EECE 571F: Advanced Topics in Deep Learning

Lecture 4: Graph Neural Networks II Graph Convolution Models

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Outline

- Laplacian, Fourier Transforms, and Convolution
- Graph Laplacian, Graph Fourier Transforms, and Graph Convolution
- Spectral Filtering and Chebyshev Polynomials
- Graph Convolutional Networks (GCNs)
- Relation between GCNs and Message Passing Neural Networks (MPNNs)
- Spectral Graph Neural Networks

Convolution on Graphs?

• Let us review Fourier Transform and Convolution Theorem

Given signal f(t) , the classical Fourier transform is:

$$\hat{f}(\xi) = \int_{\mathbb{R}} f(t) e^{-2\pi i \xi t} dt$$

i.e., expansion in terms of complex exponentials

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We have
$$\Delta(e^{-2\pi i\xi t}) = \frac{\partial^2}{\partial t^2} e^{-2\pi i\xi t} = -(2\pi\xi)^2 e^{-2\pi i\xi t}$$

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 $e^{-2\pi i\xi t}$ is the eigenfunction of Laplacian operator!

Given signal f(t) , the classical Fourier transform is:

Inverse Fourier transform

$$\hat{f}(\xi) = \int_{\mathbb{R}} f(t) e^{-2\pi i \xi t} dt \qquad f(t) = \int_{\mathbb{R}} \hat{f}(\xi) e^{2\pi i \xi t} d\xi$$

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How can we generalize them to graphs?

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- Let us review Fourier Transform and Convolution Theorem
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 - 2. Based on the convolution theorem, we can define convolution in Fourier domain

Convolution on Graphs?

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 - 2. Based on the convolution theorem, we can define convolution in Fourier domain
- How can we generalize convolution to graphs?
 - 1. What is the Laplacian operator on graph?
 - 2. How can we define convolution in (graph) Fourier domain?

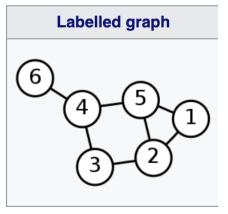
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Graph Signal

Graph G = (V, E), graph signal (node feature) X

G



A

Adjacency matrix										
(0	1	0	0	1	0)					
1	0	1	0	1	0					
0	1	0	1	0	0					
0	0	1	0	1	1					
1	1	0	1	0	0					
0/	0	0	1	0	0/					

Graph G = (V, E), graph signal (node feature) X

Degree matrix:
$$D_{ii} = \sum_{j=1}^{N} A_{ij}$$

G			Ι	\mathcal{D}							A	l						
Labelled graph		Degree matrix							Adjacency matrix									
	$\int 2$	0	0	0	0	0 \			0	1	0	0	1	0)				
(0)	0	3	0	0	0	0			1	0	1	0	1	0				
(4)-32	0	0	2	0	0	0			0	1	0	1	0	0				
I	0	0	0	3	0	0			0	0	1	0	1	1				
(3)-(2)	0	0	0	0	3	0			1	1	0	1	0	0				
	0 / 1	0	0	0	0	1/			0	0	0	1	0	0/				

Image Credit: <u>https://en.wikipedia.org/wiki/Laplacian_matrix</u>

Graph G = (V, E), graph signal (node feature) X

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(Combinatorial) Graph Laplacian: $L = D - A$

G	D								A	l			L = D - A							
Labelled graph		Degree matrix						ŀ	١dja	cen	cy n	natri	x	Laplacian matrix						
	$\int 2$	0	0	0	0	0)		$\left(\begin{array}{c} 0 \end{array} \right)$	1	0	0	1	0 \	$\begin{pmatrix} 2 \end{pmatrix}$	-1	0	0	-1	0)	
6	0	3	0	0	0	0		1	0	1	0	1	0	-1	3	-1	0	-1	0	
441	0	0	2	0	0	0		0	1	0	1	0	0	0	-1	2	-1	0	0	
L L	0	0	0	3	0	0		0	0	1	0	1	1	0	0	-1	3	-1	-1	
(3)-(2)	0	0	0	0	3	0		1	1	0	1	0	0	-1	-1	0	-1	3	0	
	\0	0	0	0	0	1/		\0	0	0	1	0	0/	\ 0	0	0	-1	0	1/	

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$$D_{ii} = \sum_{j=1}^{N} A_{ij}$$

(Combinatorial) Graph Laplacian: $L = D - A$

Compute difference between current node and its neighbors!

G	D								A	l			L = D - A							
Labelled graph		Degree matrix						dja	cen	cy n	natri	x	Laplacian matrix							
$ \begin{array}{c} 6 \\ 4 \\ -5 \\ 1 \\ 3 \\ -2 \end{array} $	0 0 0	0 0 3 0 0 2 0 0 0 0 0 0 0 0	0 0 3 0	0 0 0 3 0	$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$		$\begin{pmatrix} 0\\1\\0\\0\\1\\0 \end{pmatrix}$	1 0 1 0 1 0	0 1 0 1 0 0	0 0 1 0 1 1	$egin{array}{ccc} 1 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{array}$	$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$	$\left(egin{array}{cccccccccccccccccccccccccccccccccccc$							

For undirected graphs, (Combinatorial) Graph Laplacian:

- Symmetric ٠
- Diagonally dominant ٠
- Positive semi-definite (PSD) ٠
- The number of connected components in the graph is the algebraic multiplicity of the eigenvalue 0. ٠

G		D								A	l			L = D - A							
Labelled graph		Degree matrix						4	dja	cen	cy n	natri	ix	Laplacian matrix							
	$\int 2$	0	0	0	0	0)		$\int 0$	1	0	0	1	0 \	(2 —	1	0	0	-1	0	
6	0	3	0	0	0	0		1	0	1	0	1	0	-	-	3	-1	0	-1	0	
(4)	0	0	2	0	0	0		0	1	0	1	0	0) —	1	2	-1	0	0	
	0	0	0	3	0	0		0	0	1	0	1	1)	0	-1	3	-1	-1	
370		0	0	0	3	$\begin{bmatrix} 0\\ 1 \end{bmatrix}$			1	0	1	0	0		. —	1	0	-1	3		
	\ 0	0	0	0	0	1/		0/	0	0	1	0	0/)	0	0	-1	0	1/	

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Symmetrically Normalized Graph Laplacian:

$$L = D^{-\frac{1}{2}} (D - A) D^{-\frac{1}{2}} = I - D^{-\frac{1}{2}} A D^{-\frac{1}{2}}$$

Eigenvalues lie in [0, 2], why? (Try to show it by yourself!)

