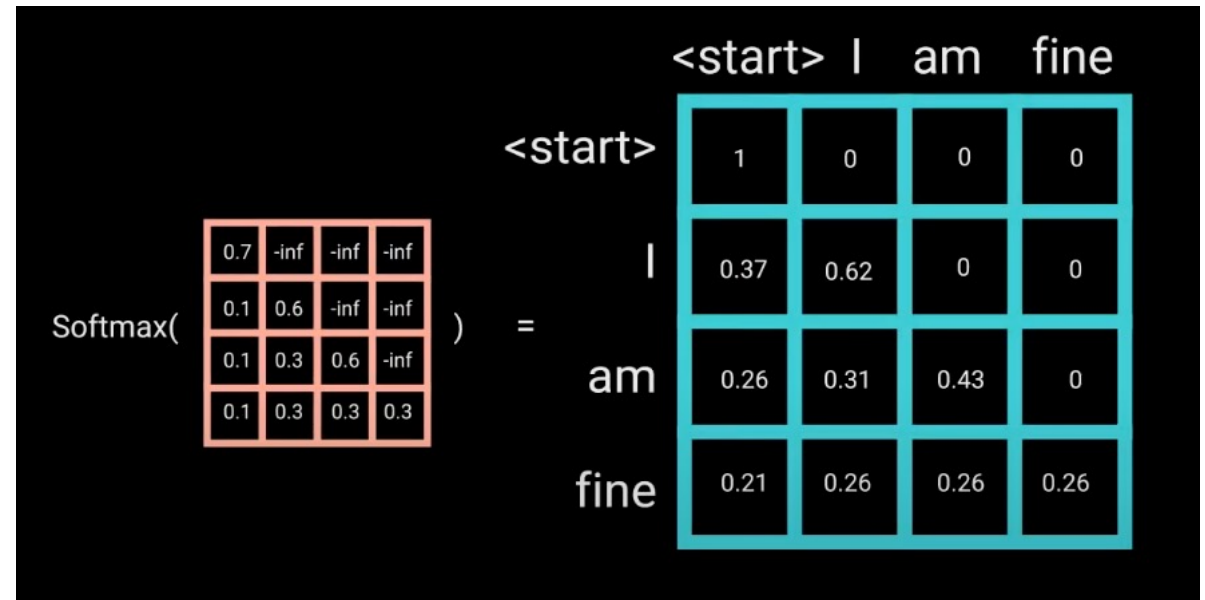
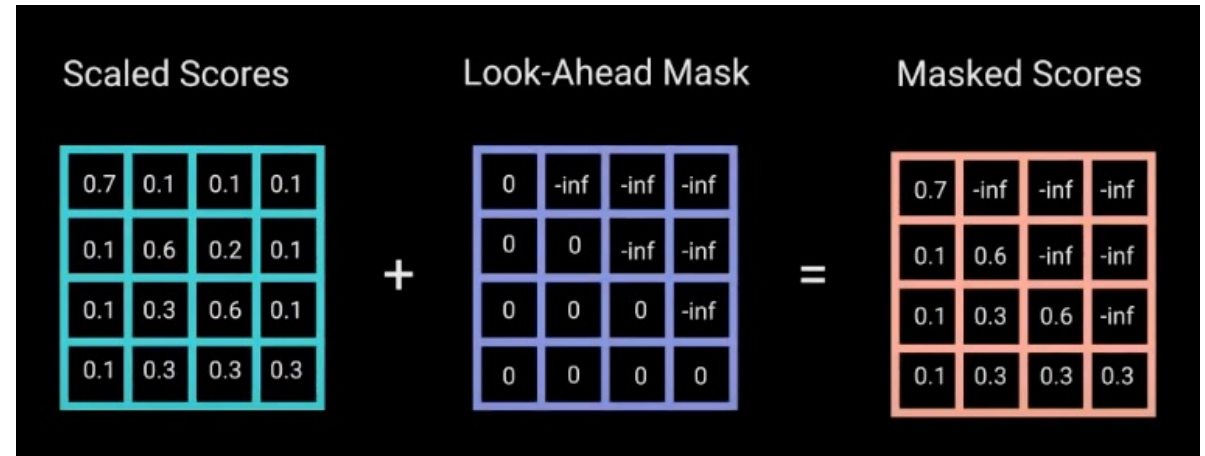
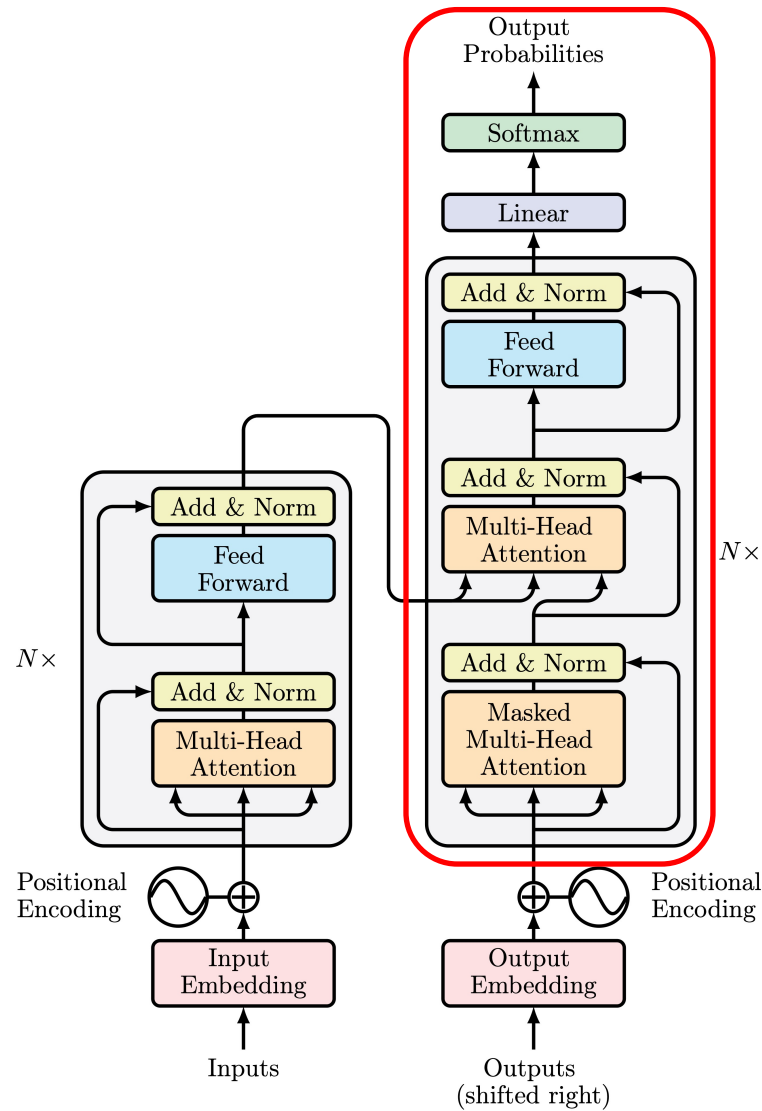