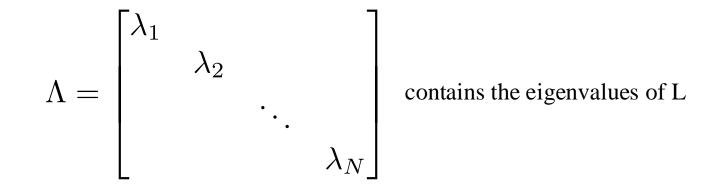
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$ \begin{array}{c} 6 \\ 4 - 5 \\ 3 - 2 \end{array} $	$\left(\begin{array}{ccccccccccc} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{array}\right)$	$\begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{pmatrix}$							

Spectral Theorem

If L is a symmetric matrix, we have

$$L = U\Lambda U^{\top} = \sum_{i=1}^{N} \lambda_i \mathbf{u}_i \mathbf{u}_i^{\top}$$

where $U = [\mathbf{u}_1, \mathbf{u}_2, \cdots, \mathbf{u}_N]$ contains eigenvectors of L and is orthogonal $UU^{\top} = U^{\top}U = I$



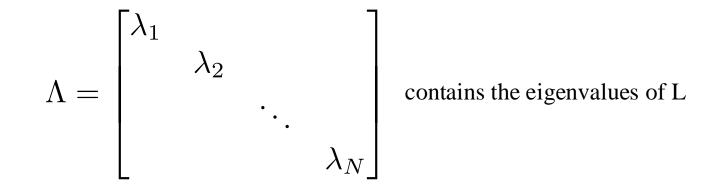
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Spectral Decomposition

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Given graph signal $X \in \mathbb{R}^{N \times 1}$, the *Graph Fourier Transform* is:

$$\hat{X}[i] = \sum_{j=1}^{N} U[j, i] X[j]$$
$$\hat{X} = U^{\top} X$$

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Graph Convolution (Spectral Filtering)

Convolution:

$$(f*h)(t) = \int_{\mathbb{R}} f(\tau)h(t-\tau)d\tau = \int_{\mathbb{R}} \hat{f}(\xi)\hat{h}(\xi)e^{2\pi i\xi t}d\xi$$

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Graph Convolution in Fourier domain (Spectral Filtering):

$$h_{\theta} * X = U h_{\theta}(\Lambda) U^{\top} X$$

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Graph Convolution in Fourier domain (Spectral Filtering):

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Can we find some efficient construction of h?

- Chebyshev polynomials [7]
- Graph wavelets [7]

Chebyshev Polynomials

Chebyshev polynomials of the first kind:

$$T_0(x) = 1$$

$$T_1(x) = x$$

$$T_{n+1}(x) = 2xT_n(x) - T_{n-1}(x)$$

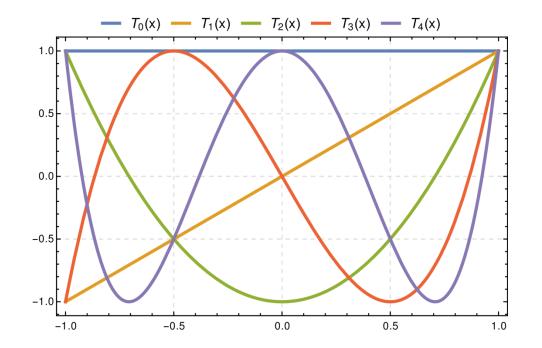
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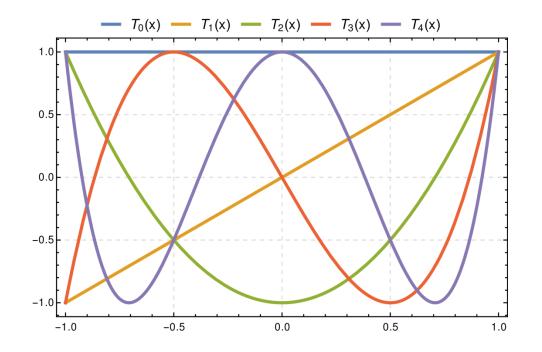


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They provide orthonormal basis in some Sobolev space on [-1, 1]:

$$h(x) = \sum_{n=0}^{\infty} a_n T_n(x)$$

Image Credit: https://en.wikipedia.org/wiki/Chebyshev_polynomials

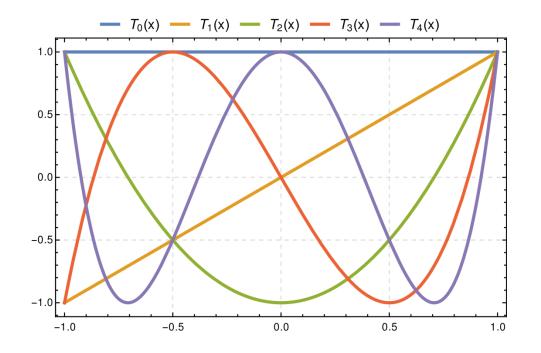
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$$h(x) = \sum_{n=0}^{\infty} a_n T_n(x) \qquad \qquad \int_{-1}^{1} T_n(x) T_m(x) \frac{dx}{\sqrt{1-x^2}} = \begin{cases} 0 & \text{if } n \neq m \\ \pi & \text{if } n = m = 0 \\ \frac{\pi}{2} & \text{if } n = m \neq 0 \end{cases}$$

Image Credit: https://en.wikipedia.org/wiki/Chebyshev_polynomials

Chebyshev expansion:

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Spectral filtering:

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Truncated Chebyshev polynomials approximation:

$$h_{\theta}(\Lambda) \approx \sum_{n=0}^{K} \theta_n T_n(\tilde{\Lambda}) = \sum_{n=0}^{K} \theta_n T_n(\frac{2\Lambda}{\lambda_{\max}} - I)$$

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Graph Convolution:

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Truncated Chebyshev polynomials based Graph Convolution:

$$h_{\theta} * X = U h_{\theta}(\Lambda) U^{\top} X$$
$$\approx U \left(\sum_{n=0}^{K} \theta_n T_n \left(\frac{2\Lambda}{\lambda_{\max}} - I \right) \right) U^{\top} X$$

Recall we do not want explicit spectral decomposition since it is expensive!

$$h_{\theta} * X \approx U\left(\sum_{n=0}^{K} \theta_n T_n \left(\frac{2\Lambda}{\lambda_{\max}} - I\right)\right) U^{\top} X$$

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Are Chebyshev polynomials efficient?

Recall

 $T_0(x) = 1$ $T_1(x) = x$ $T_{n+1}(x) = 2xT_n(x) - T_{n-1}(x)$

Recall

$$T_0(x) = 1$$

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Let

$$T_n(\tilde{L}) = UT_n\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)U^{\top}$$

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We have

$$\begin{split} T_{0}(\tilde{L}) &= I\\ T_{1}(\tilde{L}) &= U\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)U^{\top} = 2L/\lambda_{\max} - I\\ T_{n+1}(\tilde{L}) &= U\left(2\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)T_{n}\left(\frac{2\Lambda}{\lambda_{\max}} - I\right) - T_{n-1}\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)\right)U^{\top}\\ &= 2U\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)U^{\top}UT_{n}\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)U^{\top} - UT_{n-1}\left(\frac{2\Lambda}{\lambda_{\max}} - I\right)U^{\top}\\ &= 2\left(\frac{2L}{\lambda_{\max}} - I\right)T_{n}(\tilde{L}) - T_{n-1}(\tilde{L}) \end{split}$$

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$$h_{\theta} * X \approx U\left(\sum_{n=0}^{K} \theta_n T_n(\frac{2\Lambda}{\lambda_{\max}} - I)\right) U^{\top} X$$
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Let

 $T_0(\tilde{X}) = T_0(\tilde{L})X$

We have

$$T_0(\tilde{X}) = X$$

$$T_1(\tilde{X}) = 2LX/\lambda_{\max} - X$$

$$T_{n+1}(\tilde{X}) = 2\left(\frac{2L}{\lambda_{\max}} - I\right)T_n(\tilde{X}) - T_{n-1}(\tilde{X})$$

Truncated Chebyshev polynomials based Graph Convolution:

$$h_{\theta} * X \approx \sum_{n=0}^{K} \theta_n T_n(\tilde{X})$$

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What if we truncate to 1st order?

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What if we truncate to 1st order?

That is Graph Convolutional Networks (GCNs) [8] !

Outline

- Laplacian, Fourier Transforms, and Convolution
- Graph Laplacian, Graph Fourier Transforms, and Graph Convolution
- Spectral Filtering and Chebyshev Polynomials
- Graph Convolutional Networks (GCNs)
- Relation between GCNs and Message Passing Neural Networks (MPNNs)
- Spectral Graph Neural Networks

Truncated Chebyshev polynomials based Graph Convolution:

$$h_{\theta} * X \approx \sum_{n=0}^{K} \theta_n T_n(\tilde{X})$$
$$T_0(\tilde{X}) = X$$
$$T_1(\tilde{X}) = 2LX/\lambda_{\max} - X$$
$$T_{n+1}(\tilde{X}) = 2\left(\frac{2L}{\lambda_{\max}} - I\right)T_n(\tilde{X}) - T_{n-1}(\tilde{X})$$

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$$h_{\theta} * X \approx \sum_{n=0}^{K} \theta_n T_n(\tilde{X}) \qquad \qquad h_{\theta} * X \approx \theta_0 X + \theta_1 T_1(\tilde{X})$$

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$$\frac{T_{n+1}(\tilde{X}) - 2\left(\frac{2L}{\lambda_{\max}} I\right) T_n(\tilde{X}) - T_{n-1}(\tilde{X})}{T_{n-1}(\tilde{X})}$$

We can use the normalize graph Laplacian so that its eigenvalues are in [0, 2]

$$L = I - D^{-\frac{1}{2}}AD^{-\frac{1}{2}}$$

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Assuming $\lambda_{\max} \approx 2$ $h_{\theta} * X \approx \theta_0 X + \theta_1 T_1(\tilde{X})$ $\approx \theta_0 X - \theta_1 D^{-\frac{1}{2}} A D^{-\frac{1}{2}} X$

Simplified Truncated Chebyshev polynomials based Graph Convolution:

$$h_{\theta} * X \approx \theta_0 X + \theta_1 T_1(\tilde{X})$$
$$\approx \theta_0 X - \theta_1 D^{-\frac{1}{2}} A D^{-\frac{1}{2}} X$$
$$= \theta \left(I + D^{-\frac{1}{2}} A D^{-\frac{1}{2}} \right) X$$

Simplified Truncated Chebyshev polynomials based Graph Convolution:

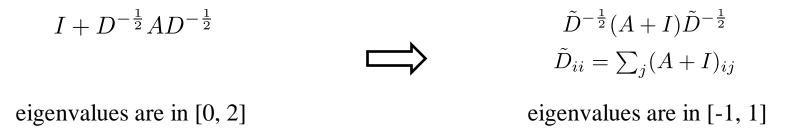
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 $I + D^{-\frac{1}{2}}AD^{-\frac{1}{2}}$

eigenvalues are in [0, 2]

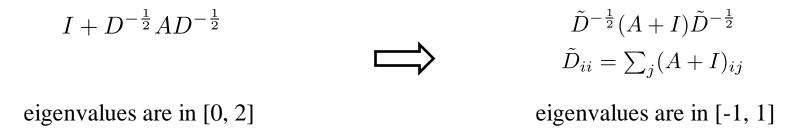
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Final Form of Graph Convolution:

 $h_{\theta} * X \approx \theta \tilde{D}^{-\frac{1}{2}} (A+I) \tilde{D}^{-\frac{1}{2}} X$

Graph convolution in GCNs for 1D graph signal:

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Graph convolution in GCNs for 1D graph signal:

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Generalize to multi-input and multi-output convolution:

 $h_W * X \approx \tilde{D}^{-\frac{1}{2}} (A+I) \tilde{D}^{-\frac{1}{2}} X W$ $= \tilde{L} X W$

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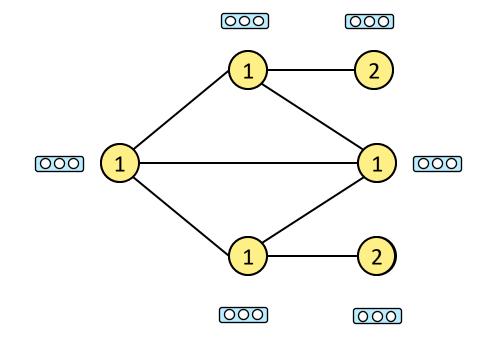
 $h_W * X \approx \tilde{D}^{-\frac{1}{2}} (A+I) \tilde{D}^{-\frac{1}{2}} X W$ $= \tilde{L} X W$

Add nonlinearity:

$$\sigma\left(h_W * X\right) \approx \sigma\left(\tilde{L}XW\right)$$

Our Spectral Filters are Localized:

$$\tilde{L} = \tilde{D}^{-\frac{1}{2}} (A+I) \tilde{D}^{-\frac{1}{2}}$$



1-step Graph Convolution: $h_W * X \approx \tilde{L}XW$ 2-step Graph Convolution: $h_{W_2} * h_{W_1} * X \approx \tilde{L}^2 X W_1 W_2$

Exponent of matrix power indicates how far the propagation is!

• We start with Chebyshev Polynomials which can represent any spectral filters (eigenvalues in [-1, 1])

$$h(x) = \sum_{n=0}^{\infty} a_n T_n(x)$$

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• Further simplification/approximation

$$h_{\theta} * X \approx \theta \tilde{D}^{-\frac{1}{2}} (A+I) \tilde{D}^{-\frac{1}{2}} X$$
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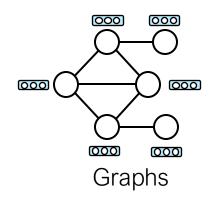
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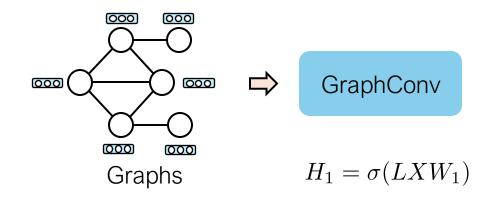
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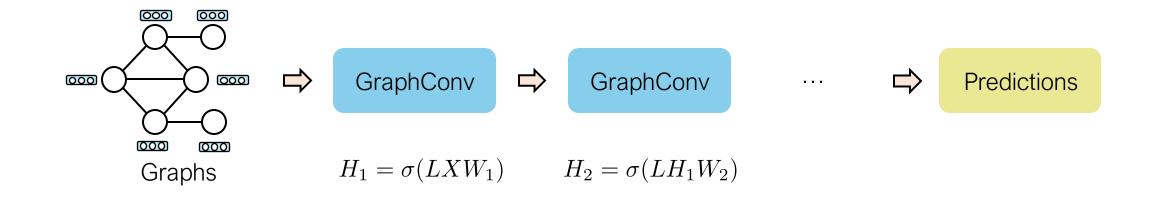
We can remedy the lost expressiveness by stacking multiple graph convolution layers!