Prevent attending from future!

Masked Multi-Head Attention



Masked Multi-Head Attention



Hugging Face Demos

<https://transformer.huggingface.co/>



Write With Transformer

Get a modern neural network to
auto-complete your thoughts.

This web app, built by the Hugging Face team, is the official demo of the `🤗/transformers` repository's text generation capabilities.



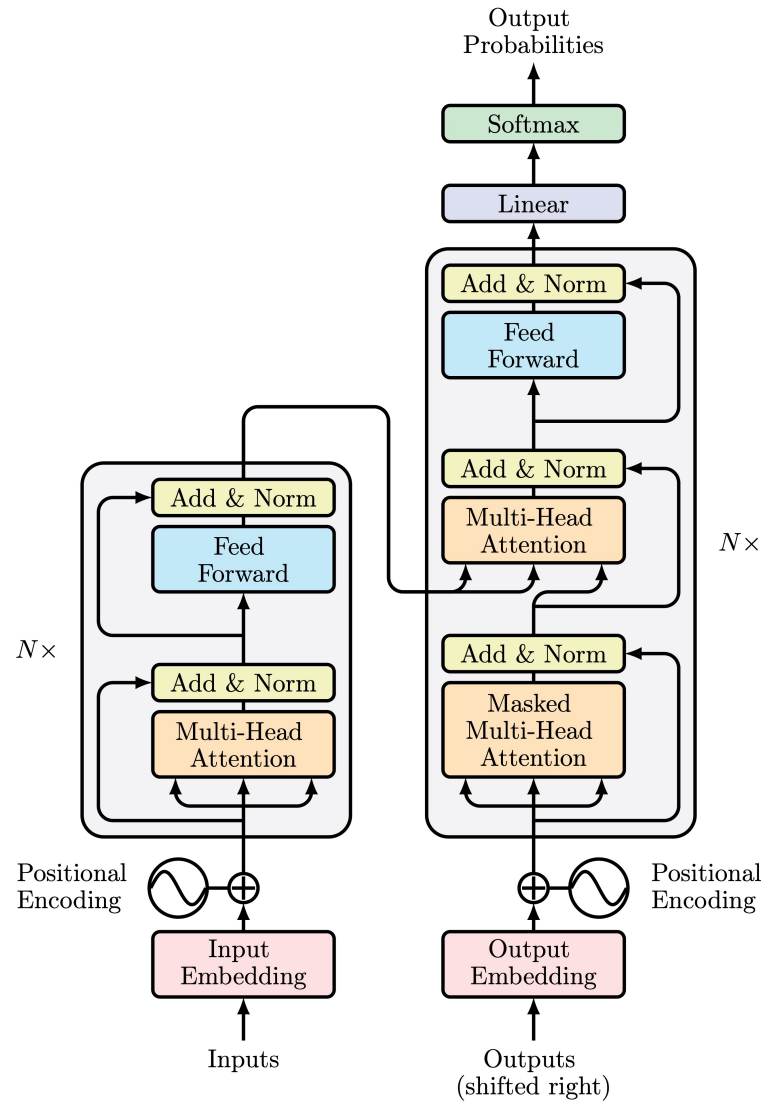
Star

57,016

Extensions: Vision Transformer



Limitations



- $O(L^2)$ time/memory cost for self-attention
- How can we incorporate prior knowledge into attention rather than having a fully connected attention?
 - Encourage sparse attention
 - Inject known graph structures
 -

References

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Questions?