Graph Convolutional Networks (GCNs)

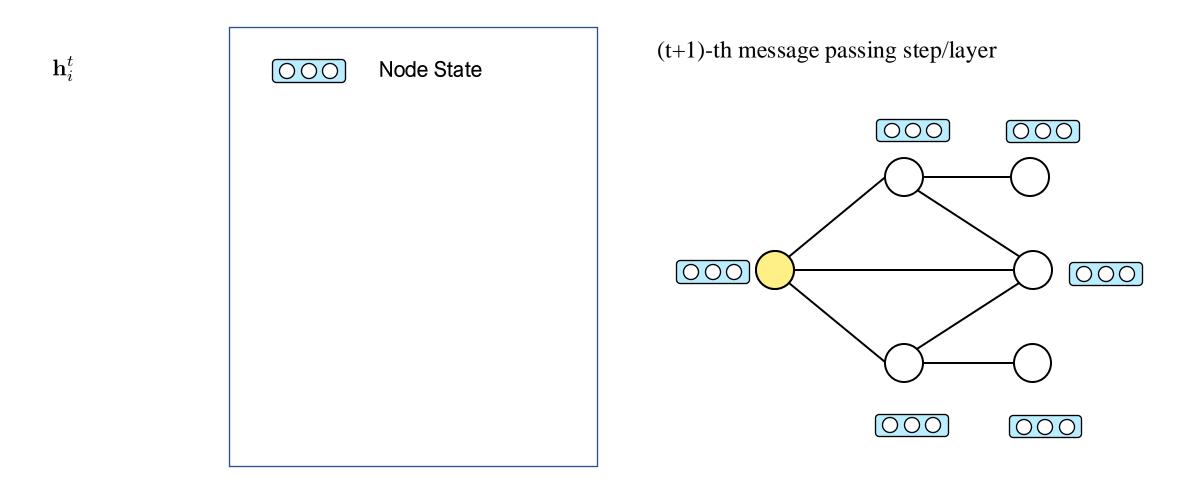


Graph Convolutional Networks (GCNs)

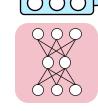


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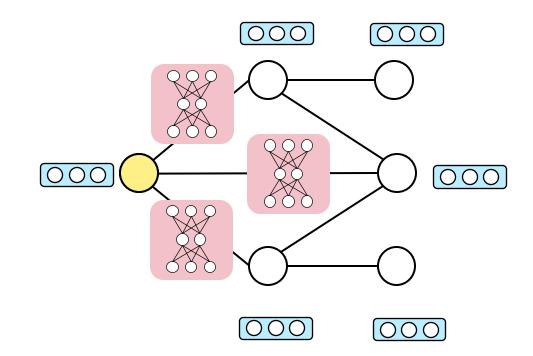


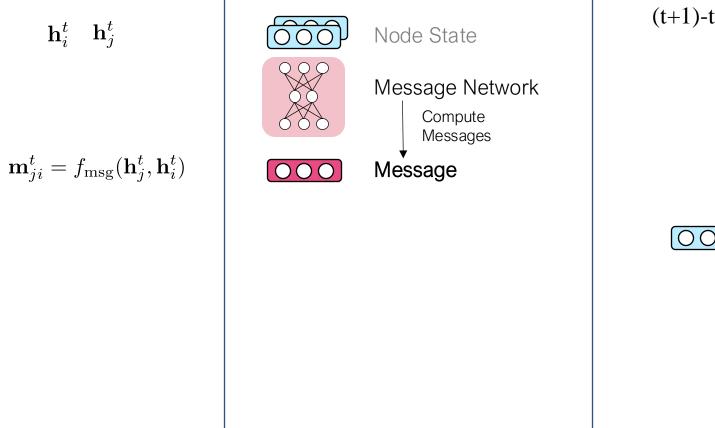
 \mathbf{h}_{i}^{t} \mathbf{h}_{j}^{t}

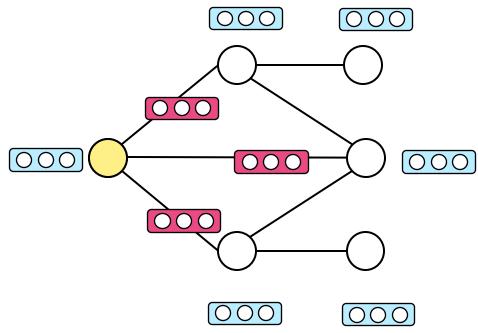


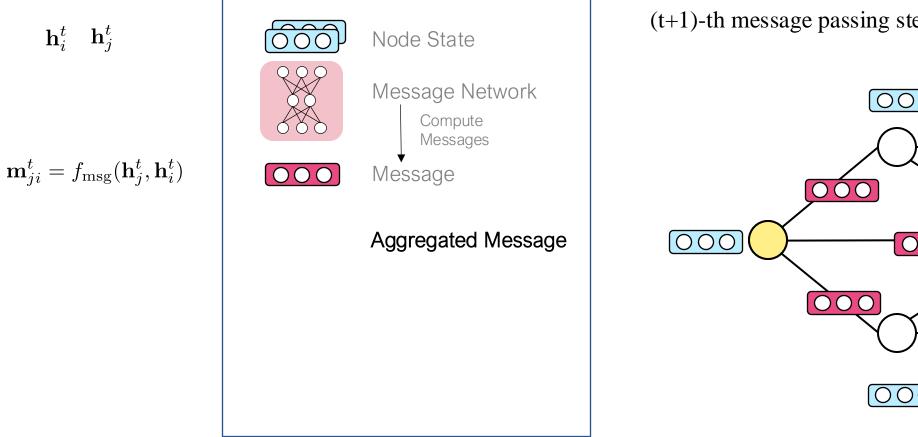
Node State

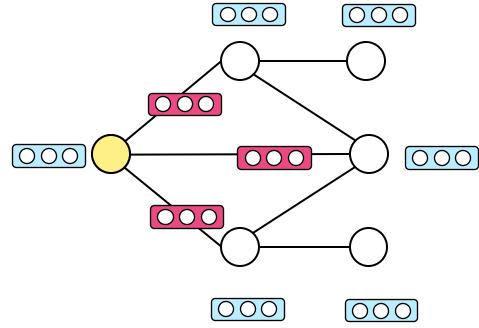
Message Network

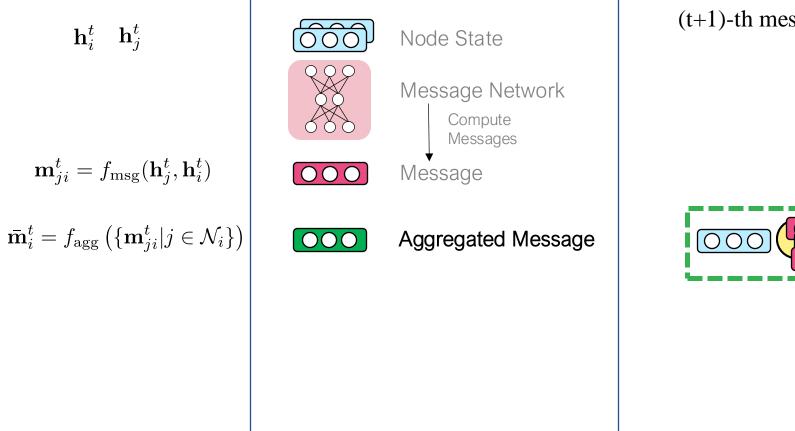


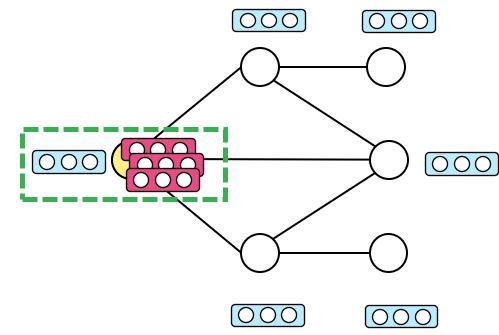


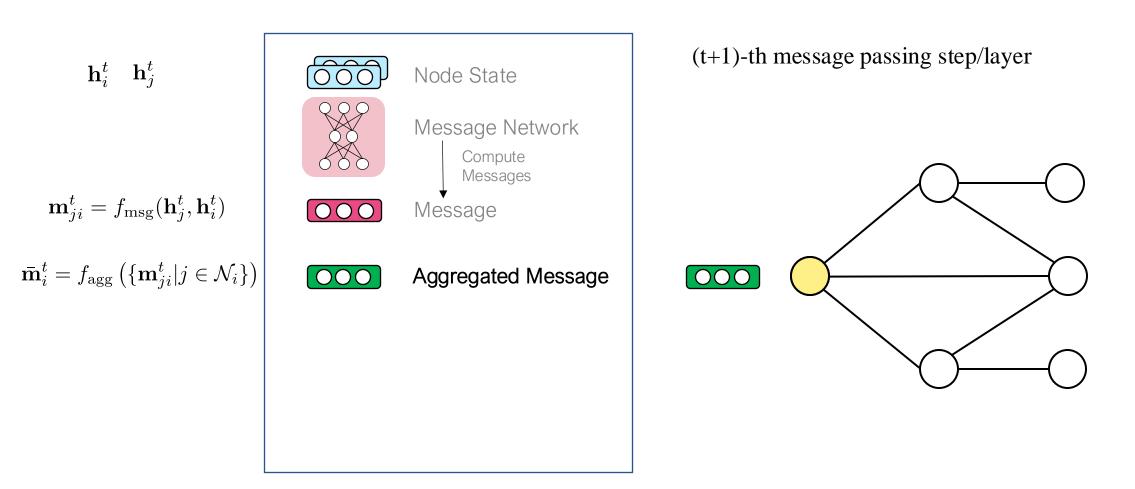




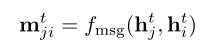




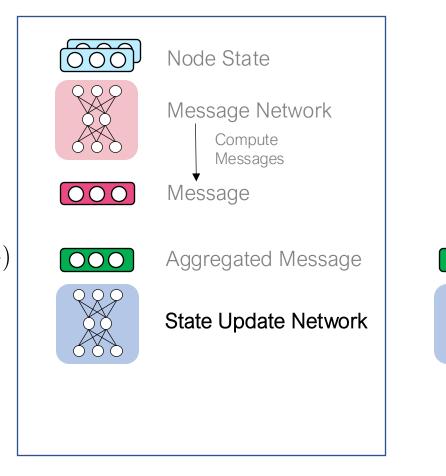


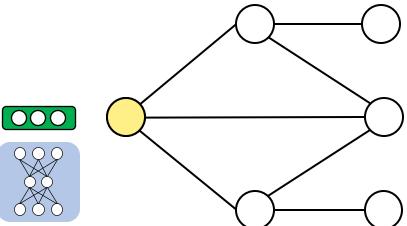


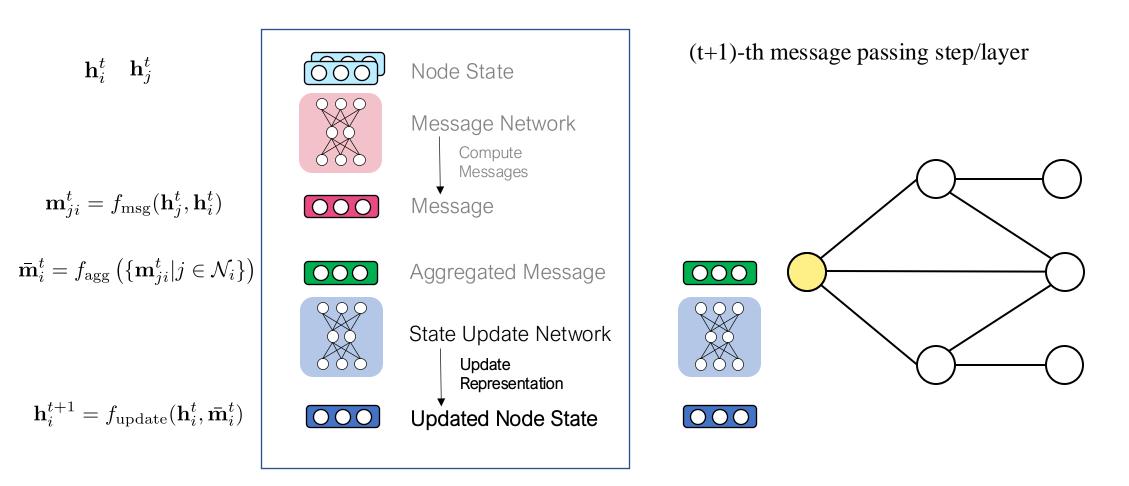


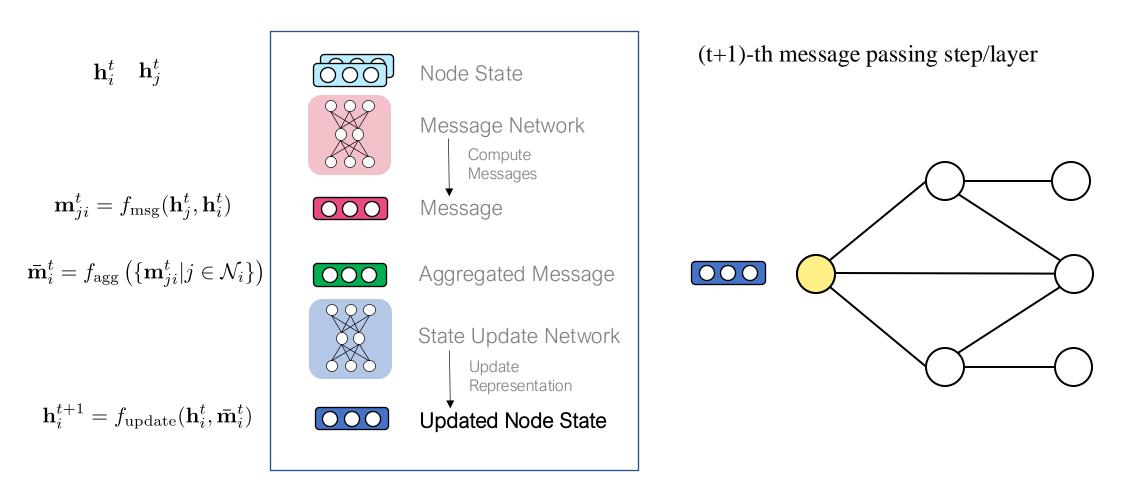


$$\bar{\mathbf{m}}_{i}^{t} = f_{\mathrm{agg}}\left(\{\mathbf{m}_{ji}^{t}|j\in\mathcal{N}_{i}\}\right)$$

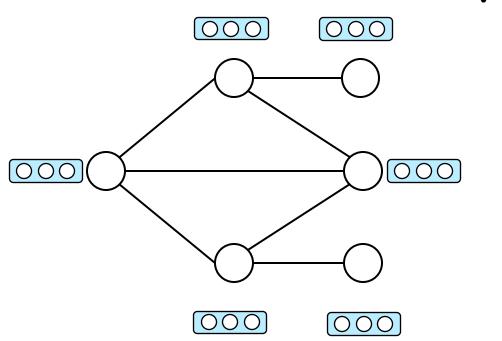








GCNs are Message Passing Networks



- Node State X

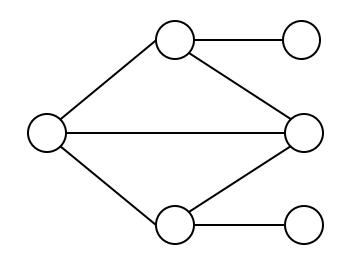
Graph Laplacian

$$\tilde{L} = \tilde{D}^{-\frac{1}{2}} (A+I) \tilde{D}^{-\frac{1}{2}}$$



GCNs are Message Passing Networks

• Node State X



Graph Laplacian

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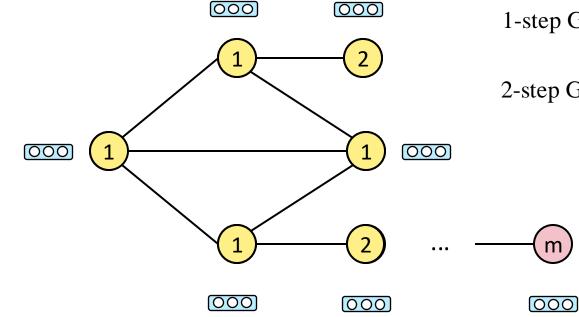
- Aggregated Message
- State Update Network W

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Our Spectral Filters are Localized:

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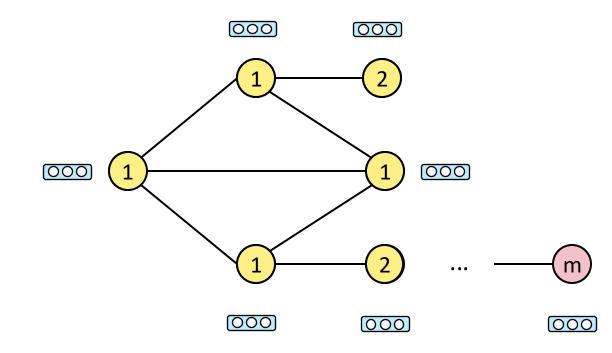
1-step Graph Convolution: $h_W * X \approx \tilde{L}XW$

2-step Graph Convolution: $h_{W_2} * h_{W_1} * X \approx \tilde{L}^2 X W_1 W_2$

What if the graph diameter m is large?

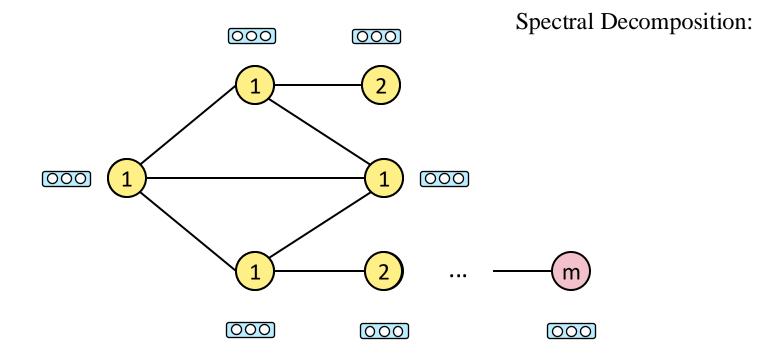
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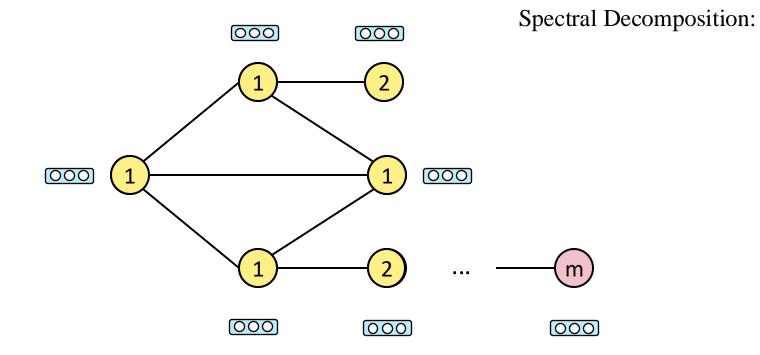


 $\tilde{L}^m = U\Lambda^m U^\top$

 $\tilde{L} = U\Lambda U^{\top}$

Our Spectral Filters are Localized:

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 $\tilde{L}^m = U\Lambda^m U^\top$

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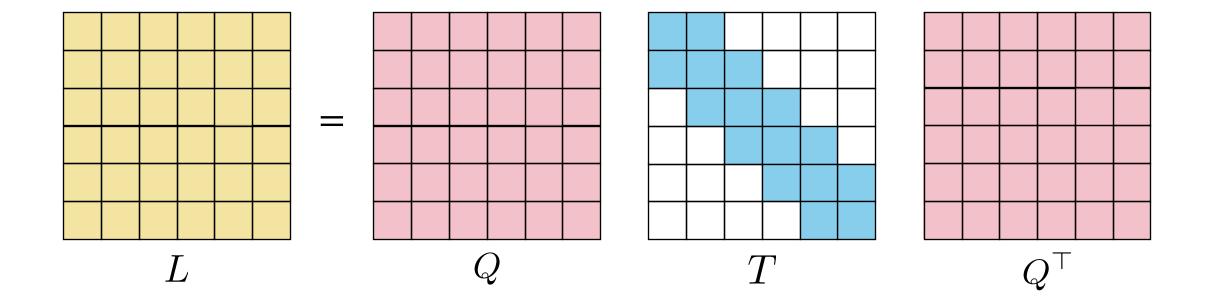
Cubic complexity O(N^3) !

Algorithm 1 : Lanczos Algorithm

1: Input: S, x, K, ϵ 2: Initialization: $\beta_0 = 0$, $q_0 = 0$, and $q_1 =$ x/||x||3: For j = 1, 2, ..., K: 4: $z = Sq_i$ 5: $\gamma_j = q_j^{\dagger} z$ 6: $z = z - \gamma_j q_j - \beta_{j-1} q_{j-1}$ 7: $\beta_j = \|z\|_2$ 8: If $\beta_i < \epsilon$, quit $q_{i+1} = z/\beta_j$ 9: 10: 11: $Q = [q_1, q_2, \cdots, q_K]$ 12: Construct T following Eq. (2)13: Eigen decomposition $T = BRB^{\top}$ 14: Return V = QB and R.

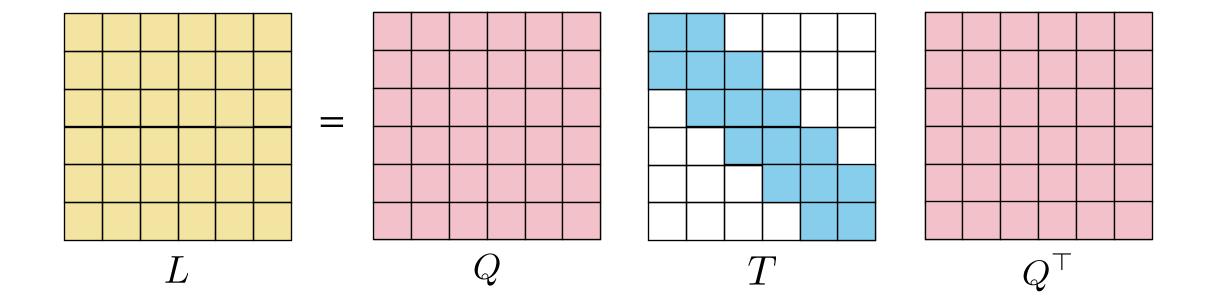
Tridiagonal Decomposition

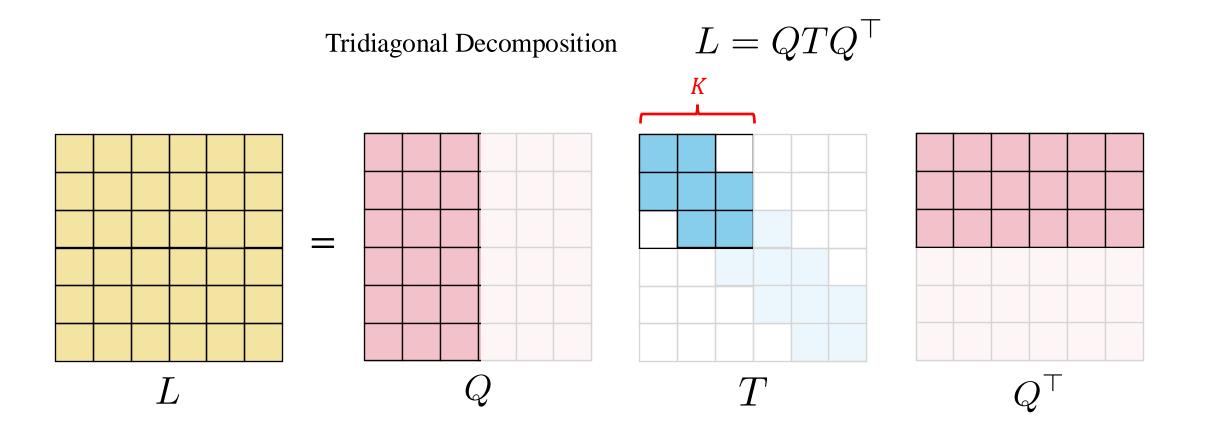
$$L = QTQ^{\top}$$



Tridiagonal Decomposition

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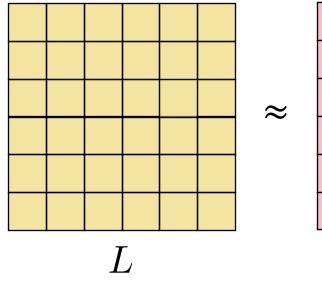


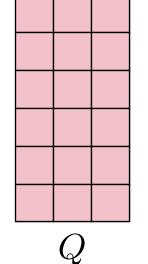


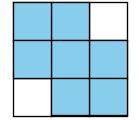
Tridiagonal Decomposition

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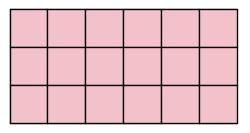
Low-rank approximation







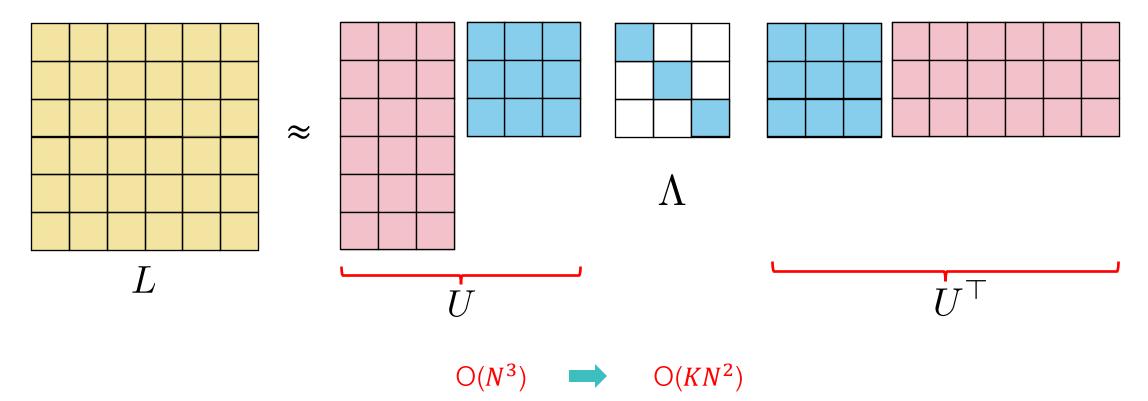
T



Tridiagonal Decomposition

$$L = QTQ^{\top}$$

Low-rank approximation with top K eigenpairs



Multi-scale Graph Convolutional Networks

• m-step GraphConv (Prior Work) $H = L^m X W$

LanczosNet [9]:

• m-step GraphConv $H = U\Lambda^m U^\top X W$

• Learn Nonlinear Spectral Filter $H = U f_{\theta} (\Lambda^m) U^{\top} X W$

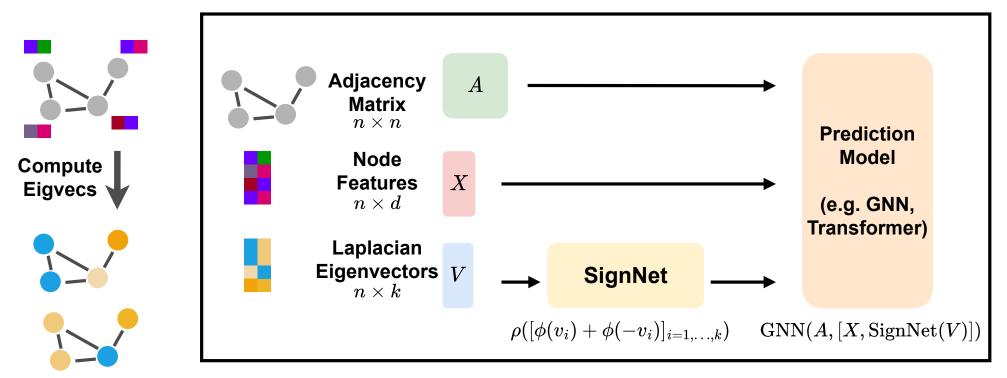
• Learning Graph Kernel / Metric $L_{ij} \propto \exp\left(-\|(X_i - X_j)M\|^2\right)$

SignNet

Eigenvectors of graph Laplacian are shown to be powerful node features, e.g., [10].

However, the sign-change of eigenvectors leaves the eigenspace unchanged. In other words, we need a network that is invariant to the sign-change. SingNet [11] does the job!

Model



Input Graph

Image Credit: [11]

SignNet

The variant of SingNet [11], called BasisNet [11], is also invariant to the change of basis of the eigenspaces:

$$f(V_1, \dots, V_l) = f(V_1Q_1, \dots, V_lQ_l),$$
$$Q_i \in O(d_i)$$

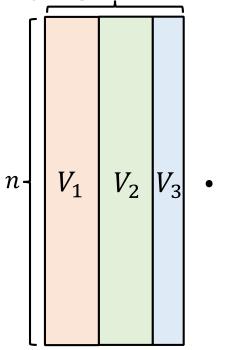
In particular, the model has the form:

$$f(V_1, \dots, V_l) = \rho\left([\phi_{d_i}(V_i V_i^{\top})]_{i=1}^l \right)$$

k eigenvectors

by eigenvalue

partitioned $k \times k$ block diagonal orthogonal matrix



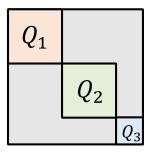
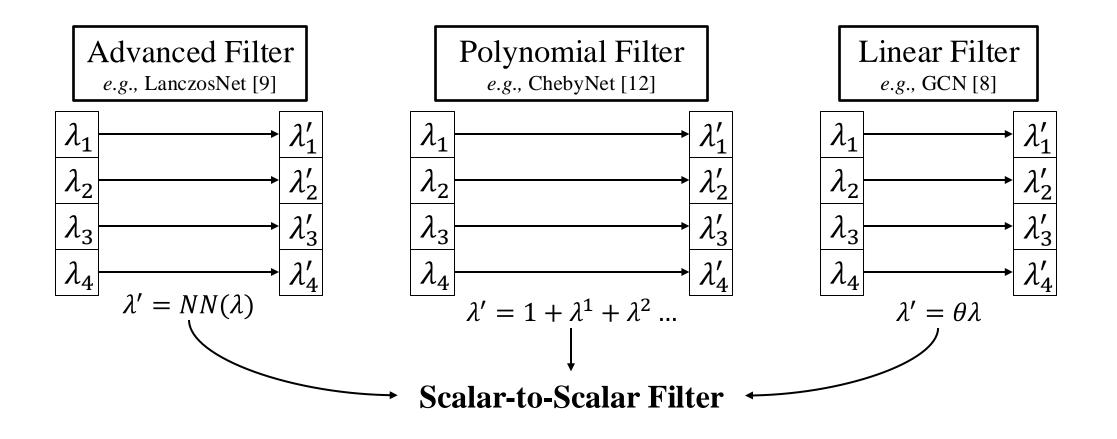


Image Credit: [11]



Previous work employ scalar-to-scalar spectral filters



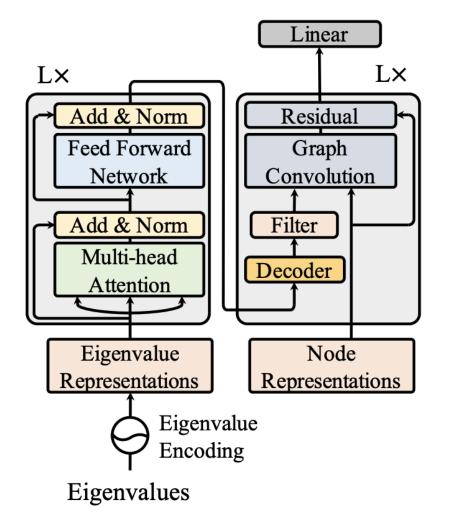


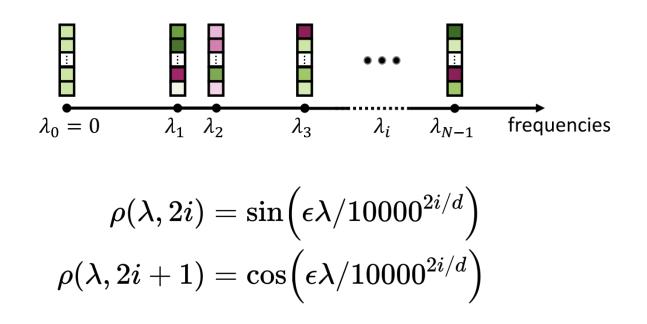
Previous work employ scalar-to-scalar spectral filters, which may fail to capture global graph properties.

Spectrum Information	Example	Definition	Scalar Input	Set Input
Algebraic Connectivity		$Count(\lambda = 0)$	×	
Diameter		$\left[\frac{4}{n\lambda_2},\frac{1}{2m\lambda_1}\right]$	×	
Clusterability		$\begin{array}{l} \lambda_2 - \lambda_1 \\ (\lambda_1 \neq \lambda_2 \neq 0) \end{array}$		

Specformer

Instead of employing scalar-to-scalar spectral filters, Specformer [13] uses set-to-set spectral filters:





Due to the eigenvalue encoding, the spectral filter is permutation invariant!

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Questions?